

SCATSAT-1 Scatterometer Level-1B Data Quality Evaluation Report

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Satellite Id	ScatSat-1	Start Orbit	15992	Total Scans	1004
Sensor Name	Scatterometer	End Orbit	15993	No of Inner FootPrints	281
Processor Version	v1.1.3	Rev. Number	15992_15993	No Of Outer FootPrints	282
Half Orbit Direction	SN	Data Production Date	04-10-2019	No. Of Inner Slices	9
Equator Crossing Date	04-10-2019	Equator Crossing Time	03:57:32.000	No Of Outer Slices	15

Brightness Temperature(k) Footprint trace

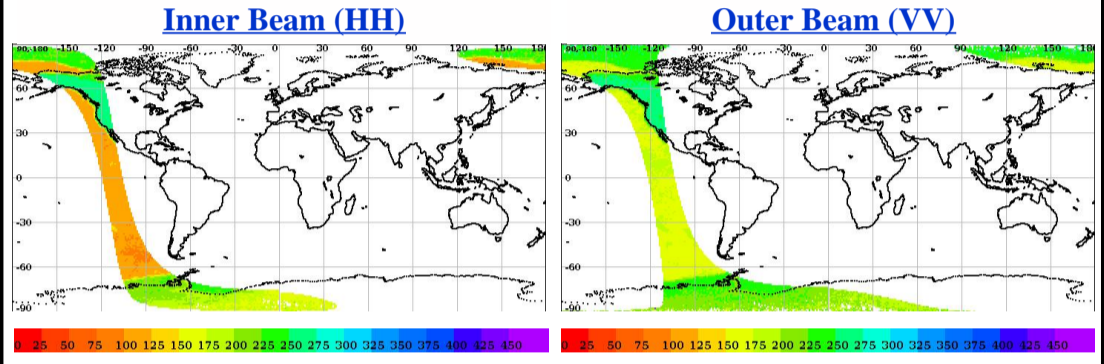
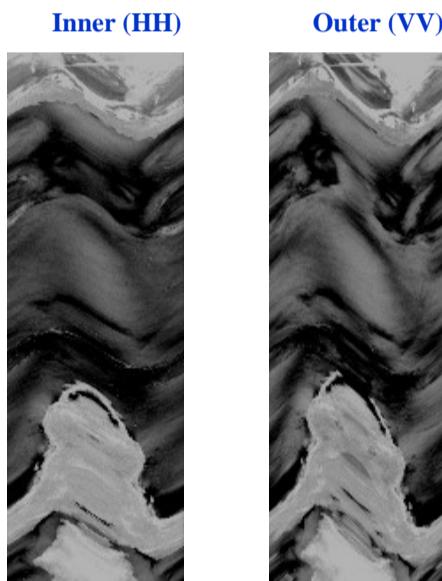
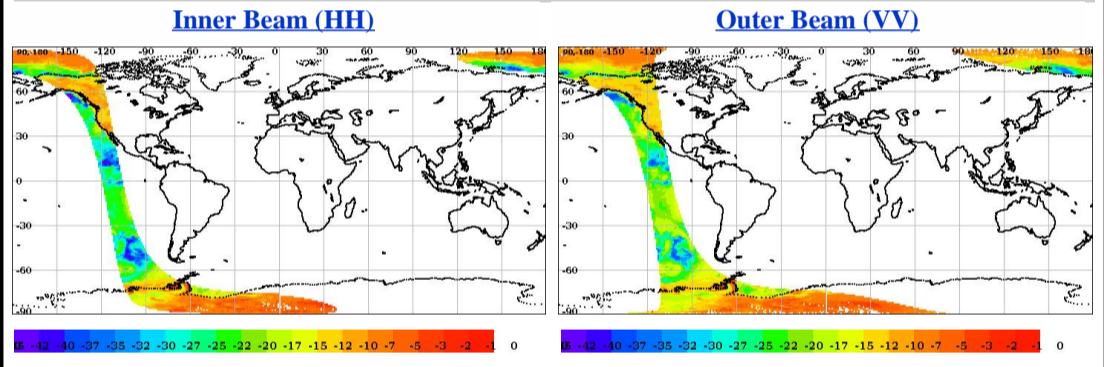


Image Snapshot for Inner & Outer Beam



Sigma0(dB) Footprint trace



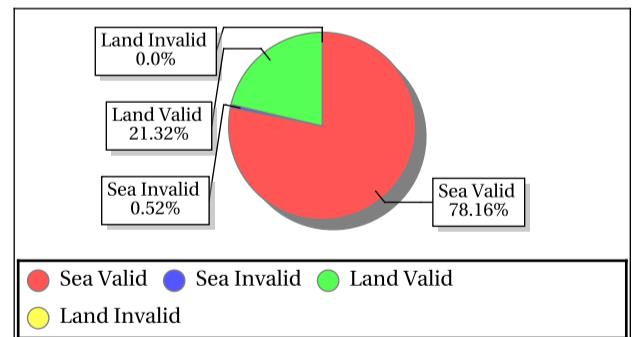
Invalid and Poor Sigma-0 Quality Flag Statistics for Inner/Outer Slices*

Sigma-0 Flags	Inner Beam	Outer Beam
Invalid Sigma0(%)	0.52	0.52
Data Not Available From Payload (%)	100.0	100.0
Slice not within sample array limits (%)	0.00	0.00
C(S+N) - C(N) < 0.1 (%)	0.00	0.00
Poor Sigma0(%)	22.22	13.34
Noise samples for blending Saturated	0.0	0.0
Count samp. for interpol. saturated (%)	0.00	0.00
Sigma0 < lower bound (-96dB) (%)	0.0	0.0
Sigma0 > upper bound (0 dB) (%)	0.00	0.00
SNR < -65 dB (%)	0.05033	0.091614

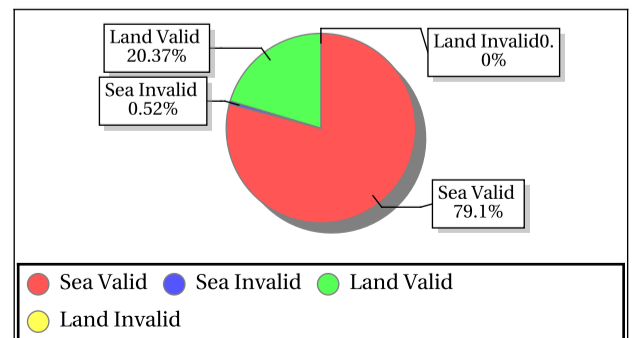
*DP Format Document

Sigma-0 Quality Flag Statistics for Inner/Outer Footprints

Inner Beam (HH)



Outer Beam (VV)



Overall statistics for the Static Parameters (Footprint-wise)

Inner Beam (HH)																
	Sea Aft				Sea Fore				Land Aft				Land fore			
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)
Kp	0.12	298.86	0.39	3.740	0.12	283.72	0.33	3.014	0.12	4.29	0.12	0.025	0.12	7.89	0.12	0.018
Kpa	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
Kpb	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000
Kpc	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
SNR	-34.89	23.97	3.97	0.075	-34.66	23.90	5.46	0.559	-16.37	27.95	17.61	9.230	-19.06	28.93	17.60	5.271

Outer Beam (VV)																
	Sea Aft				Sea Fore				Land Aft				Land fore			
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)
Kp	0.09	200.71	0.33	3.258	0.09	223.50	0.32	3.018	0.09	0.55	0.09	0.000	0.09	221.44	0.10	0.015
Kpa	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
Kpb	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
Kpc	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
SNR	-34.33	17.48	2.28	0.000	-34.79	18.41	3.22	0.000	-8.10	21.86	11.82	0.000	-34.75	22.22	11.14	0.012

Parameter Specifications					
Parameter	Kp	Kpa	Kpb	Kpc	SNR
Min	0.00	0.00	0.00	0.00	-65.00
Max	1.00	1.00	1.00	1.00	22.00

- Normal
- Deviations
- Alarming
- High Errors

Overall statistics for static parameter (Footprint-wise)

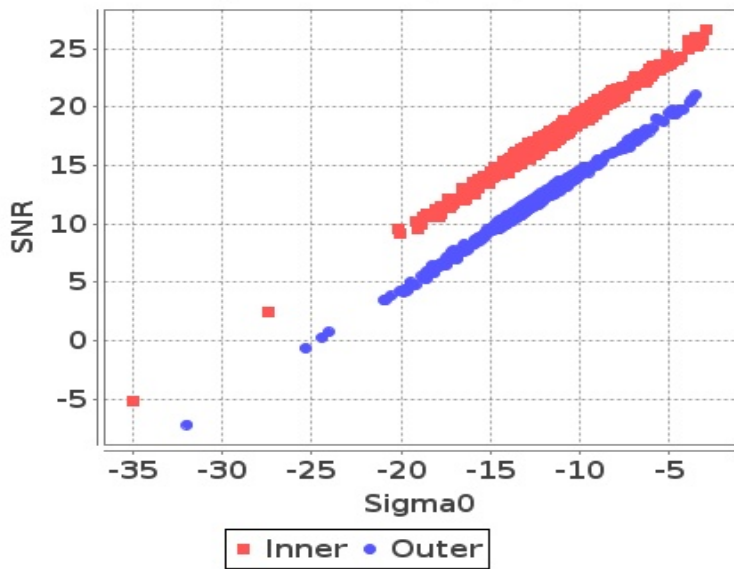
	Inner Beam (HH)				Outer Beam (VV)				Parameter Specifications		
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Parameter	Min	Max
Incidence Angle (deg)	48.77	49.47	49.05	0.000	57.52	58.26	57.93	0.000	Inci.(Inner)	47.10	49.90
Azimuth Diff. (deg)	0.0000	223.96	1.27	2.783	0.0000	297.59	1.27	3.805	Inci.(Outer)	57.30	58.90
Range(Km)	1029.71	1080.20	1049.77	0.000	1206.95	1269.20	1231.01	7.000	Azimuth Diff.	0.60	2.00
X Factor(dbm)	-91.75	-89.99	-90.47	0.000	-93.61	-92.03	-92.23	0.000	Range(Inner)	1025.00	1095.70
Across Distance (Km)	15.49	16.01	15.73	0.000	12.57	37.94	20.76	5.000	Range(Outer)	1210.00	1280.00
Along Distance (Km)	18.70	10073.94	197.63	18.000	8.97	10295.93	201.53	20.000	X-Factor	-100.00	-80.00
									Ac.Distance(Inner)	15.00	20.00
									Ac.Distance(Outer)	15.00	22.00
									Al.Distance(Inner)	15.00	30.00
									Al.Distance(Outer)	10.00	30.00
									 Normal	 Alarming	
									 Deviations	 High Errors	



