

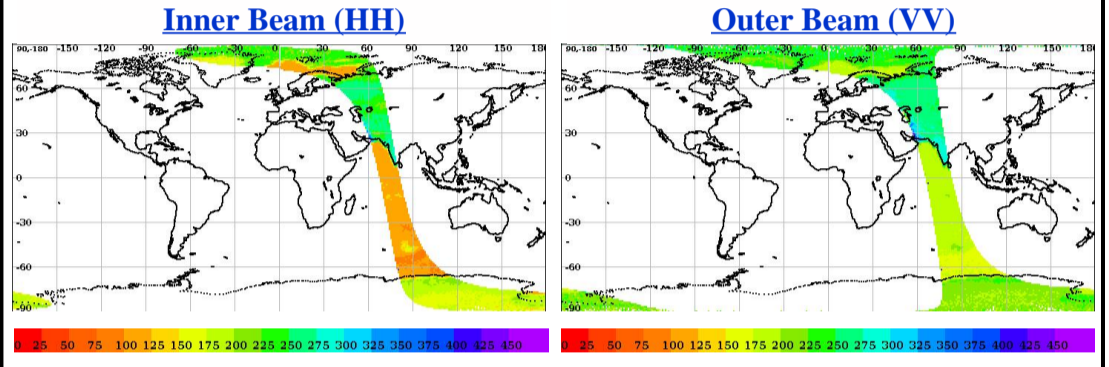
# SCATSAT-1 Scatterometer Level-1B Data Quality Evaluation Report

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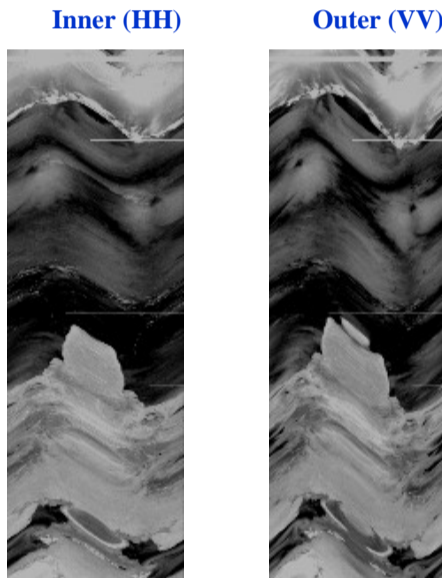
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<b>Satellite Id</b>	ScatSat-1	<b>Start Orbit</b>	12983	<b>Total Scans</b>	1004
<b>Sensor Name</b>	Scatterometer	<b>End Orbit</b>	12984	<b>No of Inner FootPrints</b>	281
<b>Processor Version</b>	v1.1.3	<b>Rev. Number</b>	12983_12984	<b>No Of Outer FootPrints</b>	282
<b>Half Orbit Direction</b>	SN	<b>Data Production Date</b>	10-03-2019	<b>No. Of Inner Slices</b>	9
<b>Equator Crossing Date</b>	10-03-2019	<b>Equator Crossing Time</b>	15:40:48.000	<b>No Of Outer Slices</b>	15

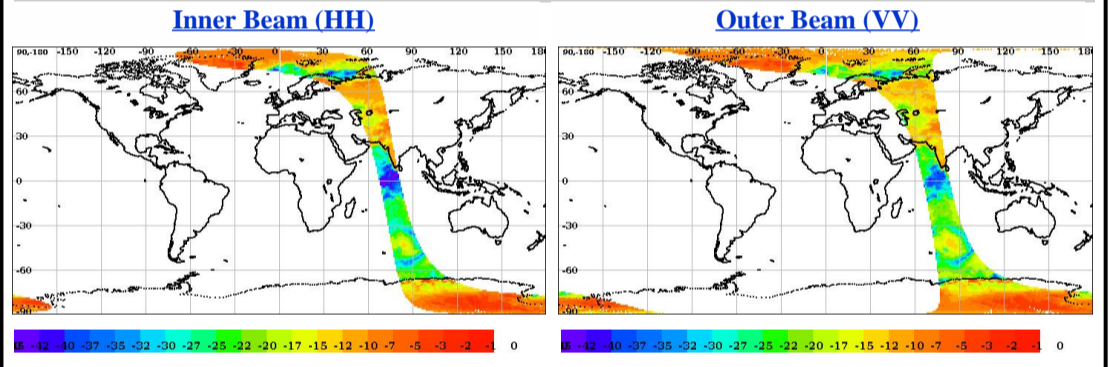
## Brightness Temperature(k) Footprint trace



## Image Snapshot for Inner & Outer Beam



## Sigma0(dB) Footprint trace



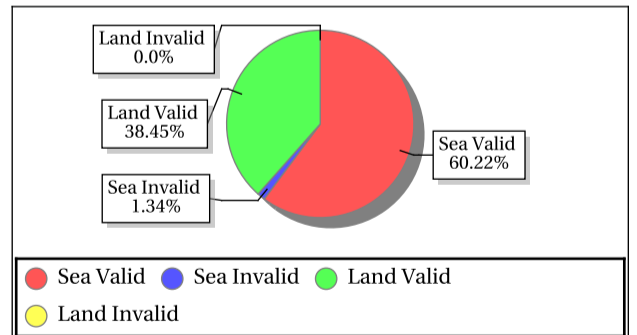
## Invalid and Poor Sigma-0 Quality Flag Statistics for Inner/Outer Slices\*

Sigma-0 Flags	Inner Beam	Outer Beam
<b>Invalid Sigma0(%)</b>	1.50	2.23
<b>Data Not Available From Payload (%)</b>	88.85215	59.79224
<b>Slice not within sample array limits (%)</b>	11.15	40.21
<b>C(S+N) - C(N) &lt; 0.1 (%)</b>	0.00	0.00
<b>Poor Sigma0(%)</b>	21.96	13.19
<b>Noise samples for blending Saturated</b>	0.013089	0.079245
<b>Count samp. for interpol. saturated (%)</b>	0.00	0.00
<b>Sigma0 &lt; lower bound (-96dB) (%)</b>	0.0	0.0
<b>Sigma0 &gt; upper bound (0 dB) (%)</b>	0.00	0.00
<b>SNR &lt; -65 dB (%)</b>	0.039268	0.09388

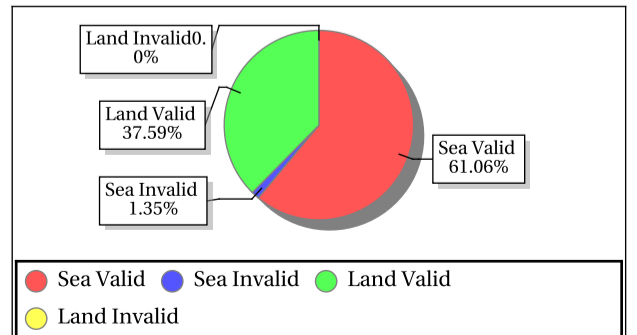
\*DP Format Document

## Sigma-0 Quality Flag Statistics for Inner/Outer Footprints

### Inner Beam (HH)



### Outer Beam (VV)



## Invariant Site Sigma-0 Statistics for Ascending/Descending, Fore/Aft in HH/VV beams

Site Name	Center Lat	Center Lon	Beam	Node	ScanDir	Sigma0 Min	Sigma0 Max	Sigma0 Mean	Sigma0 Std	BT Min	BT Max	BT Mean	BT Std
ROK	23.00	73.60	Inner	ASC	Aft	-12.46	-9.06	-10.76	0.70	236.16	303.55	275.67	14.95
ROK	23.00	73.60	Inner	ASC	Fore	-12.05	-8.18	-10.51	0.76	240.32	328.15	272.76	16.55
ANT_1	-75.00	121.00	Inner	ASC	Aft	-8.88	-6.11	-7.75	0.76	148.26	188.16	175.40	12.18
ANT_1	-75.00	121.00	Inner	ASC	Fore	-8.79	-6.34	-7.42	0.78	147.39	209.97	178.39	18.19
GreenLand_2	77.50	-41.50	Inner	ASC	Fore	-6.56	-5.28	-5.86	0.50	159.86	193.83	175.55	11.81
ROK	23.00	73.60	Outer	ASC	Aft	-13.06	-10.39	-11.86	0.68	242.55	311.99	283.17	17.51
ROK	23.00	73.60	Outer	ASC	Fore	-12.91	-10.21	-11.62	0.63	244.53	304.15	277.82	14.64
ANT_1	-75.00	121.00	Outer	ASC	Aft	-9.56	-7.58	-8.73	0.66	180.05	253.26	213.21	22.69
ANT_1	-75.00	121.00	Outer	ASC	Fore	-8.84	-7.07	-8.17	0.65	167.11	226.20	201.92	19.74
GreenLand_2	77.50	-41.50	Outer	ASC	Fore	-5.33	-4.18	-4.75	0.41	206.41	238.84	220.88	12.39
GreenLand_1	74.69	-42.50	Outer	ASC	Fore	-8.82	-8.65	-8.76	0.08	236.95	249.12	242.69	4.99



## Overall statistics for the Static Parameters (Footprint-wise)

Inner Beam (HH)																
	Sea Aft				Sea Fore				Land Aft				Land fore			
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)
<b>Kp</b>	0.12	286.00	0.53	6.143	0.12	304.53	0.39	4.022	0.12	1.00	0.12	0.000	0.12	42.35	0.12	0.002
<b>Kpa</b>	0.01	0.03	0.01	0.000	0.01	0.03	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000
<b>Kpb</b>	0.02	0.04	0.02	0.000	0.02	0.04	0.02	0.000	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000
<b>Kpc</b>	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
<b>SNR</b>	-34.70	27.82	3.63	0.173	-34.97	28.13	5.64	1.046	-9.70	31.96	18.41	16.682	-26.40	29.87	18.78	14.828

Outer Beam (VV)																
	Sea Aft				Sea Fore				Land Aft				Land fore			
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)
<b>Kp</b>	0.09	216.72	0.41	4.413	0.09	233.25	0.34	3.323	0.09	0.63	0.09	0.000	0.09	0.34	0.09	0.000
<b>Kpa</b>	0.01	0.01	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.01	0.01	0.000
<b>Kpb</b>	0.01	0.01	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000
<b>Kpc</b>	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
<b>SNR</b>	-34.66	21.04	1.85	0.000	-34.98	21.29	2.76	0.000	-8.62	23.57	12.72	0.244	-5.69	23.10	12.75	0.213

Parameter Specifications					
Parameter	Kp	Kpa	Kpb	Kpc	SNR
Min	0.00	0.00	0.00	0.00	-65.00
Max	1.00	1.00	1.00	1.00	22.00

- Normal
- Deviations
- Alarming
- High Errors

## Overall statistics for static parameter (Footprint-wise)

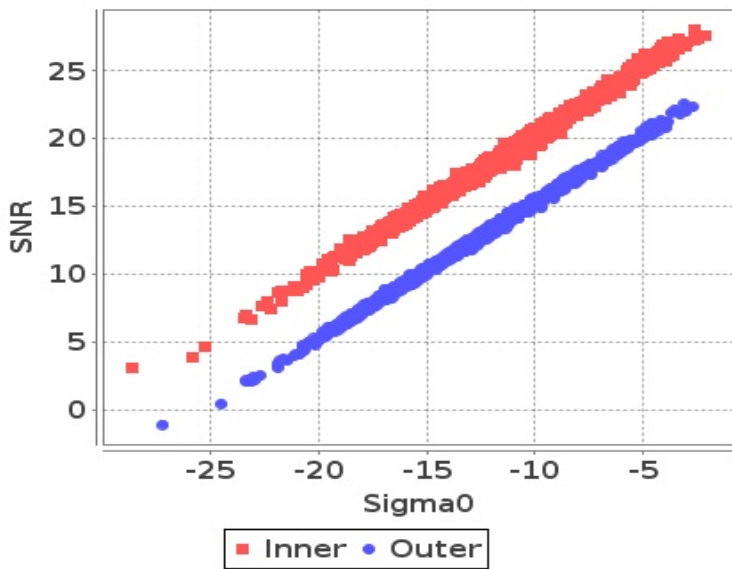
	Inner Beam (HH)				Outer Beam (VV)				Parameter Specifications		
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Parameter	Min	Max
<b>Incidence Angle (deg)</b>	48.46	49.38	49.02	0.000	57.11	58.35	57.84	0.000	Inci.(Inner)	47.10	49.90
<b>Azimuth Diff. (deg)</b>	0.0000	240.86	1.28	2.801	0.0000	287.65	1.28	3.580	Inci.(Outer)	57.30	58.90
<b>Range(Km)</b>	1013.82	1077.47	1040.84	25.285	1183.94	1265.61	1220.61	39.765	Azimuth Diff.	0.60	2.00
<b>X Factor(dbm)</b>	-94.19	-89.73	-90.29	0.000	-95.65	-91.78	-92.12	0.000	Range(Inner)	1025.00	1095.70
<b>Across Distance (Km)</b>	15.47	16.06	15.75	0.000	11.69	55.92	20.98	6.000	Range(Outer)	1210.00	1280.00
<b>Along Distance (Km)</b>	18.92	9426.19	71.72	8.000	18.67	9205.55	85.20	10.000	X-Factor	-100.00	-80.00
									Ac.Distance(Inner)	15.00	20.00
									Ac.Distance(Outer)	15.00	22.00
									Al.Distance(Inner)	15.00	30.00
									Al.Distance(Outer)	10.00	30.00
									<span style="display: inline-block; width: 15px; height: 15px; background-color: green; border: 1px solid black; margin-right: 5px;"></span> Normal	<span style="display: inline-block; width: 15px; height: 15px; background-color: orange; border: 1px solid black; margin-right: 5px;"></span> Alarming	
									<span style="display: inline-block; width: 15px; height: 15px; background-color: yellow; border: 1px solid black; margin-right: 5px;"></span> Deviations	<span style="display: inline-block; width: 15px; height: 15px; background-color: red; border: 1px solid black; margin-right: 5px;"></span> High Errors	



## Sigma0 Behaviour (Sigma0 Vs SNR)

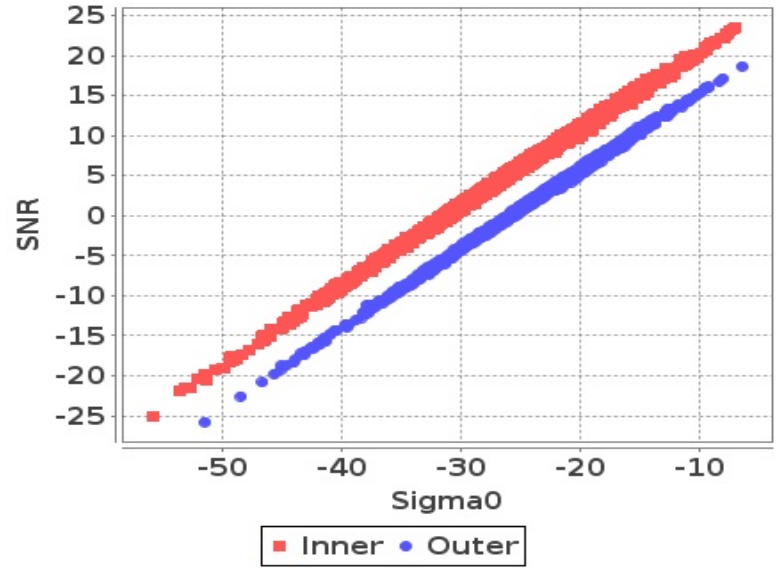
Footprint-Land

Sigma0 Vs SNR (Land)



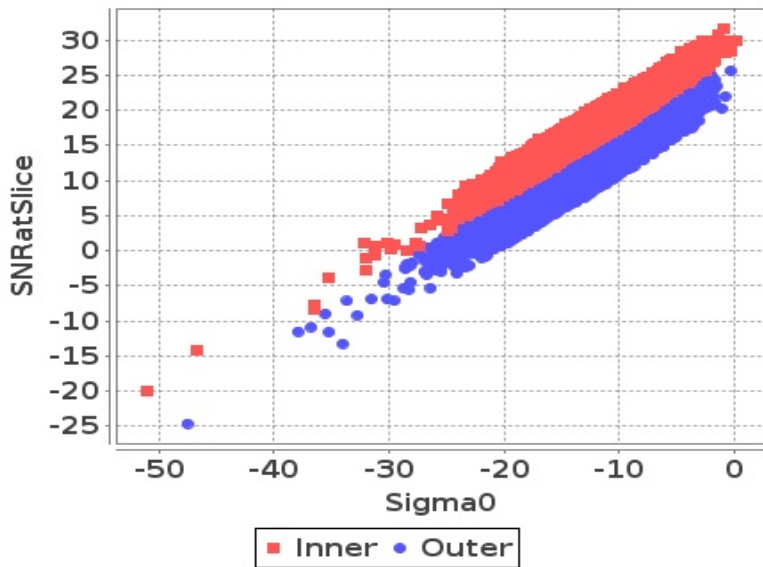
Footprint-Sea

Sigma0 Vs SNR (Sea)



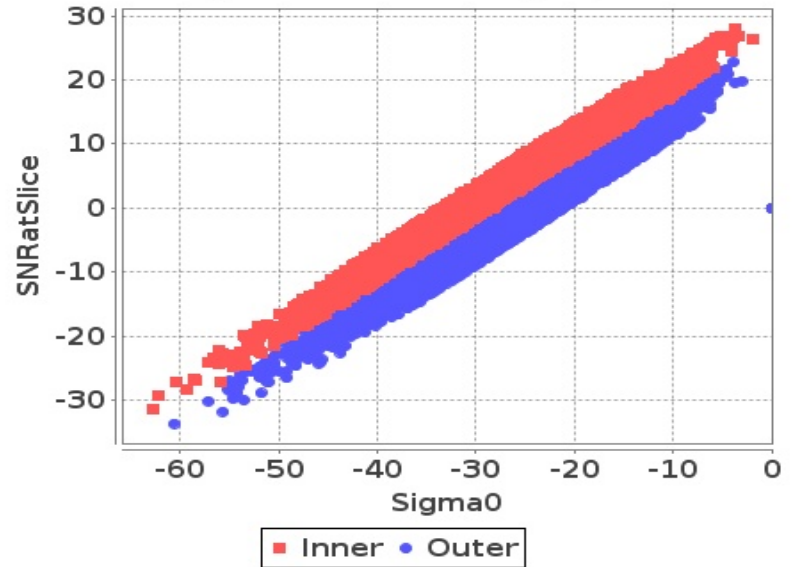
Slice-Land

Sigma0 Vs SNRatSlice (Land)



Slice-Sea

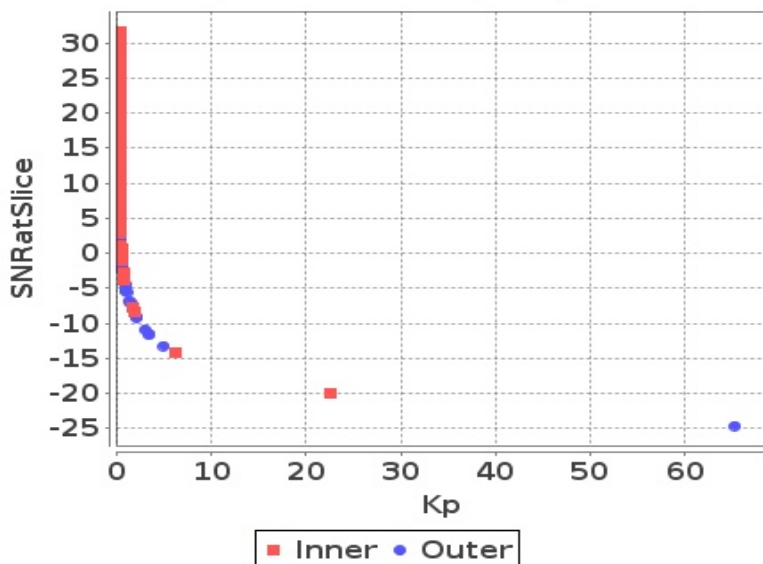
Sigma0 Vs SNRatSlice (Sea)



## Sigma0 Behaviour (Kp Vs SNR)

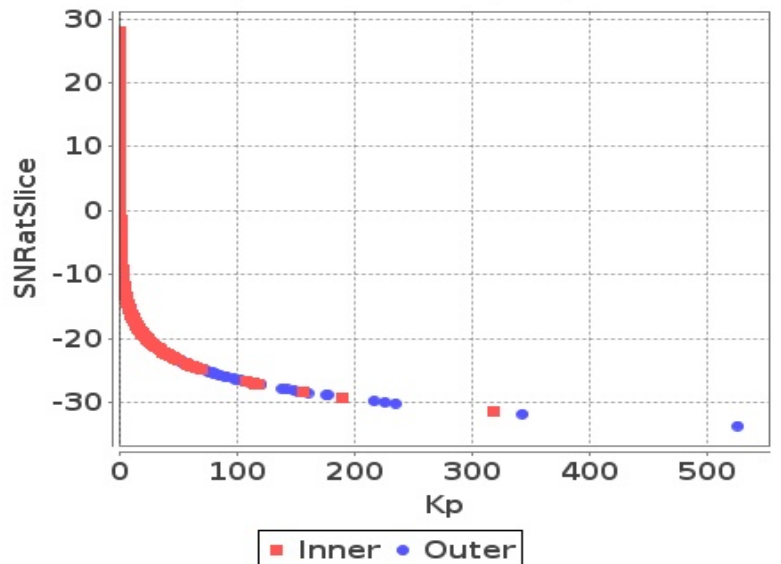
Slice

Kp Vs SNRatSlice (Land)