Sigma0 Behaviour (Sigma0 Vs SNR)

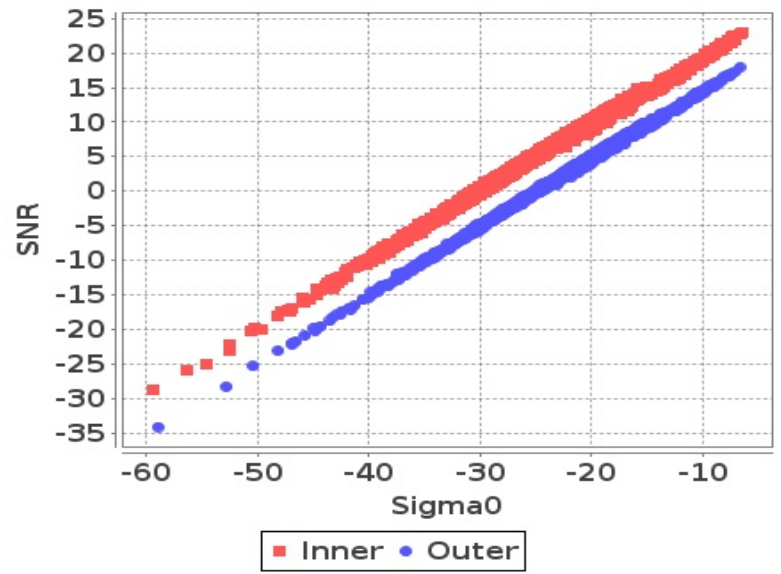
Footprint-Land

Sigma0 Vs SNR (Land)



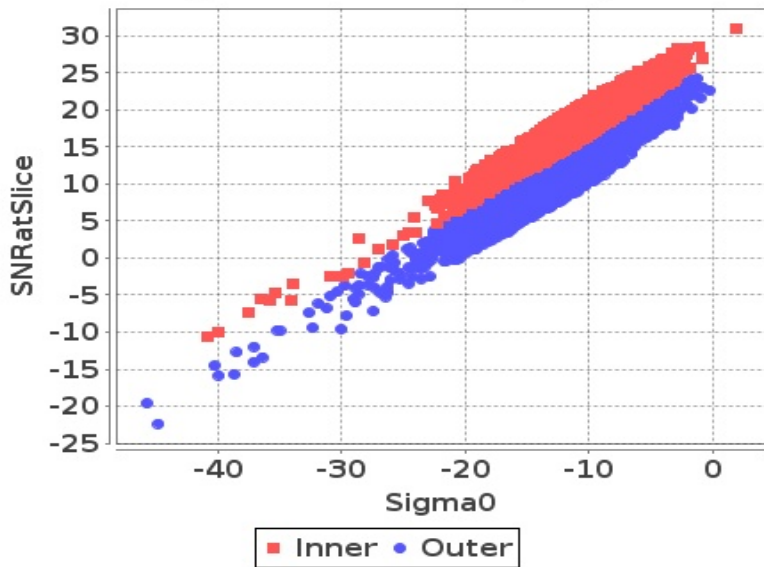
Footprint-Sea

Sigma0 Vs SNR (Sea)



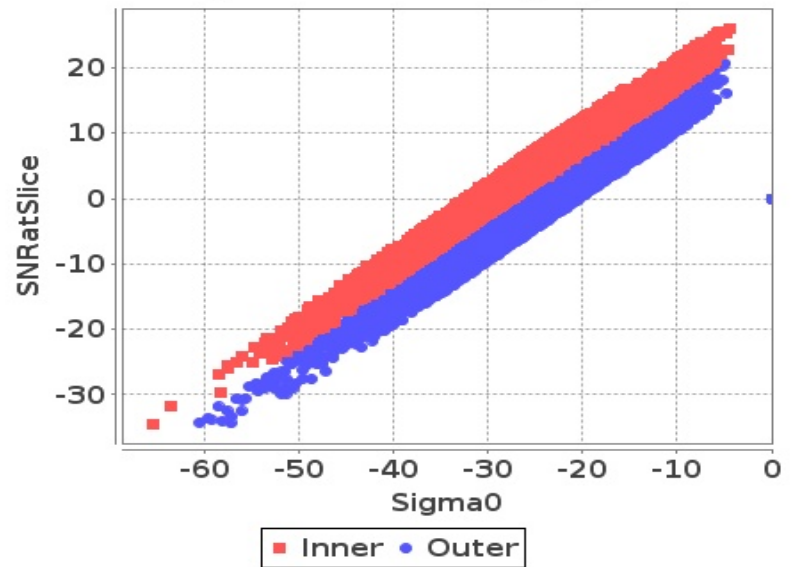
Slice-Land

Sigma0 Vs SNRatSlice (Land)



Slice-Sea

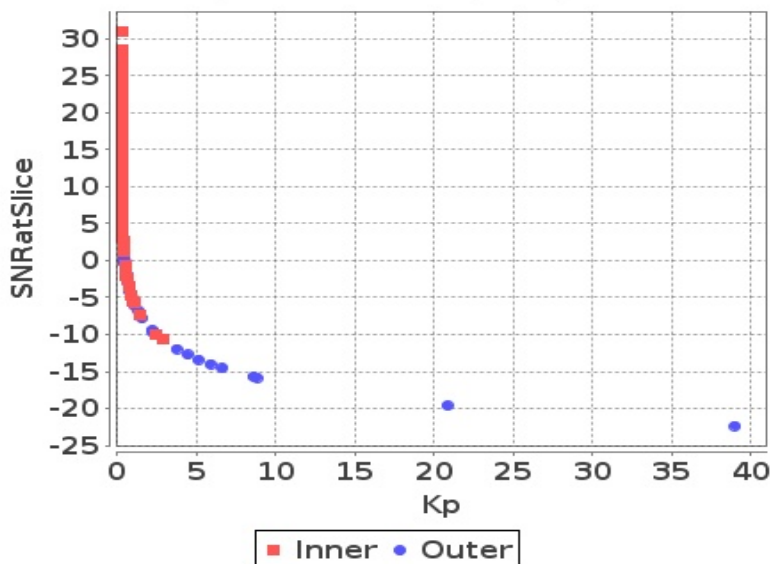
Sigma0 Vs SNRatSlice (Sea)



Sigma0 Behaviour (Kp Vs SNR)

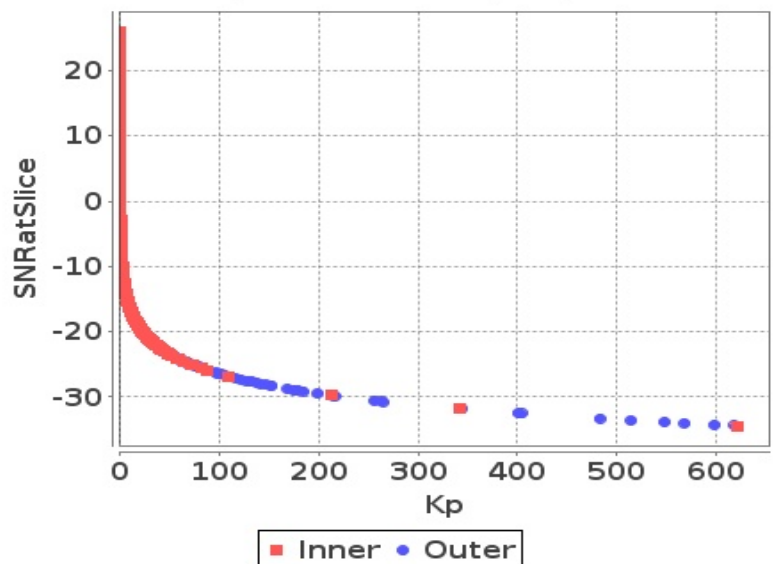
Slice

Kp Vs SNRatSlice (Land)



Slice

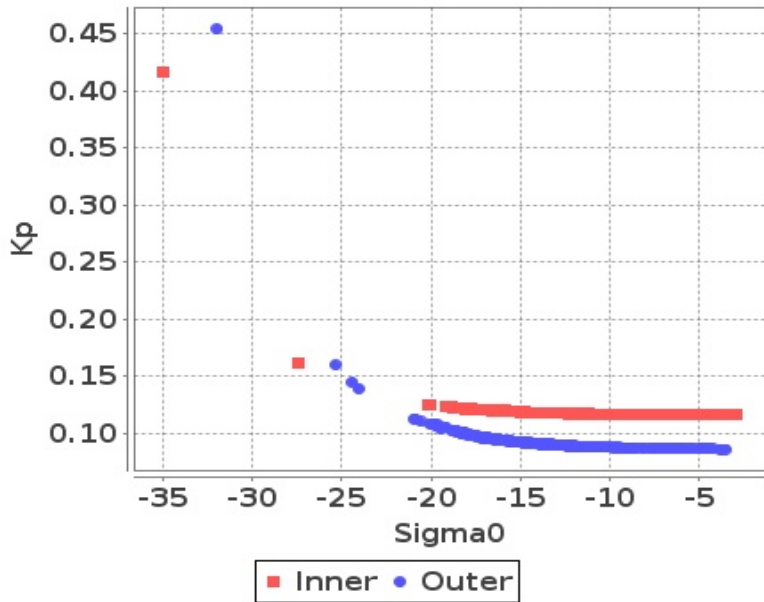
Kp Vs SNRatSlice (Sea)