Slice

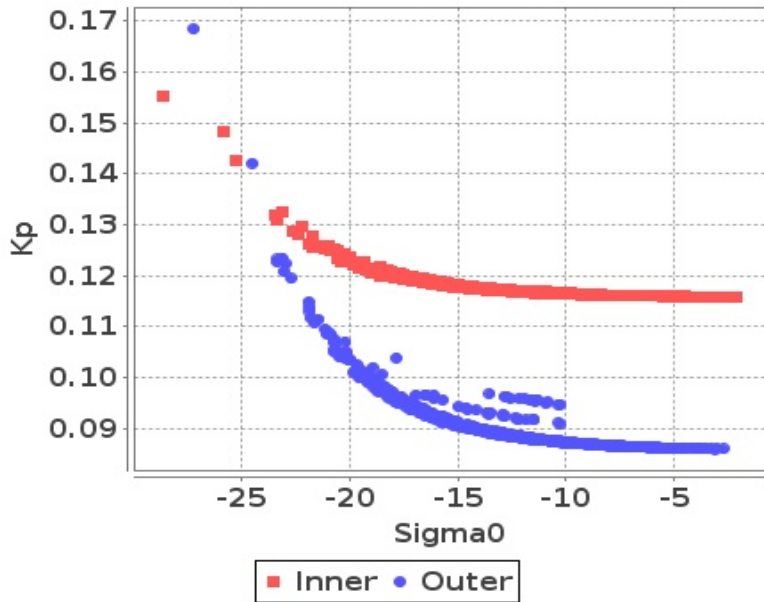
Kp Vs SNRatSlice (Sea)



# Sigma0 Behaviour(Sigma0 Vs Kp)

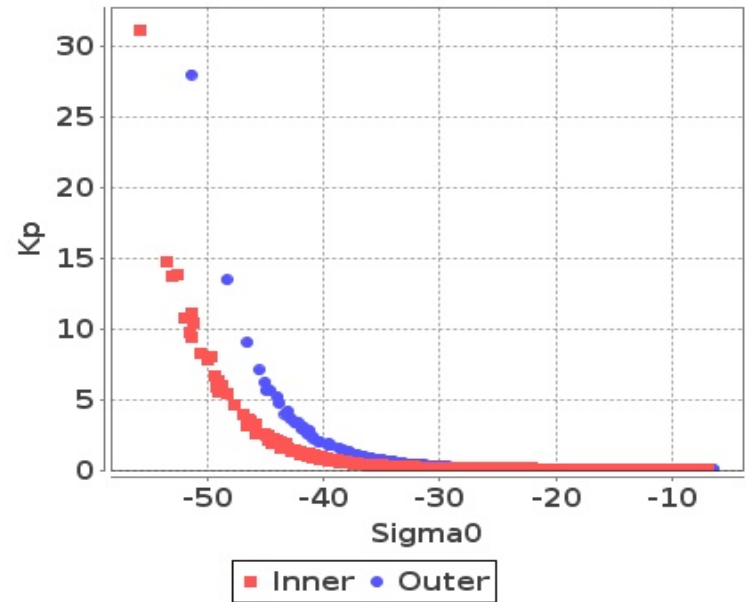
## Footprint-Land

### Sigma0 Vs Kp (Land)



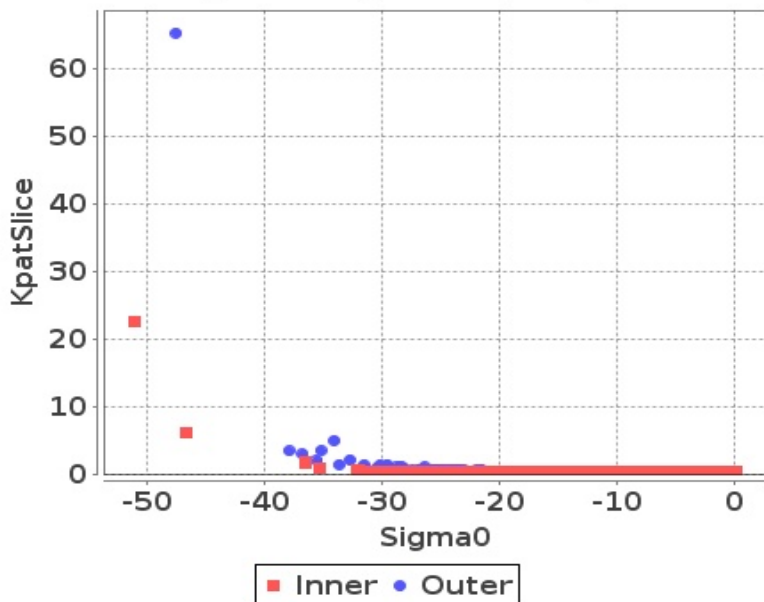
## Footprint-Sea

### Sigma0 Vs Kp (Sea)



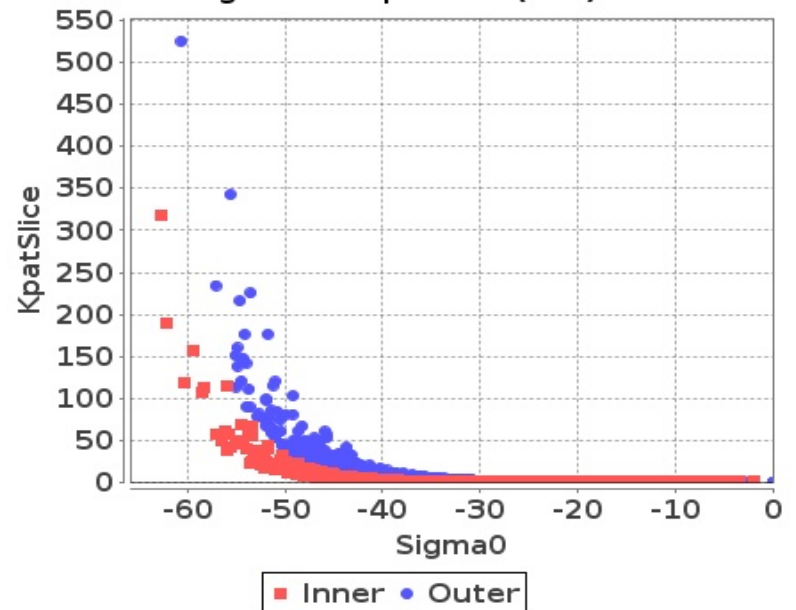
## Slice-Land

### Sigma0 Vs KpatSlice (Land)



## Slice-Sea

### Sigma0 Vs KpatSlice (Sea)

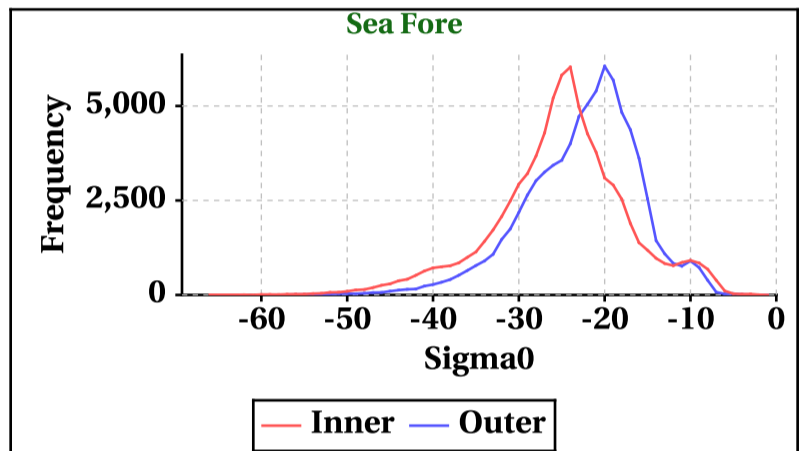
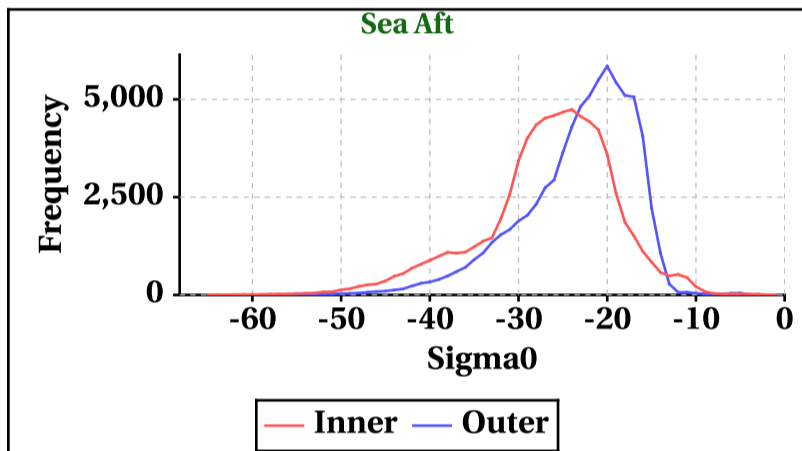
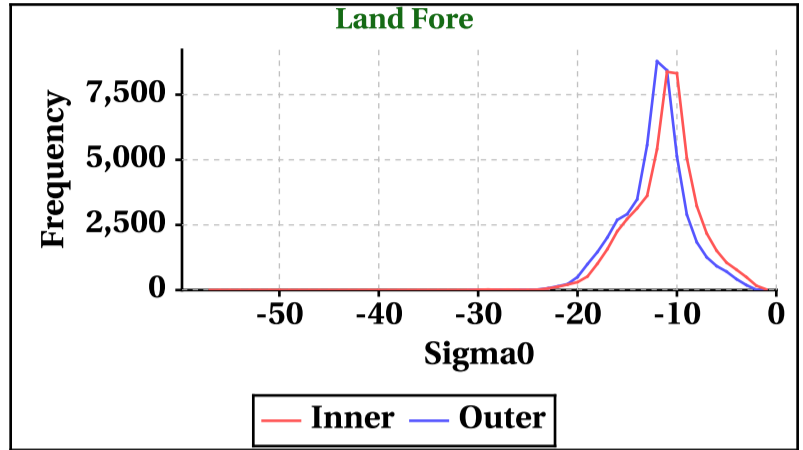
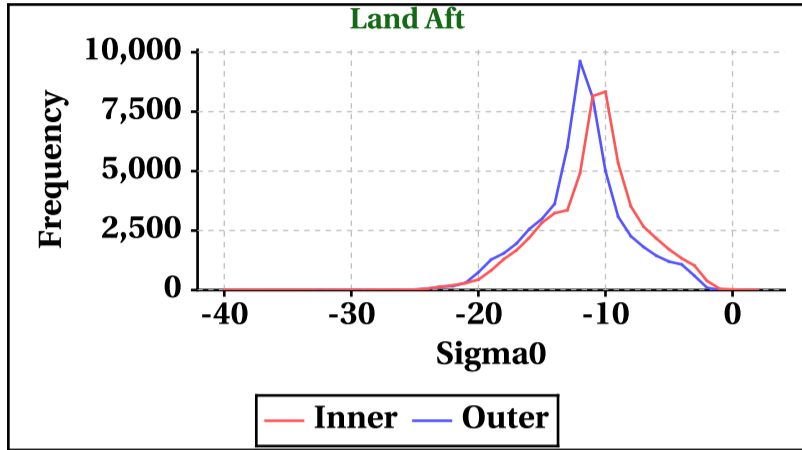