Sigma0 Behaviour(Sigma0 Vs Kp)

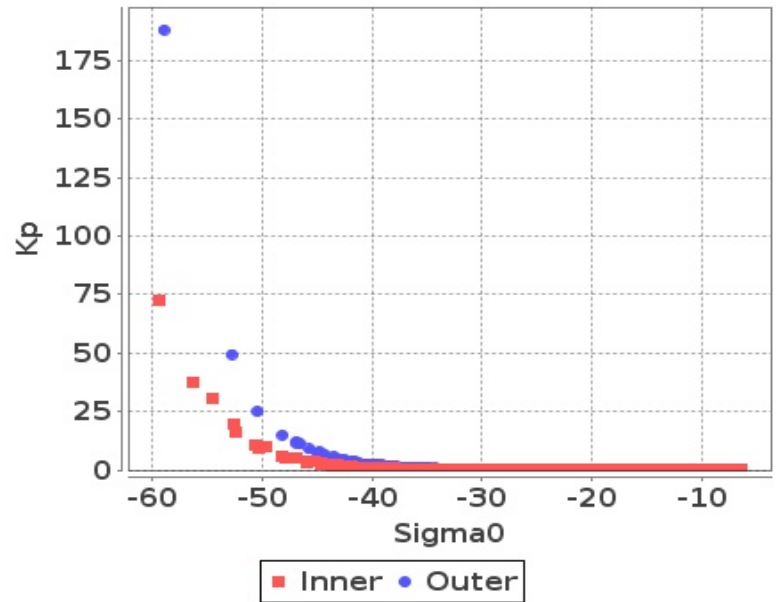
Footprint-Land

Sigma0 Vs Kp (Land)



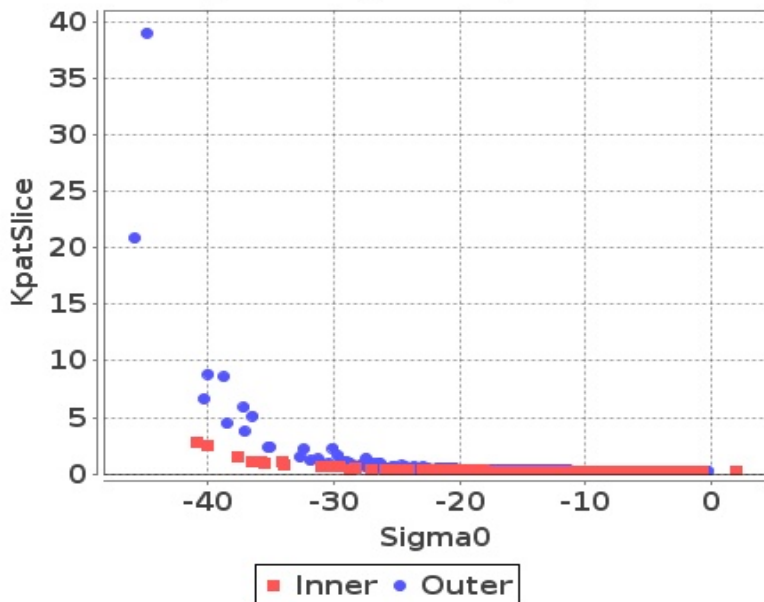
Footprint-Sea

Sigma0 Vs Kp (Sea)



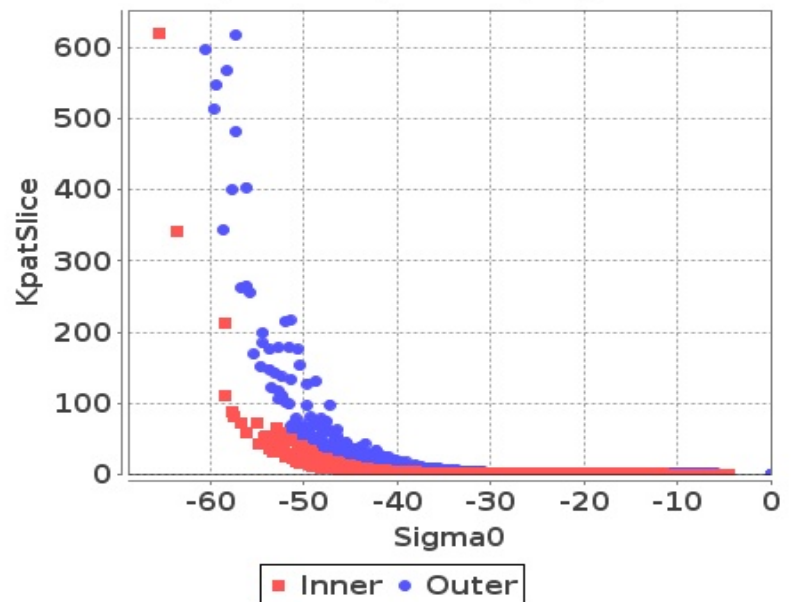
Slice-Land

Sigma0 Vs KpatSlice (Land)



Slice-Sea

Sigma0 Vs KpatSlice (Sea)

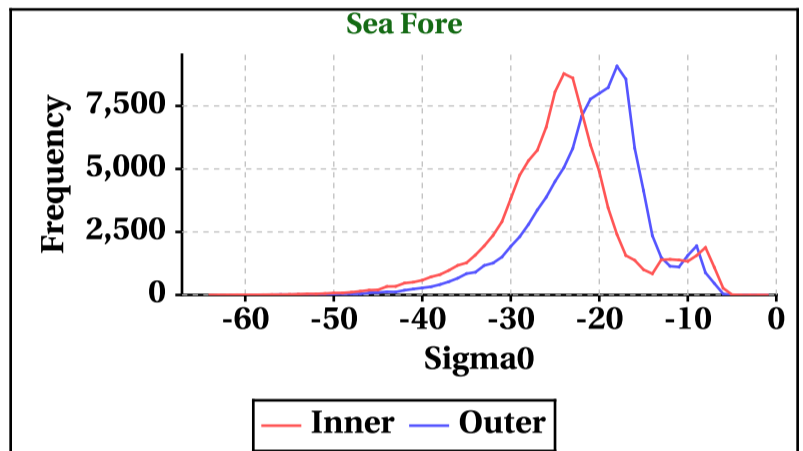
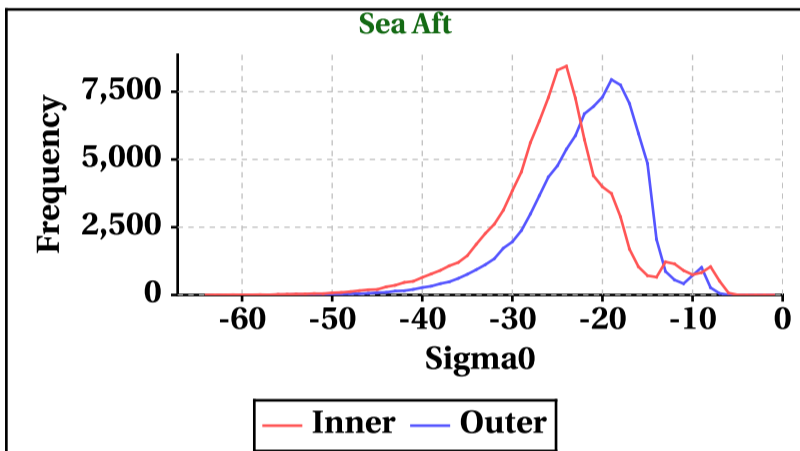
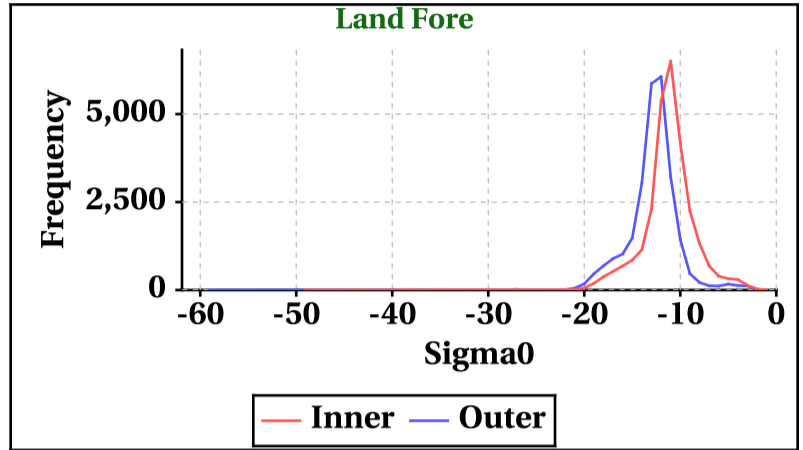
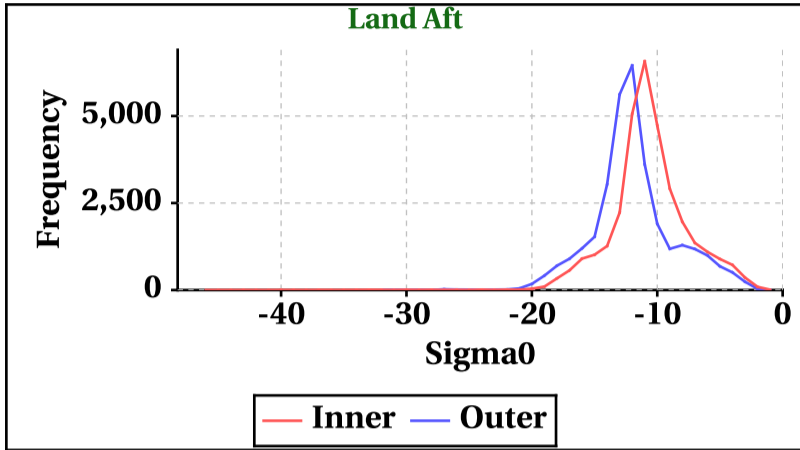