# Dynamic Range (Data Histograms)

## Sigma0(db)

Inner Beam (HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-40	-57	-65	-66
Max	2	0	0	0

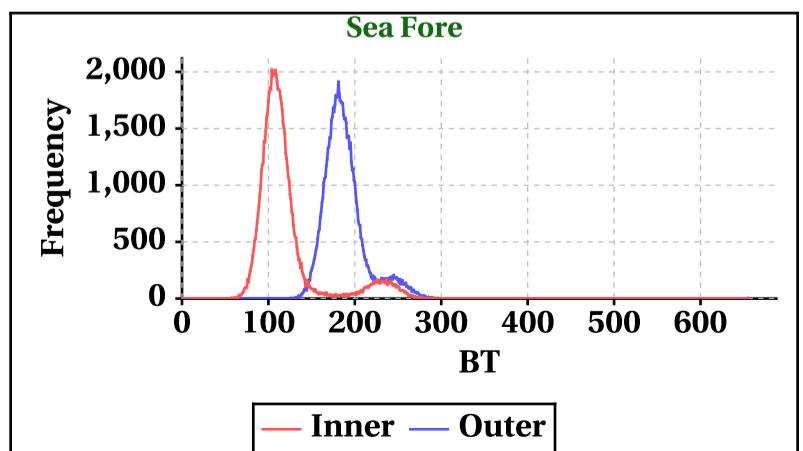
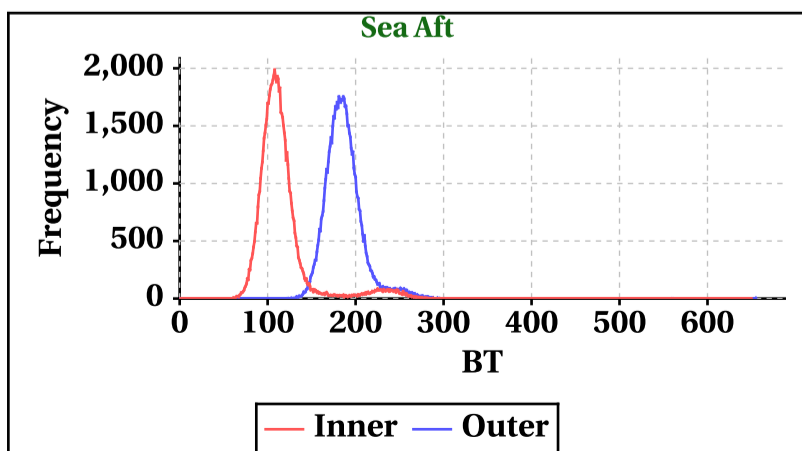
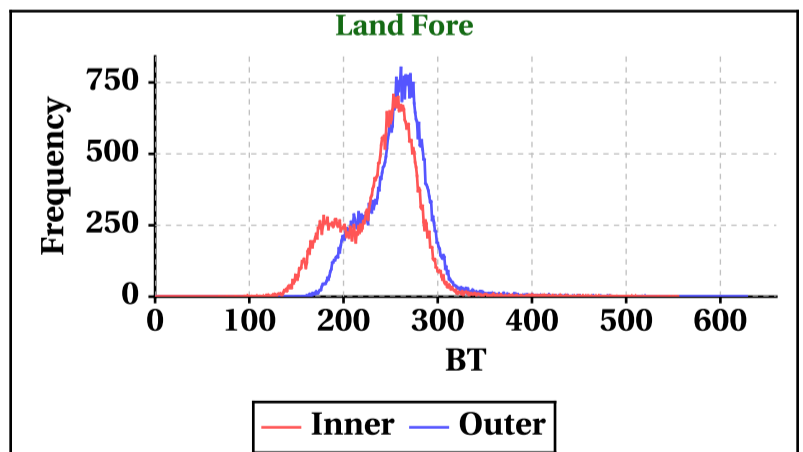
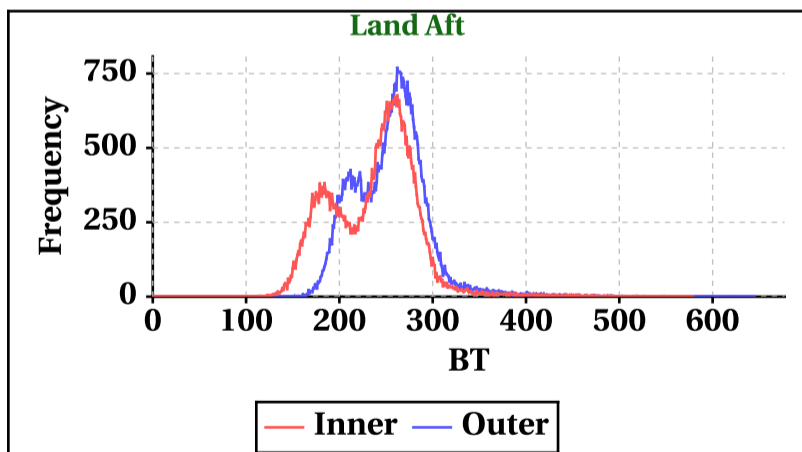
Outer Beam (VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-33	-31	-60	-60
Max	0	0	0	0



## Brightness Temperature(K)

Inner Beam(HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	0	0
Max	579	555	650	655

Outer Beam(VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	0	0
Max	645	628	655	655

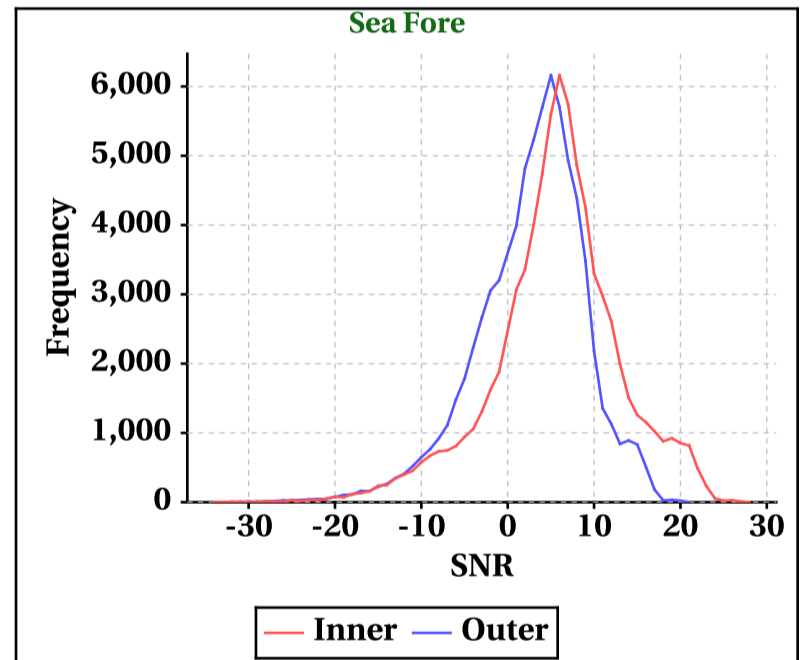
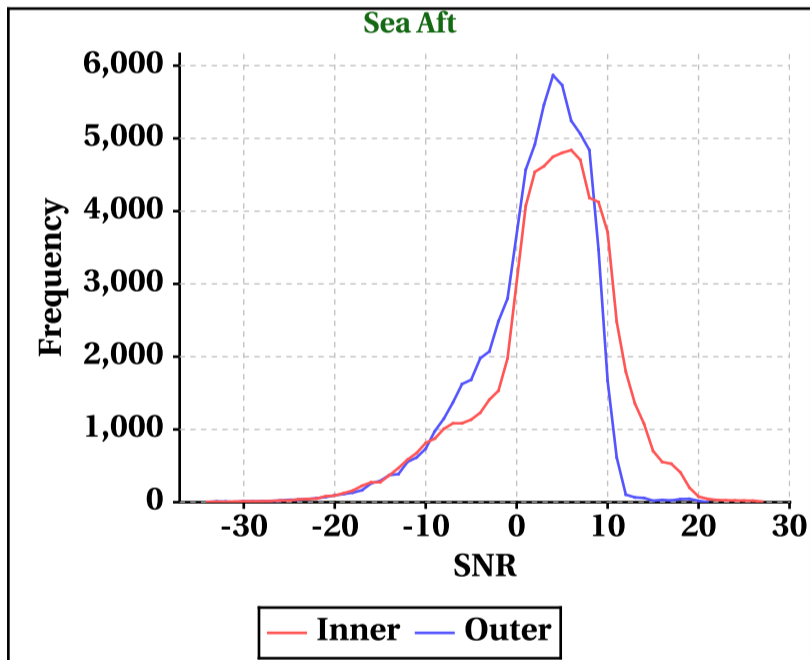
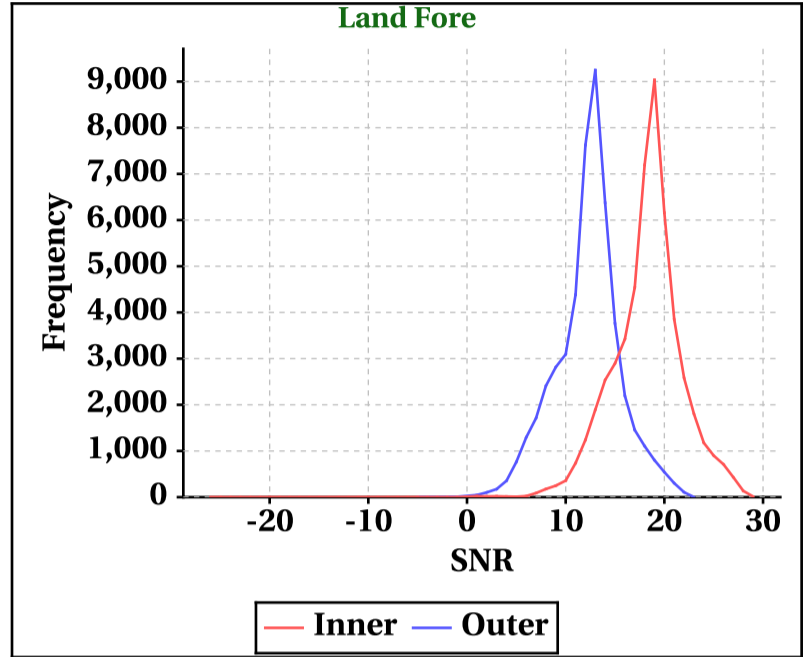
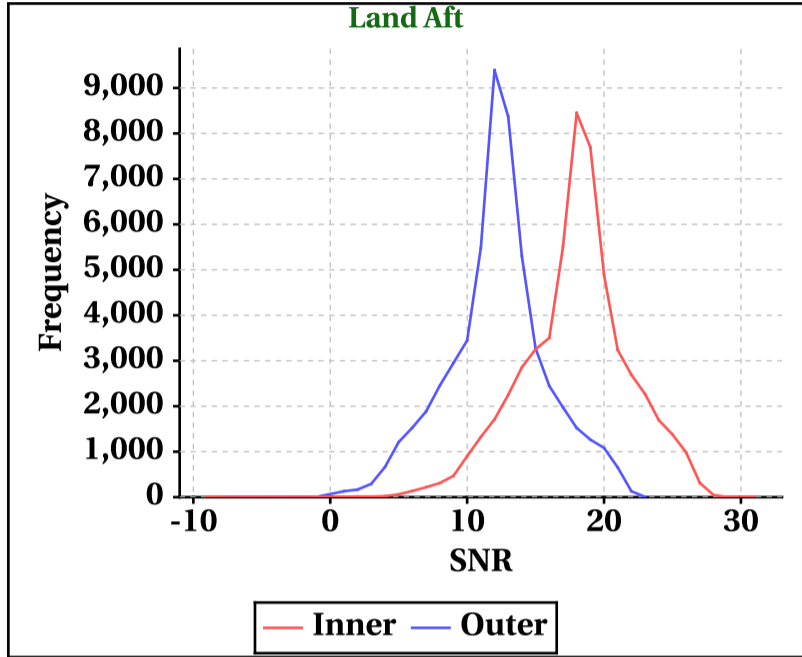