Dynamic Range (Data Histograms)

Sigma0(db)

Inner Beam (HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-46	-49	-64	-64
Max	0	0	0	0

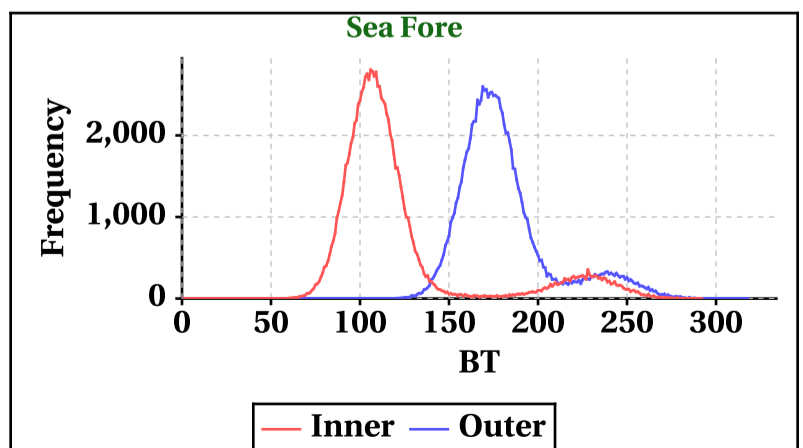
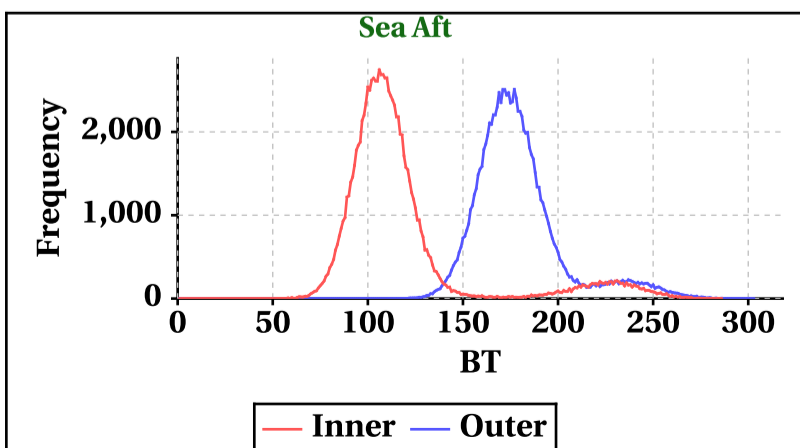
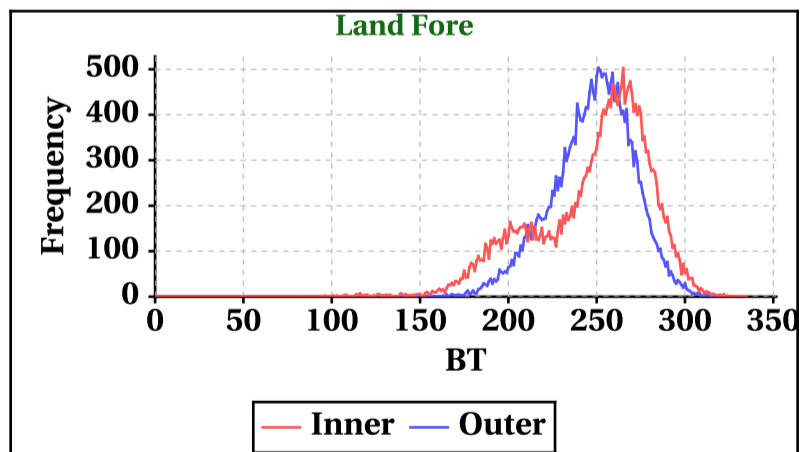
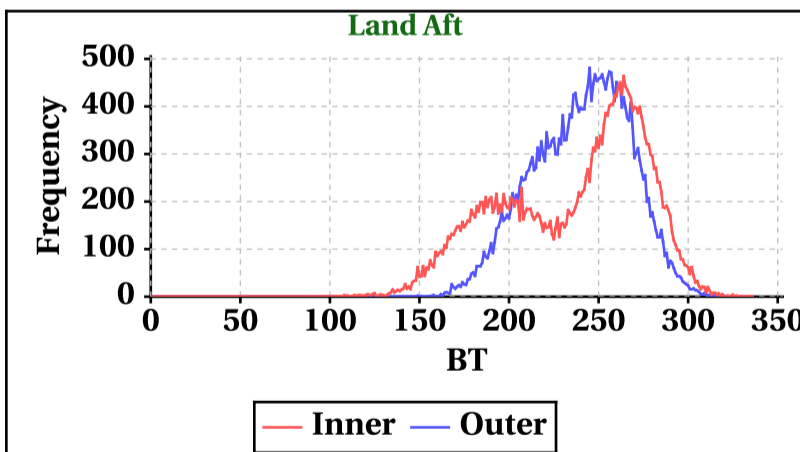
Outer Beam (VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-32	-59	-58	-59
Max	0	0	0	0



Brightness Temperature(K)

Inner Beam(HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	0	0
Max	336	335	286	292

Outer Beam(VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	0	0
Max	333	329	303	318

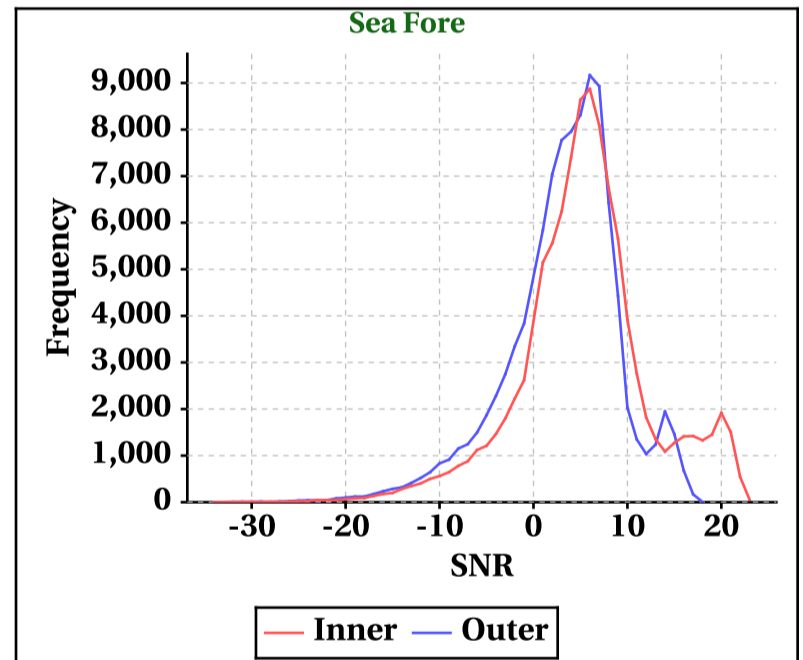
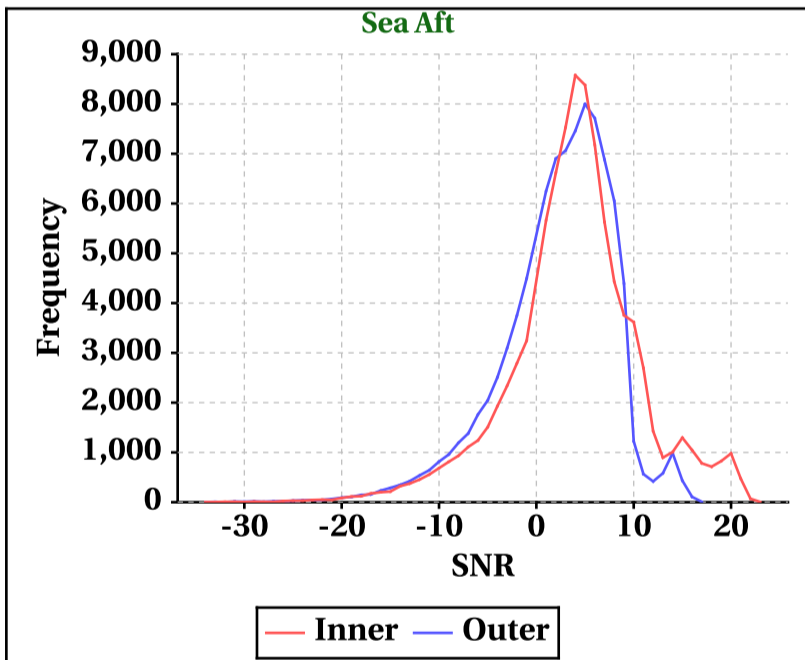
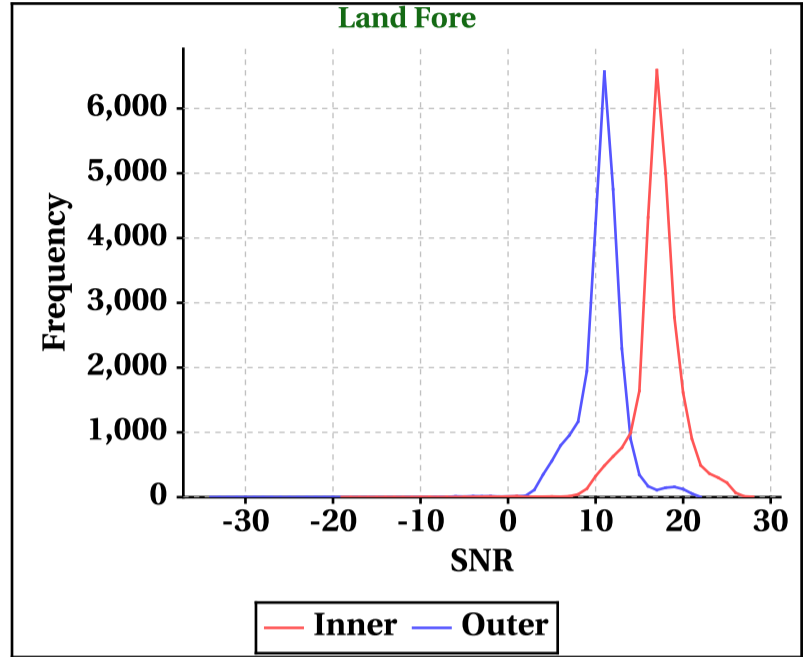
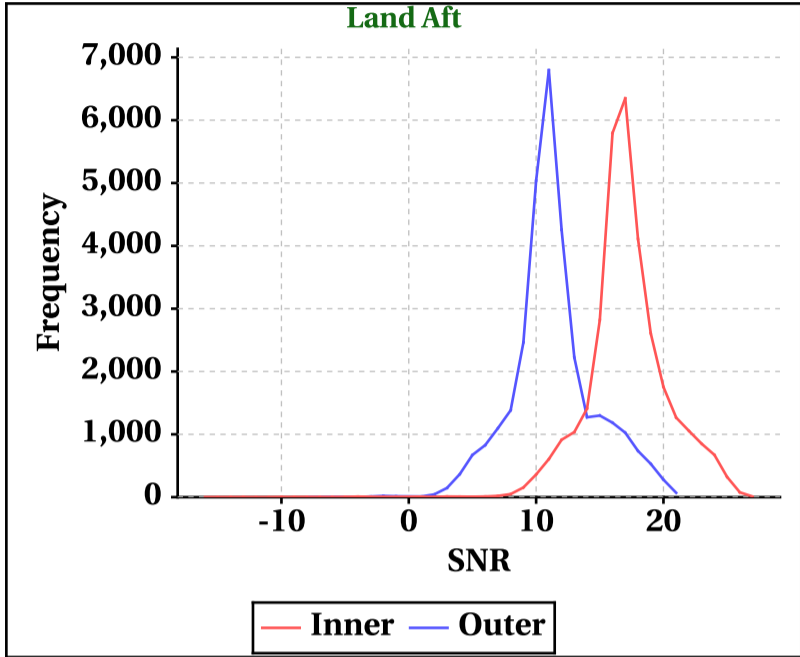


Dynamic Range (Data Histograms)

SNR(dBm)

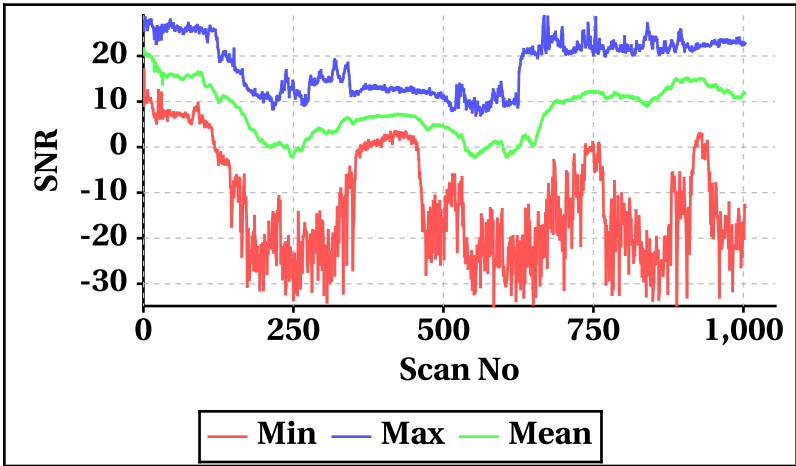
Inner Beam (HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-16	-19	-34	-34
Max	27	28	23	23

Outer Beam (VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-8	-34	-34	-34
Max	21	22	17	18

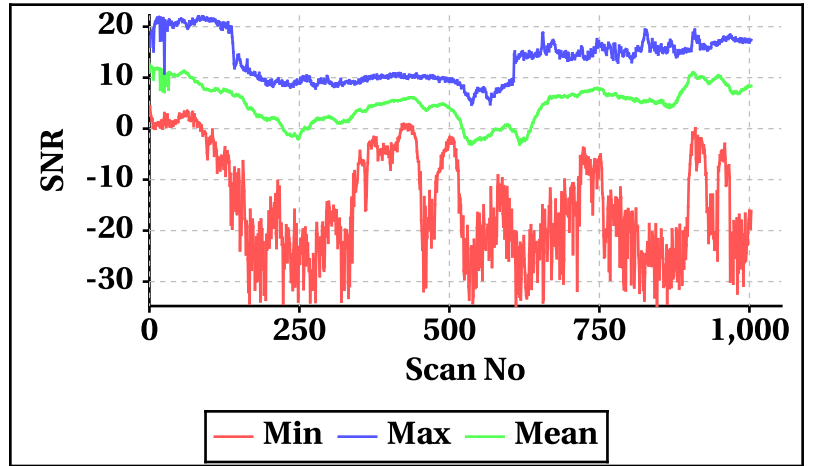


Orbit-wise behaviour of SNR

Inner Beam (HH)

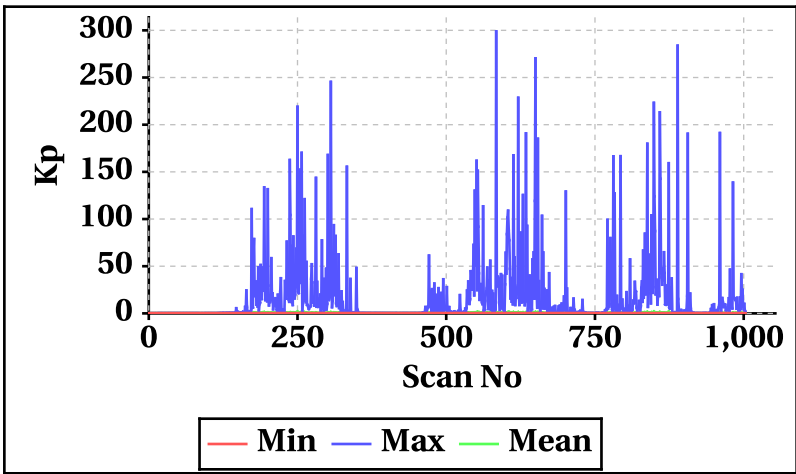


Outer Beam(VV)

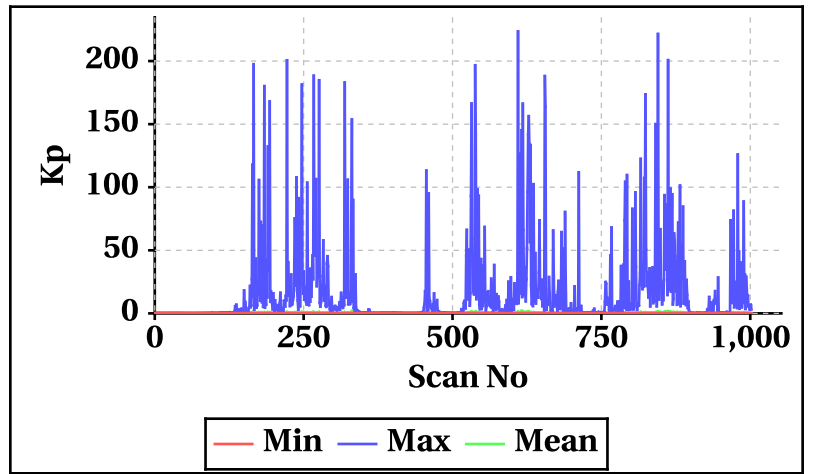


Orbit-wise behaviour of Kp,Kpa,Kpb,Kpc

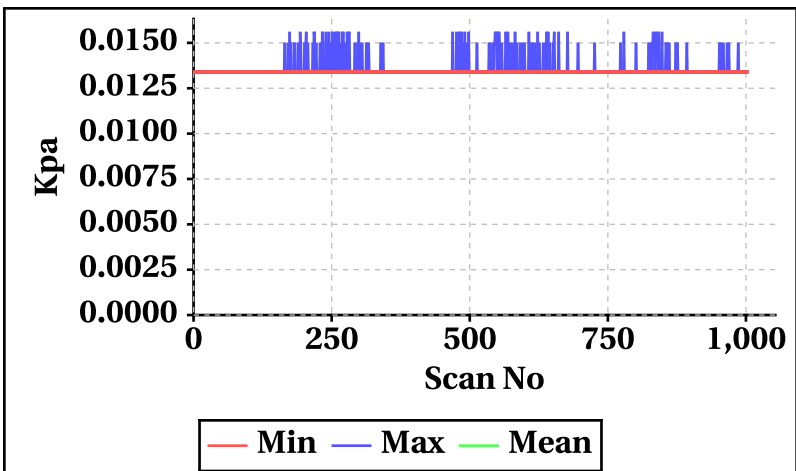
Inner Beam(HH)



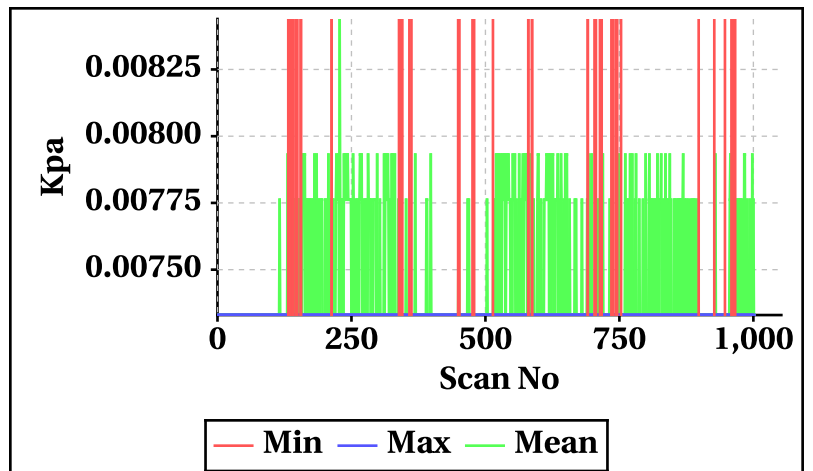
Outer Beam(VV)