# Dynamic Range (Data Histograms)

## SNR(dBm)

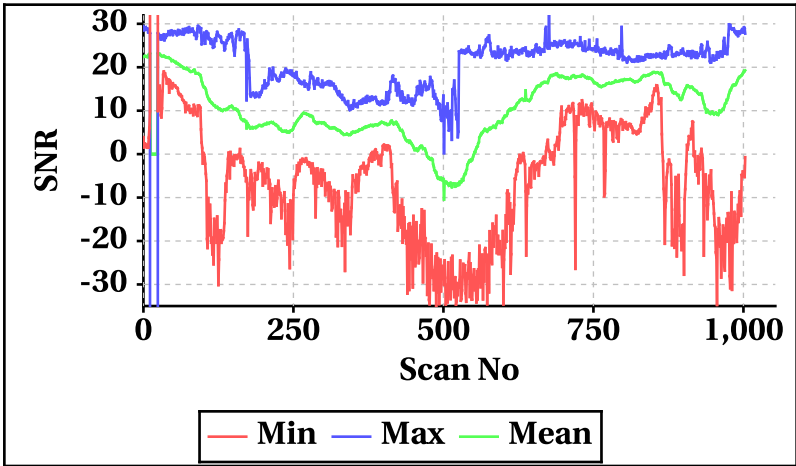
Inner Beam (HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-9	-26	-34	-34
Max	31	29	27	28

Outer Beam (VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-8	-5	-34	-34
Max	23	23	21	21

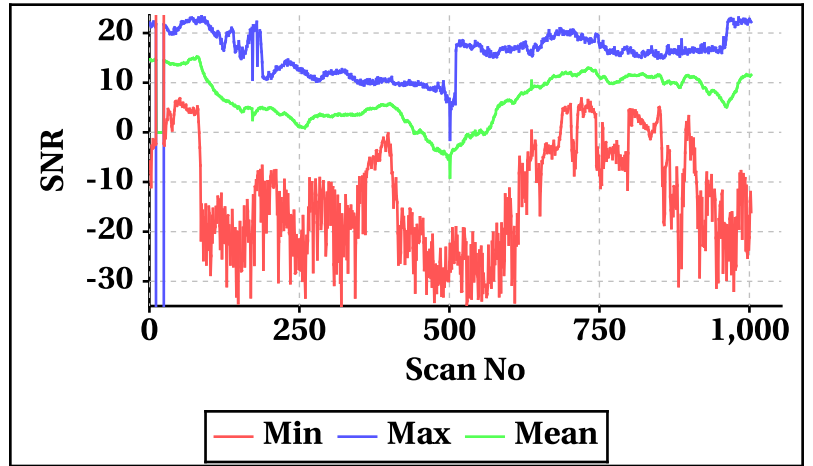


## Orbit-wise behaviour of SNR

**Inner Beam (HH)**

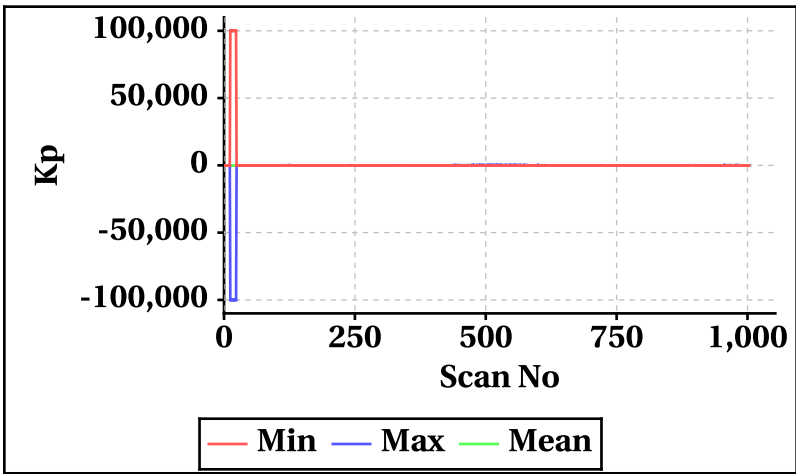


**Outer Beam(VV)**

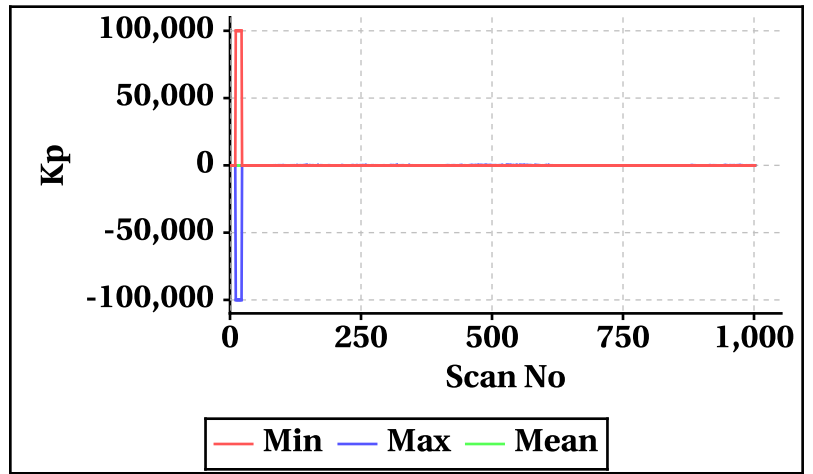


## Orbit-wise behaviour of Kp,Kpa,Kpb,Kpc

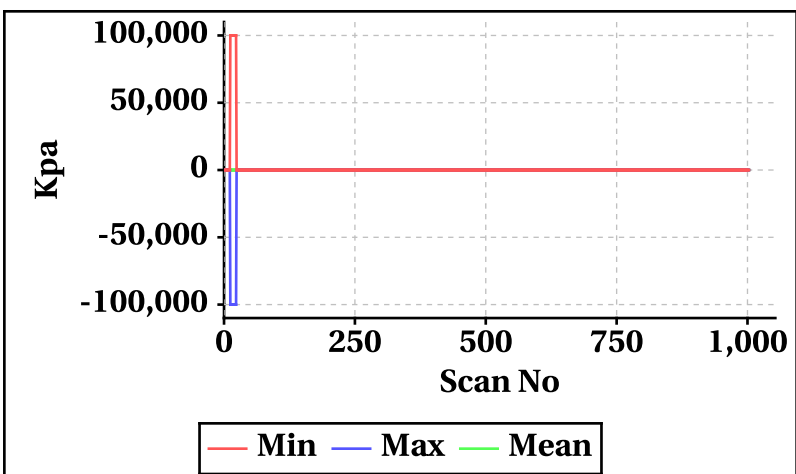
**Inner Beam(HH)**



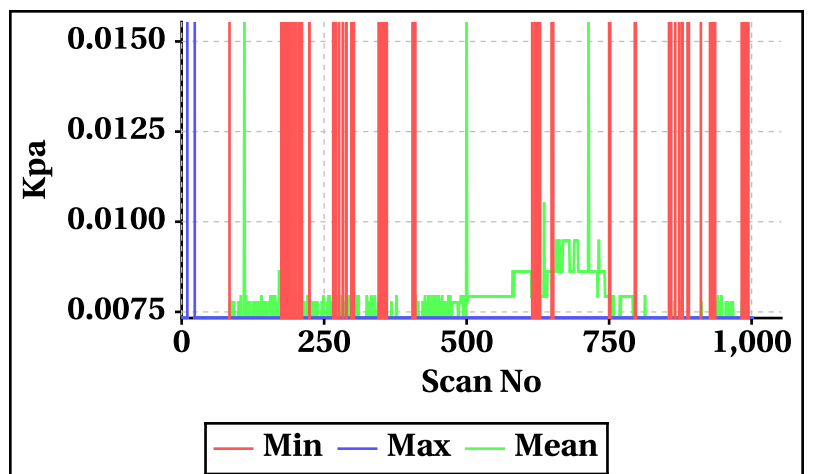
**Outer Beam(VV)**



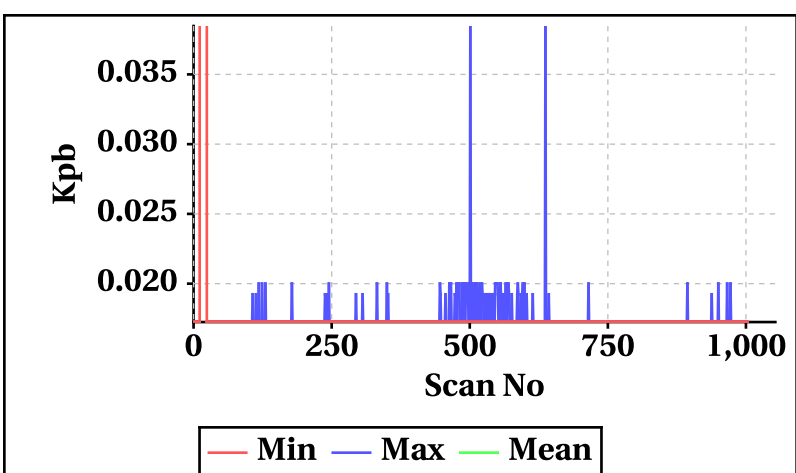
**Inner Beam(HH)**



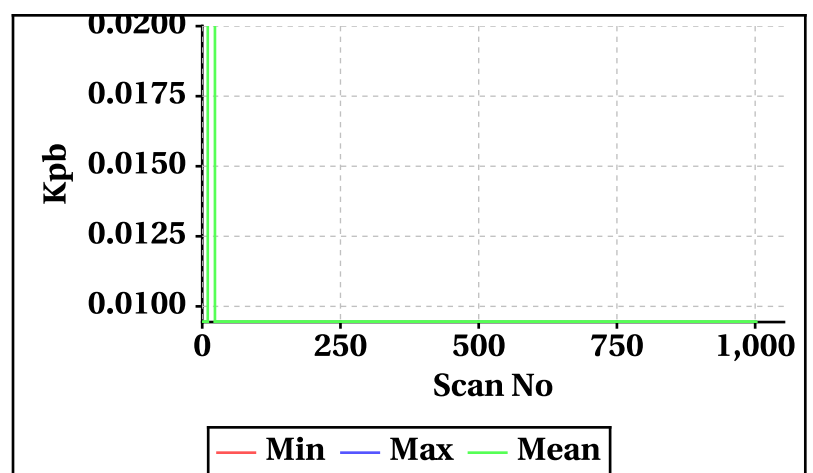
**Outer Beam(VV)**



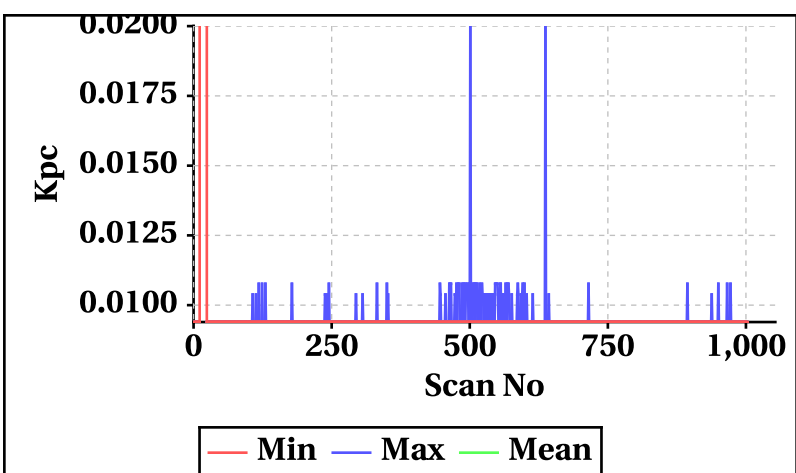
**Inner Beam(HH)**



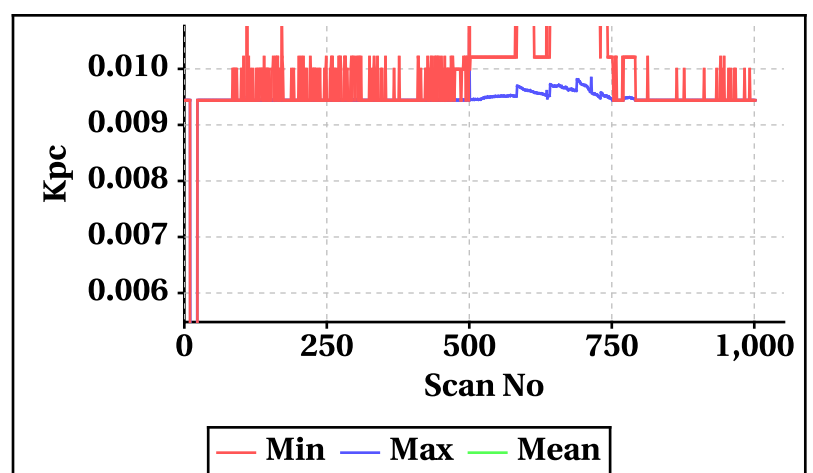
**Outer Beam(VV)**



**Inner Beam(HH)**



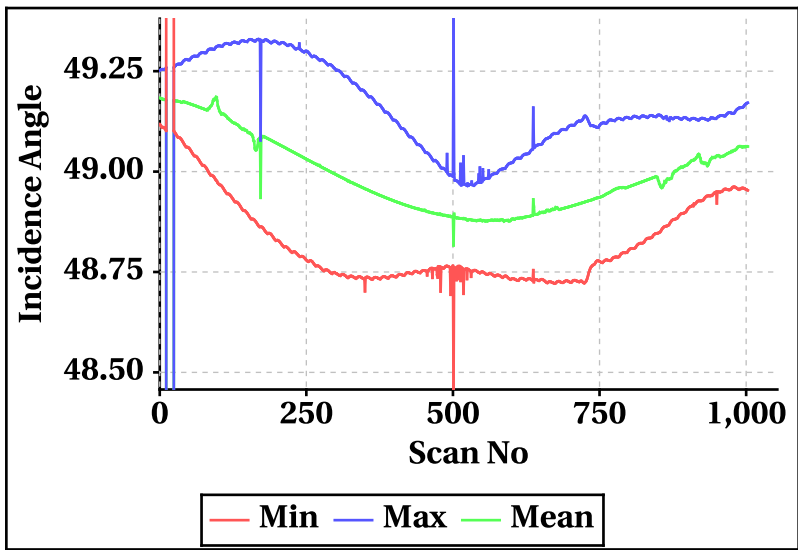
**Outer Beam(VV)**



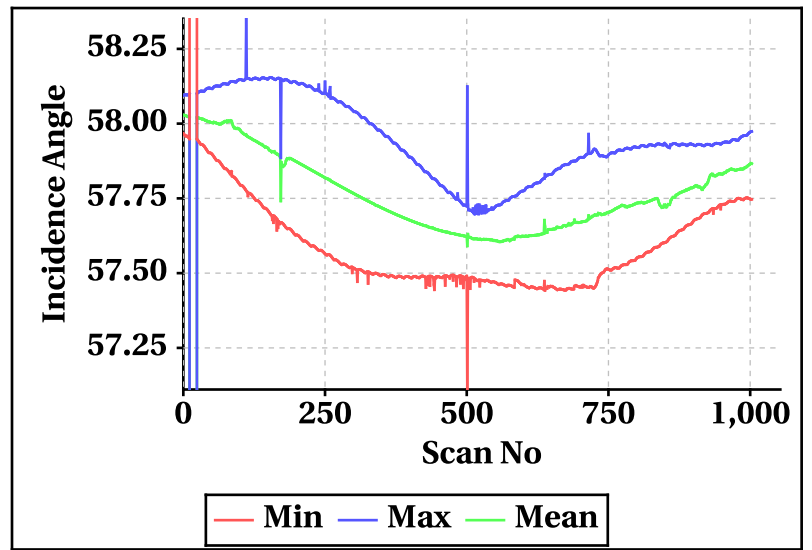


Orbit-wise behaviour of Incidence, Azimuth, Range, X-Factor

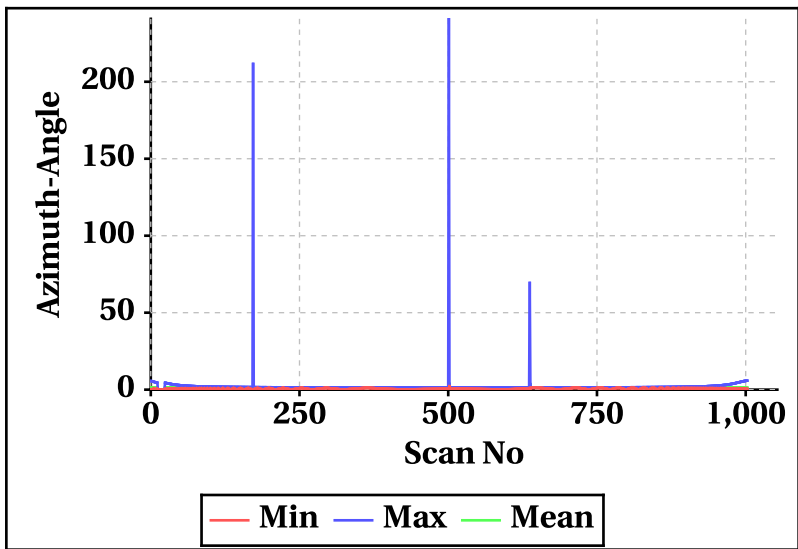
Inner Beam (HH)



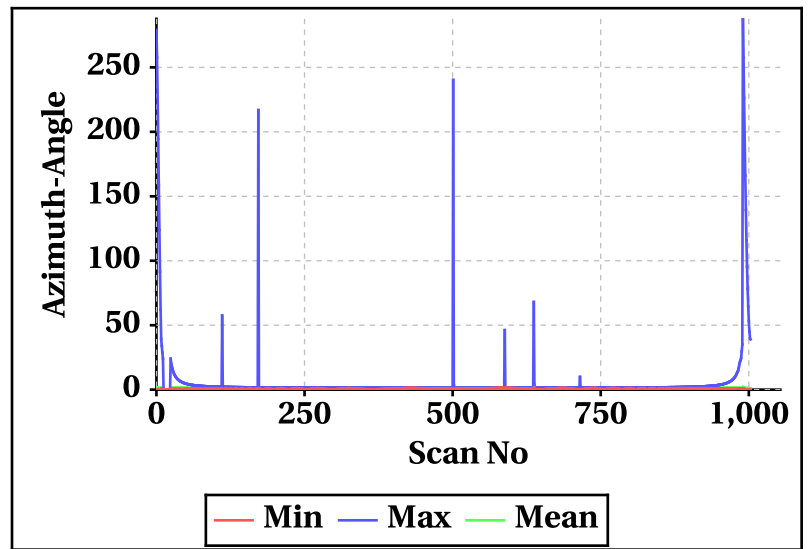
Outer Beam(VV)