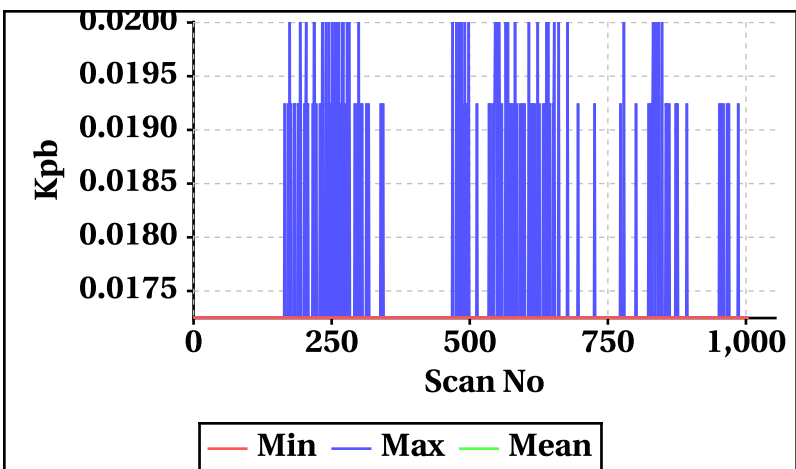
Inner Beam(HH)



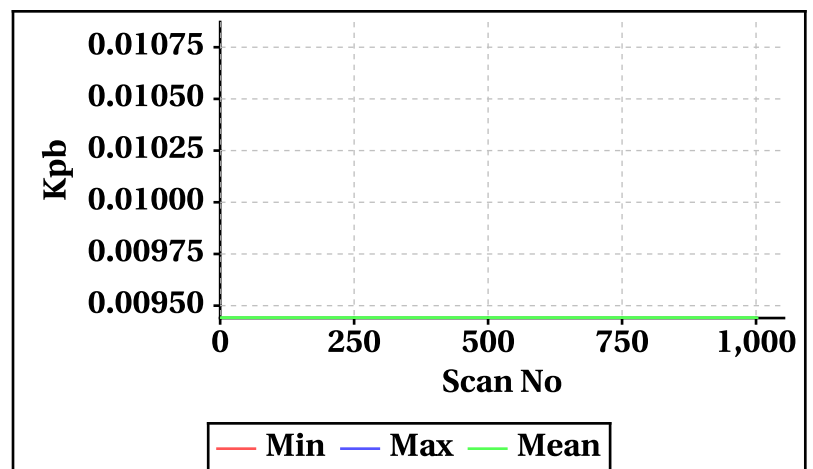
Outer Beam(VV)



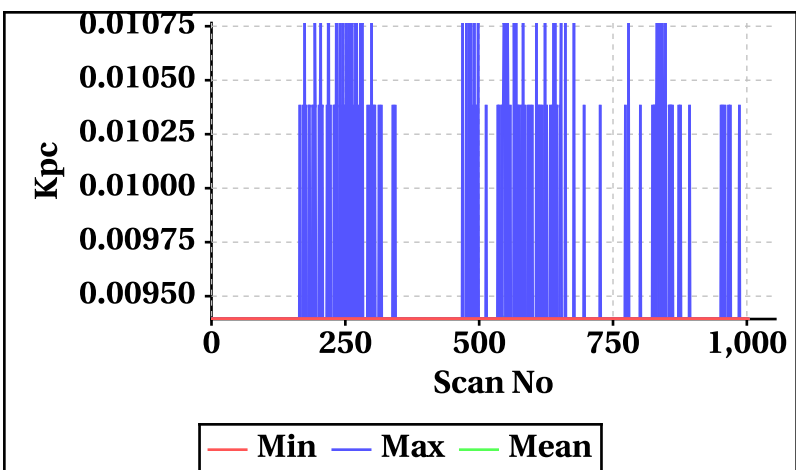
Inner Beam(HH)



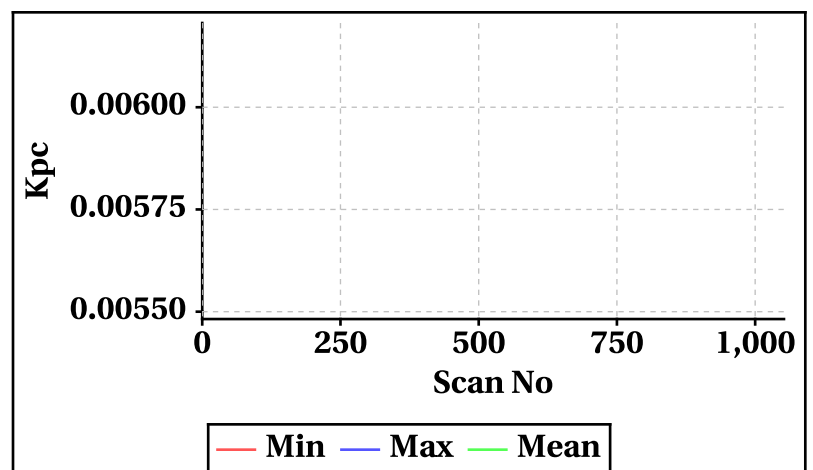
Outer Beam(VV)



Inner Beam(HH)

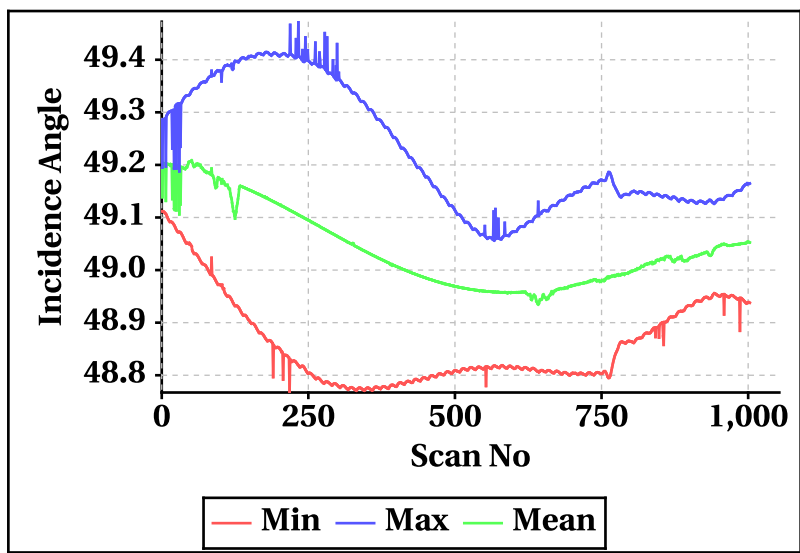


Outer Beam(VV)

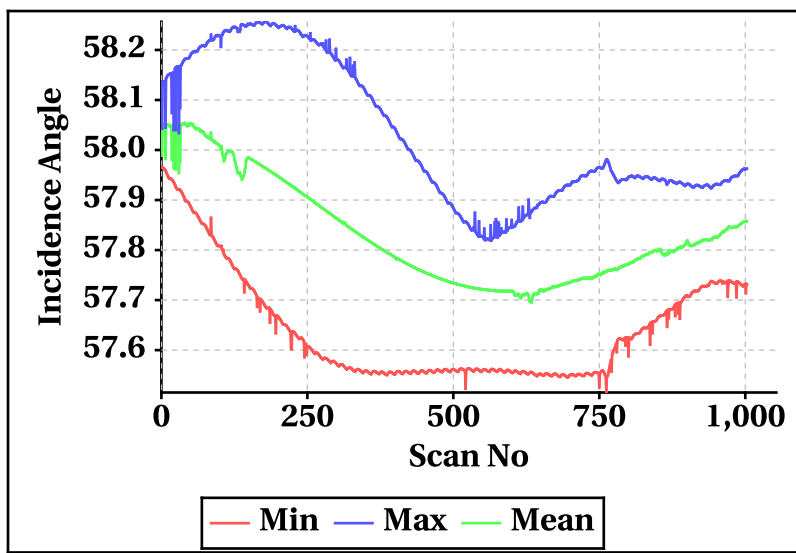


Orbit-wise behaviour of Incidence, Azimuth, Range, X-Factor

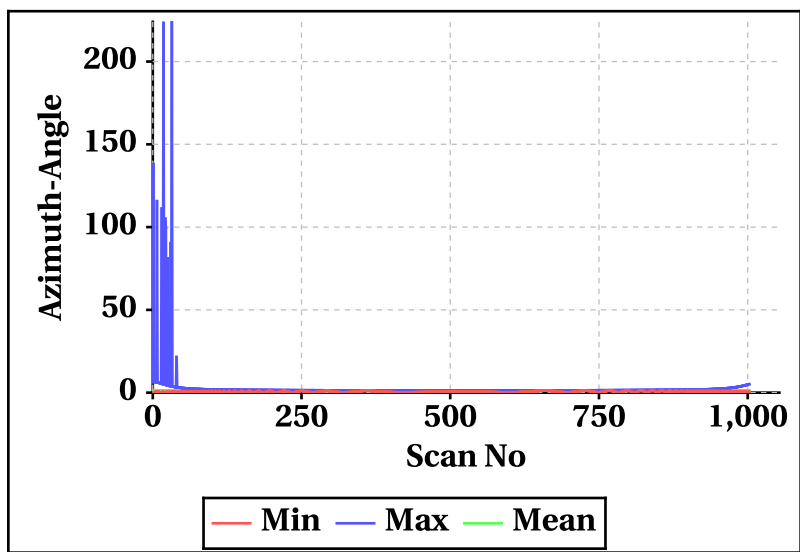
Inner Beam (HH)



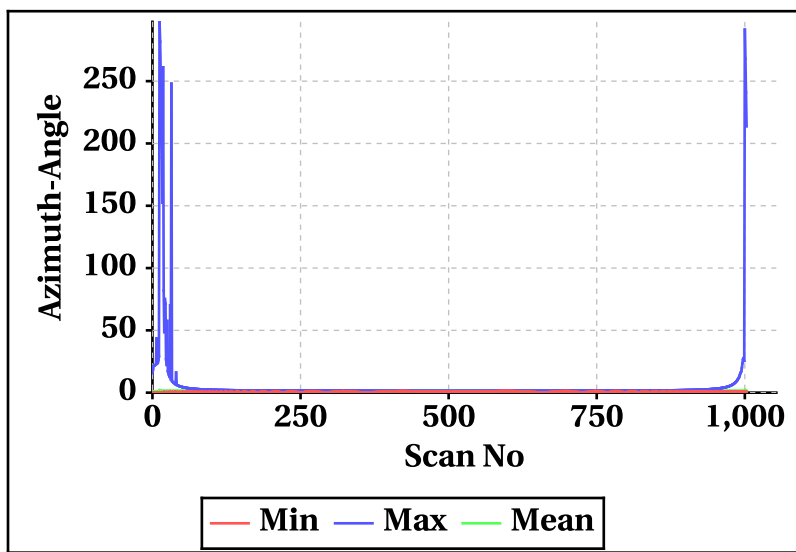
Outer Beam(VV)



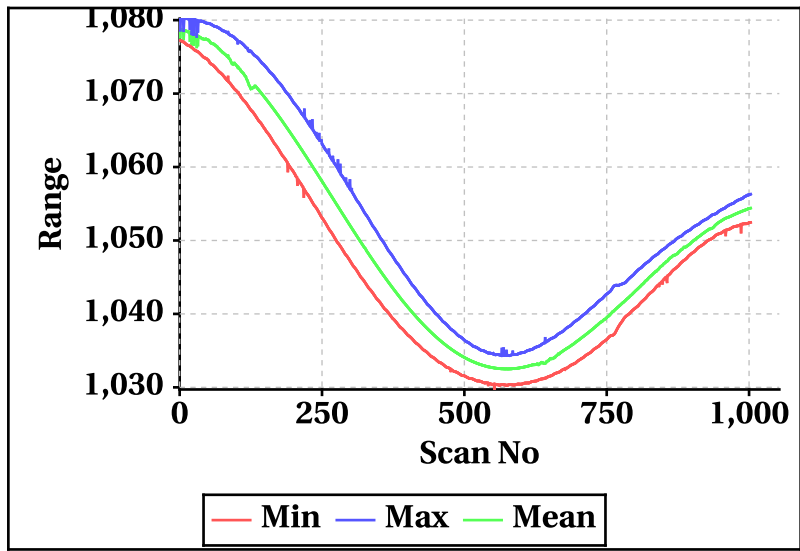
Inner Beam (HH)



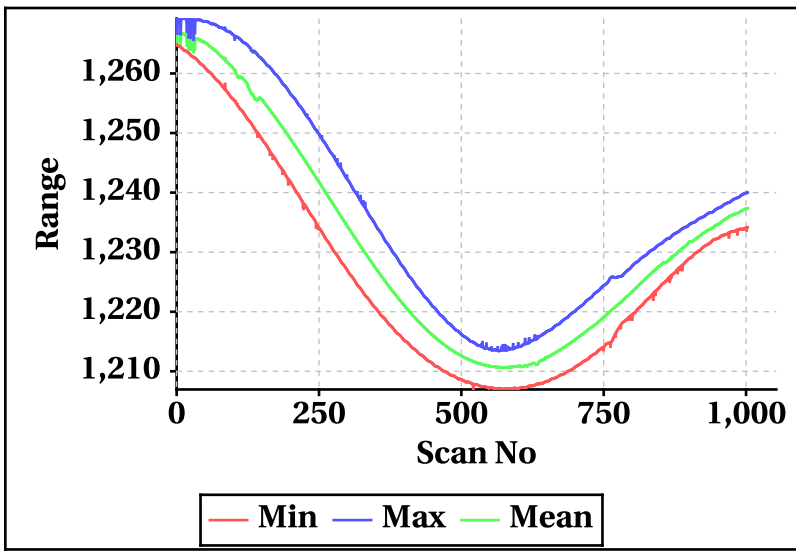
Outer Beam(VV)



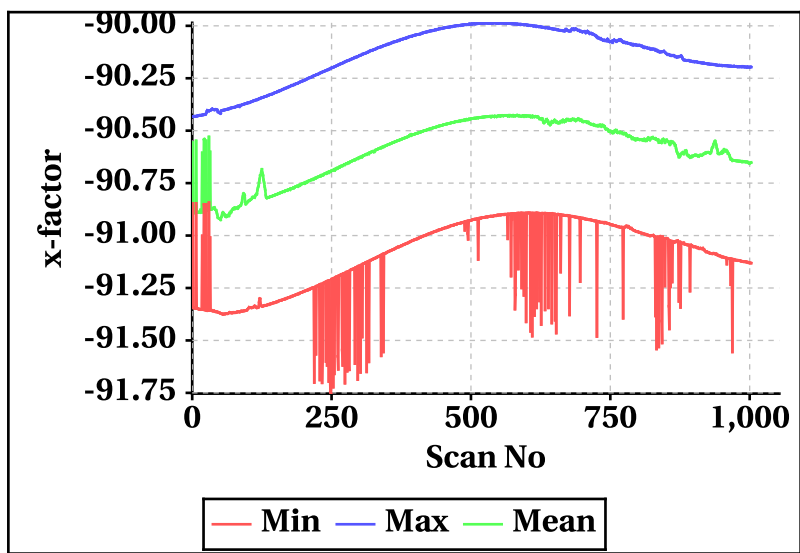
Inner Beam (HH)



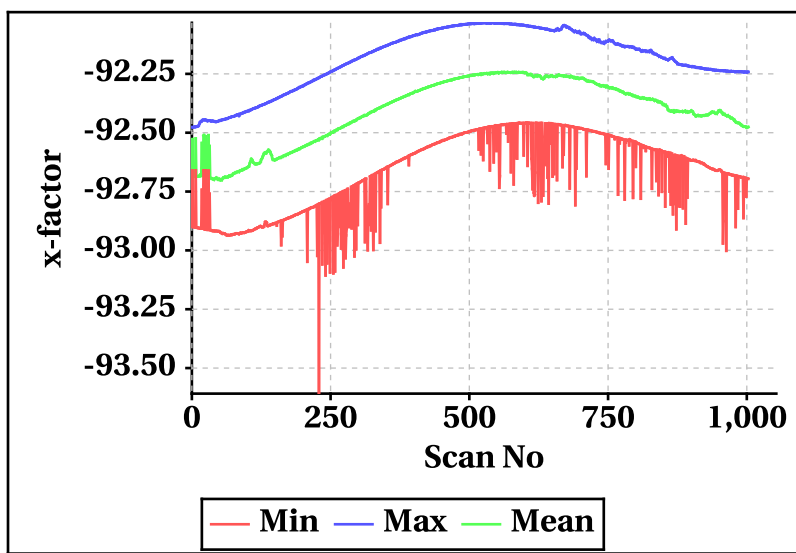
Outer Beam(VV)



Inner Beam (HH)



Outer Beam(VV)

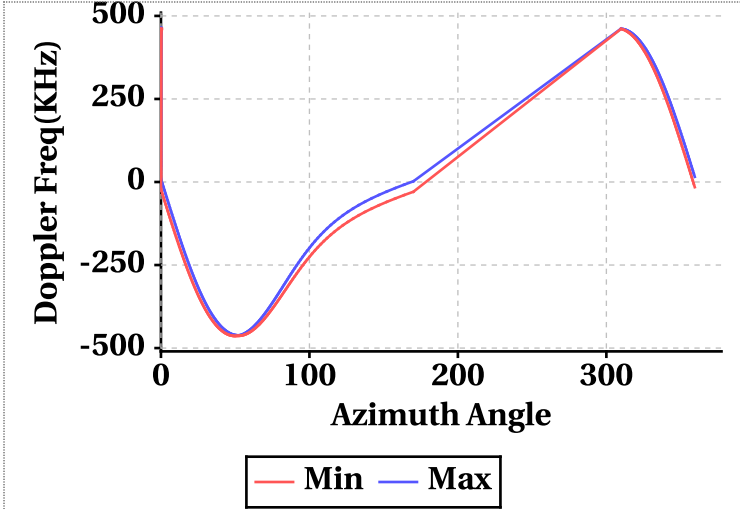


Doppler Frequency Variation

Doppler Frequency(KHz) variation statistics Over the half Orbit

	Inner Beam (HH)	Outer Beam (VV)
Min	-463.60	-519.54
Max	463.48	519.42

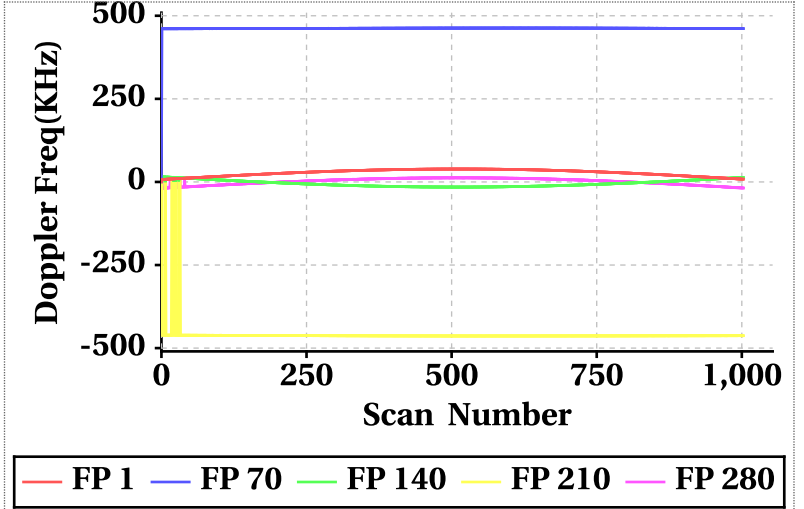
Footprint wise Doppler frequency variation Inner Beam (HH)