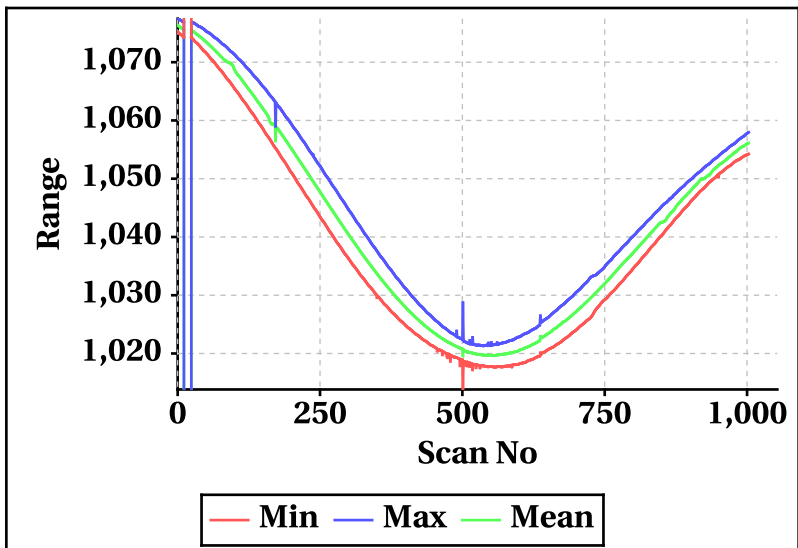
Inner Beam (HH)



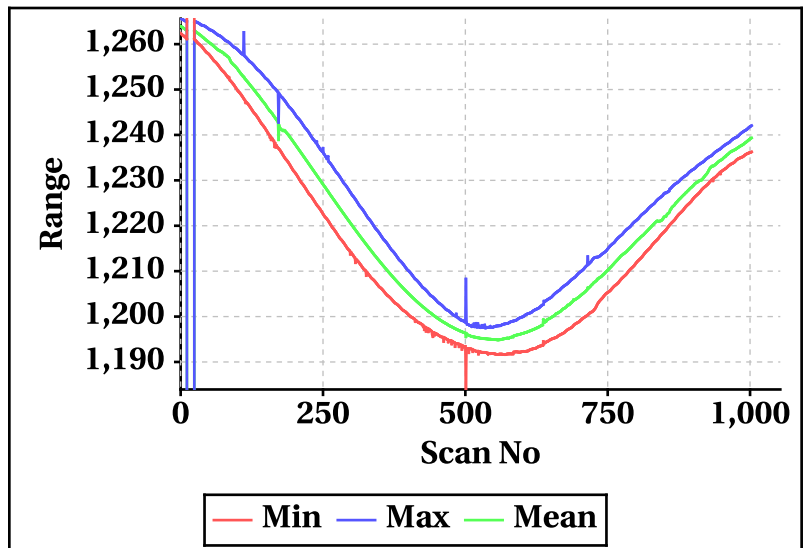
Outer Beam(VV)



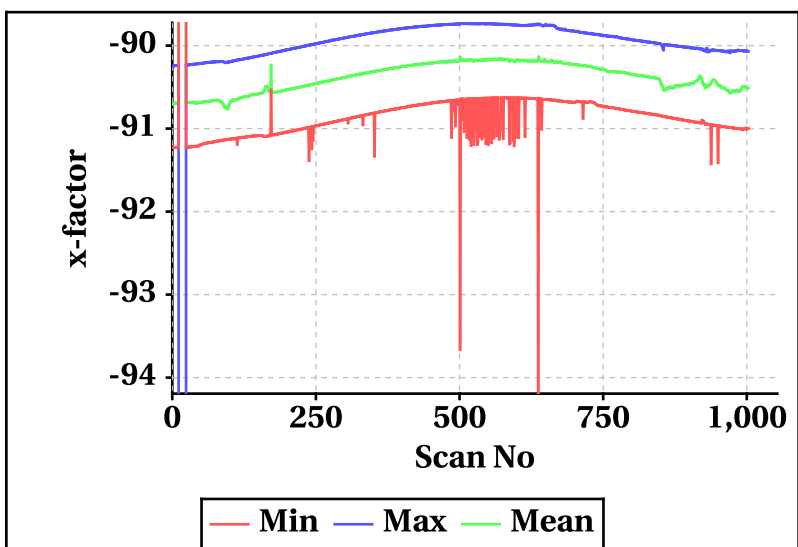
Inner Beam (HH)



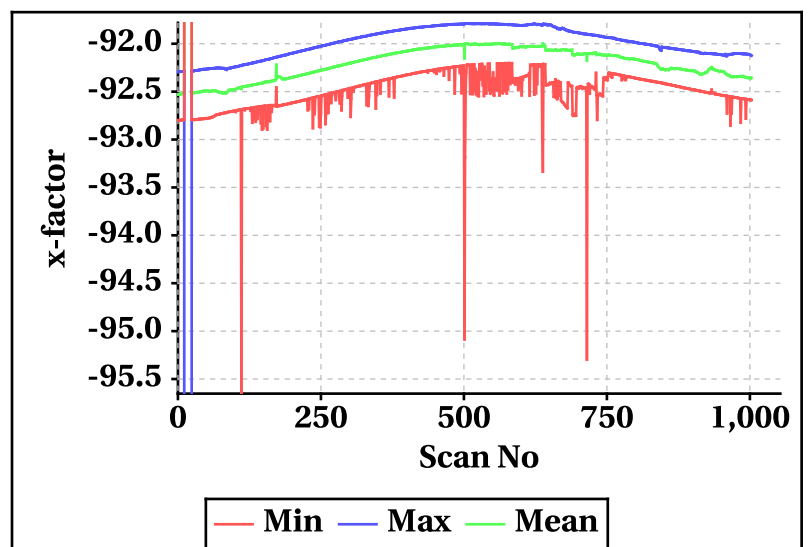
Outer Beam(VV)



Inner Beam (HH)



Outer Beam(VV)

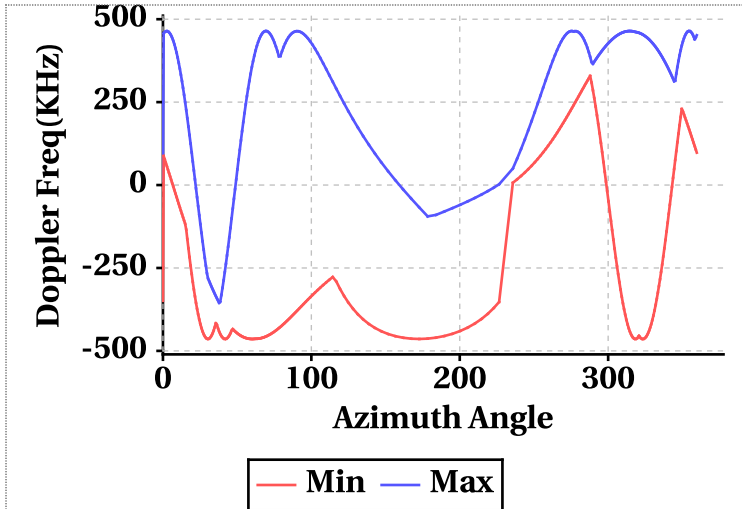


# Doppler Frequency Variation

**Doppler Frequency(KHz) variation statistics Over the half Orbit**

	Inner Beam (HH)	Outer Beam (VV)
<b>Min</b>	-464.08	-520.08
<b>Max</b>	464.24	520.18

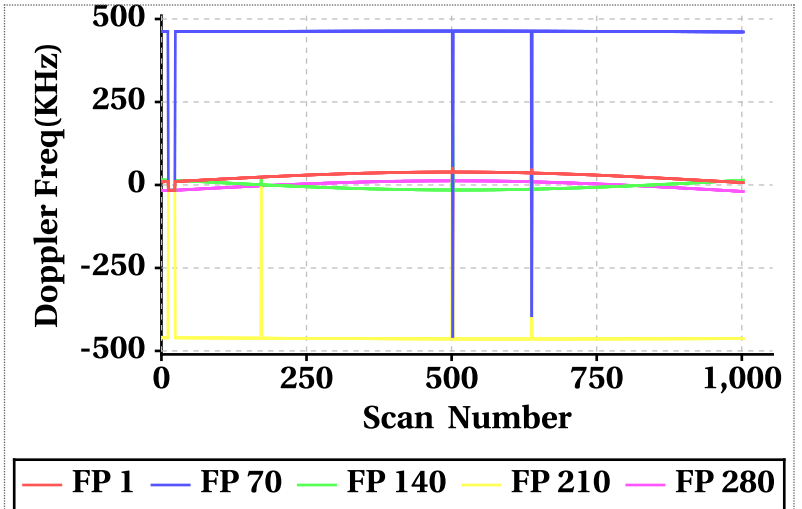
**Footprint wise Doppler frequency variation Inner Beam (HH)**



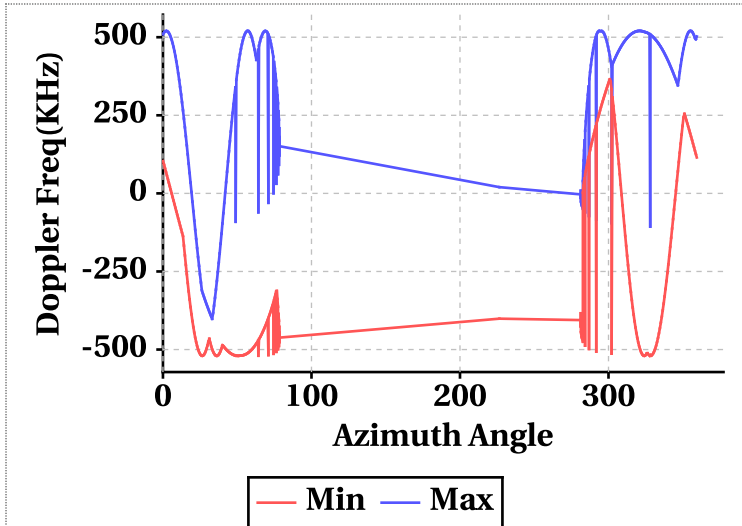
**Doppler Frequency(KHz) variation**

Doppler_FP	Inner Beam (HH)			Outer Beam (VV)		
	Min	Max	Mean	Min	Max	Mean
Doppler_1	-16.06	49.88	27.15	-12.28	39.38	24.90
Doppler_70	-456.22	463.68	455.29	-508.04	519.86	510.45
Doppler_140	-16.06	424.26	-3.66	-22.96	469.06	-9.83
Doppler_210	-464.02	373.38	-455.44	-519.90	428.14	-510.32
Doppler_280	-349.16	33.82	0.37	-401.20	37.98	6.27

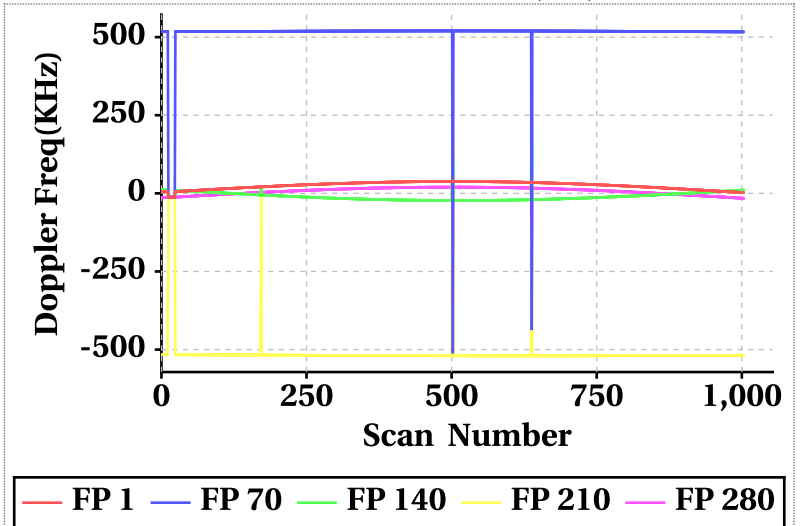
**Doppler frequency variation at footprints: 1, 70, 140, 210 & 280 Inner Beam (HH)**



**Footprint wise Doppler frequency variation Outer Beam (VV)**

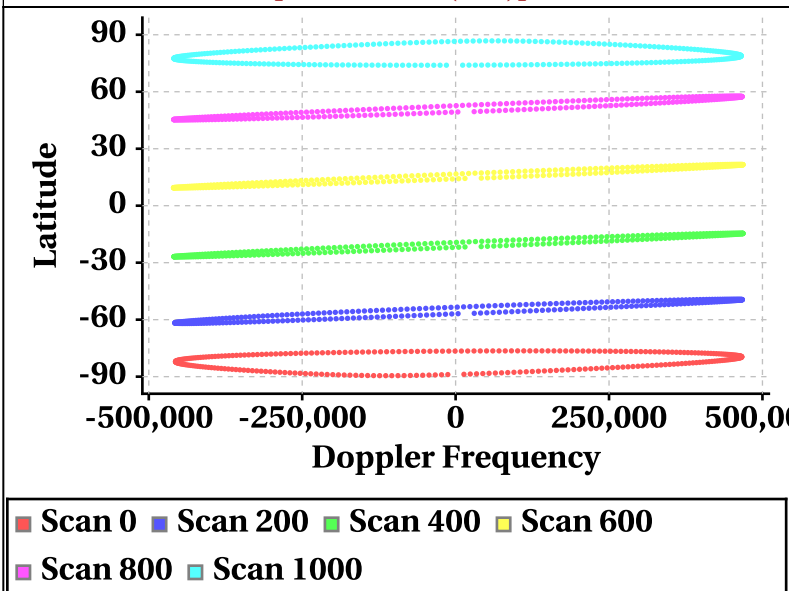


**Doppler frequency variation at footprints: 1, 70, 140, 210 & 280 Outer Beam (VV)**

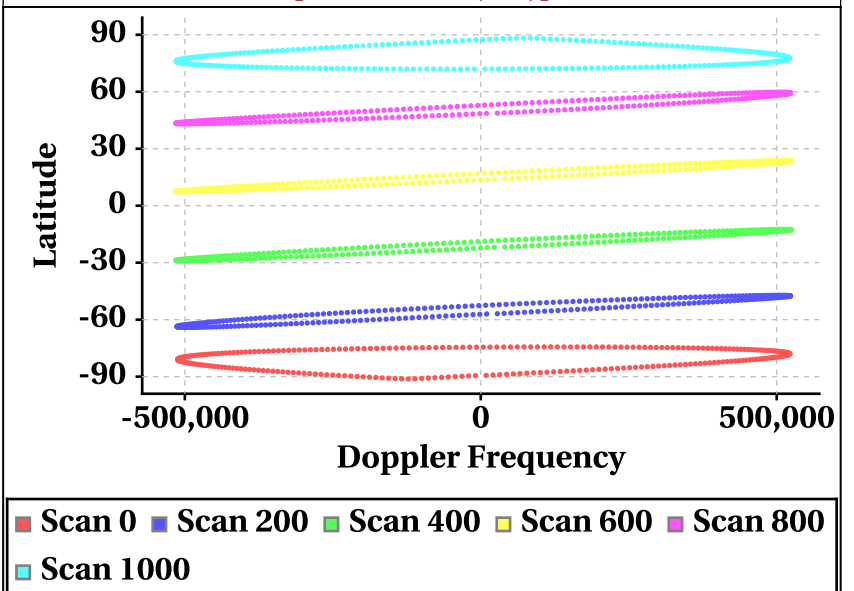


## Latitude Vs Doppler Frequency

**Doppler Frequency at Scan Interval of 200 [Inner Beam(HH)]**



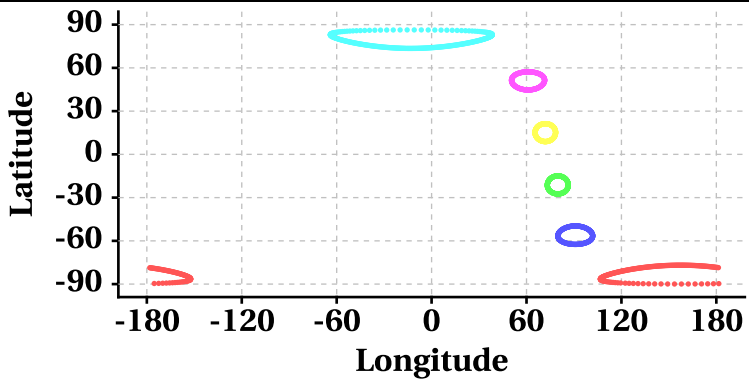
**Doppler Frequency at Scan Interval of 200 [Outer Beam(VV)]**



# Parameter as a function of Latitude

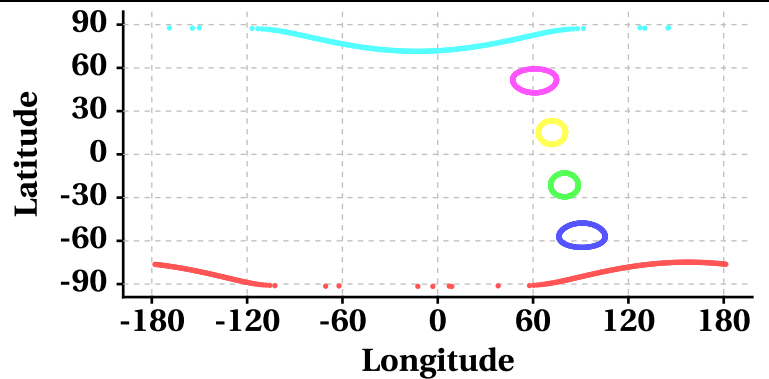
## Latitude Vs Longitude

Scan Trace [Inner Beam(HH)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800 Scan 1000

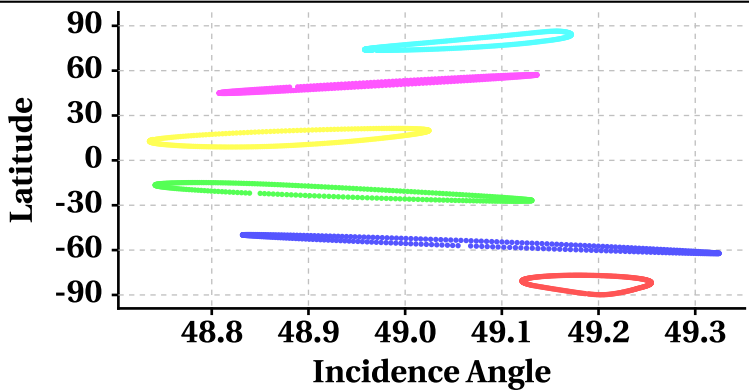
Scan Trace [Outer Beam (VV)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800 Scan 1000

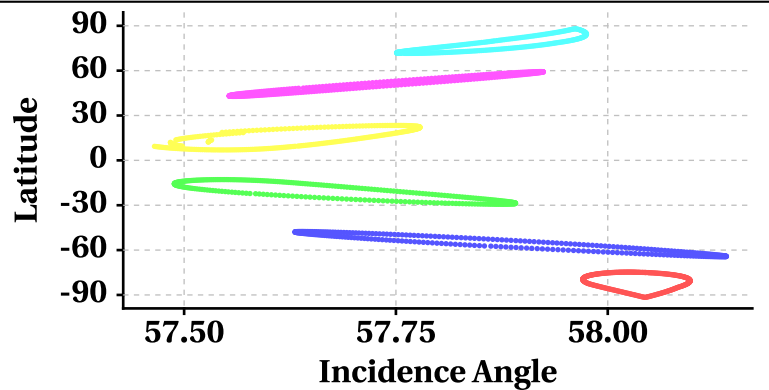
## Latitude Vs Incidence Angle

Incidence Angle at Scan Interval of 200 [Inner Beam(HH)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800 Scan 1000

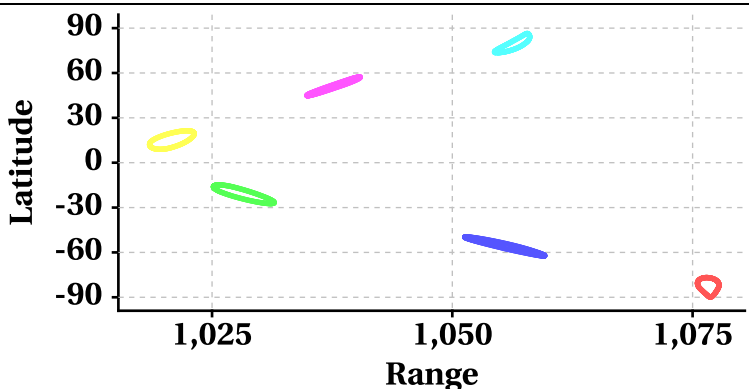
Incidence Angle at Scan Interval of 200 [Outer Beam (VV)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800 Scan 1000

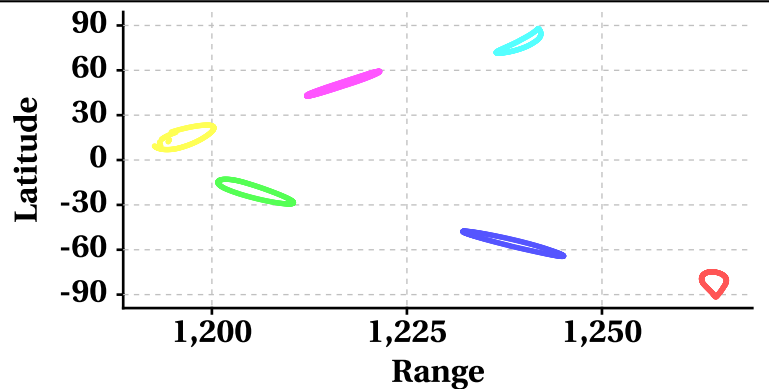
## Latitude Vs Range

Range at Scan Interval of 200 [Inner Beam(HH)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800 Scan 1000

Range at Scan Interval of 200 [Outer Beam(VV)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800 Scan 1000



# Variation in Orbit and Attitude Parameters