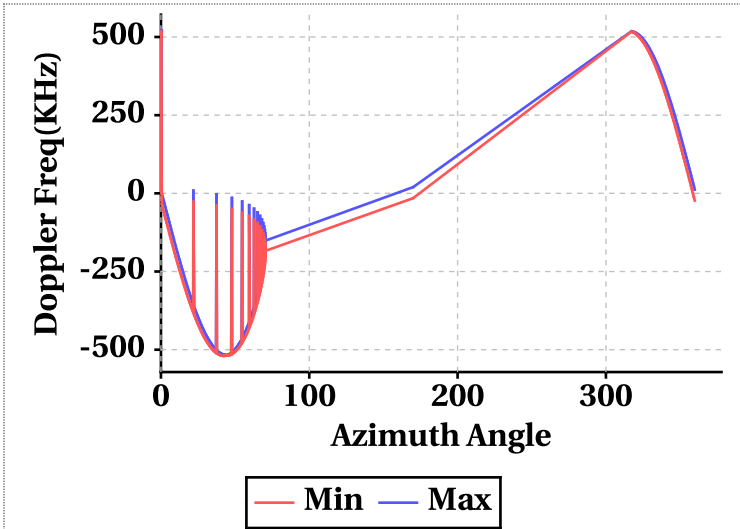
Doppler Frequency(KHz) variation

Doppler_FP	Inner Beam (HH)			Outer Beam (VV)		
	Min	Max	Mean	Min	Max	Mean
Doppler_1	0.00	38.84	27.56	-18.24	37.90	25.28
Doppler_70	0.00	463.00	461.76	-18.24	519.12	517.64
Doppler_140	-15.54	15.58	-4.59	-23.26	11.68	-10.92
Doppler_210	-463.52	5.42	-459.09	-519.32	6.22	-514.45
Doppler_280	-19.04	12.50	1.34	-15.42	19.90	7.37

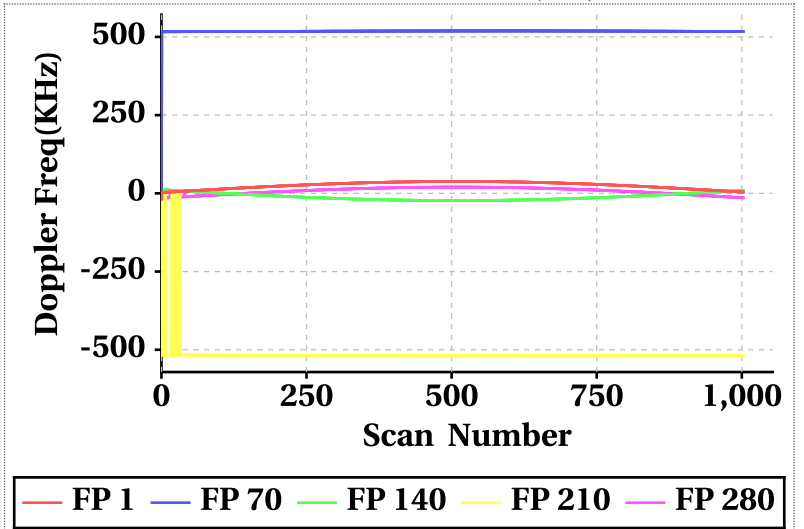
Doppler frequency variation at footprints: 1, 70, 140, 210 & 280 Inner Beam (HH)



Footprint wise Doppler frequency variation Outer Beam (VV)

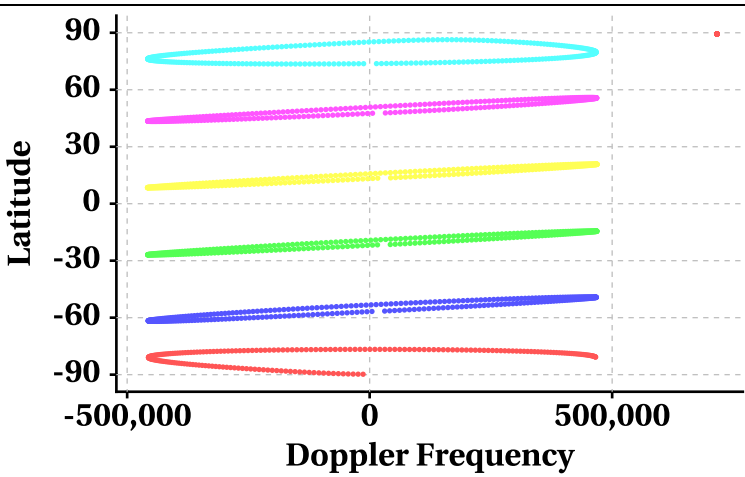


Doppler frequency variation at footprints: 1, 70, 140, 210 & 280 Outer Beam (VV)

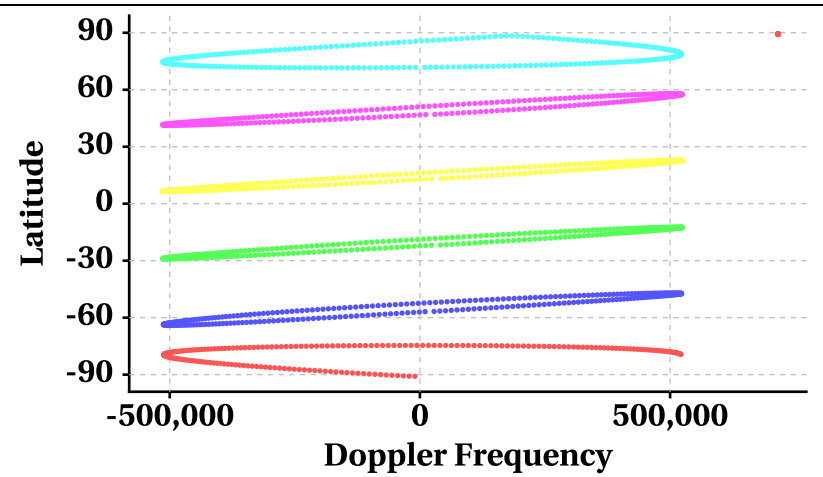


Latitude Vs Doppler Frequency

Doppler Frequency at Scan Interval of 200 [Inner Beam(HH)]



Doppler Frequency at Scan Interval of 200 [Outer Beam(VV)]



■ Scan 0
 ■ Scan 200
 ■ Scan 400
 ■ Scan 600
 ■ Scan 800
 ■ Scan 1000

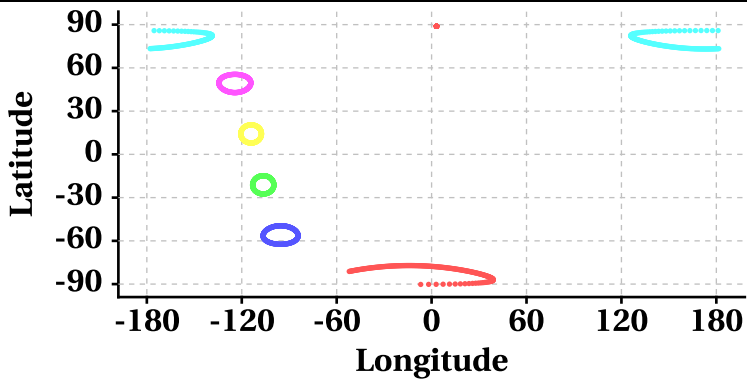
■ Scan 0
 ■ Scan 200
 ■ Scan 400
 ■ Scan 600
 ■ Scan 800
 ■ Scan 1000



Parameter as a function of Latitude

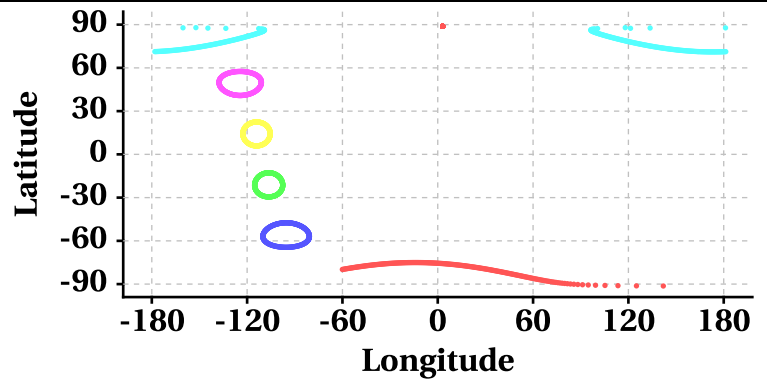
Latitude Vs Longitude

Scan Trace [Inner Beam(HH)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

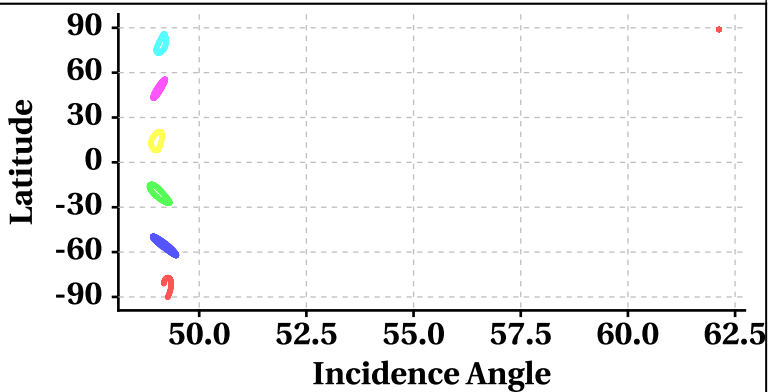
Scan Trace [Outer Beam (VV)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

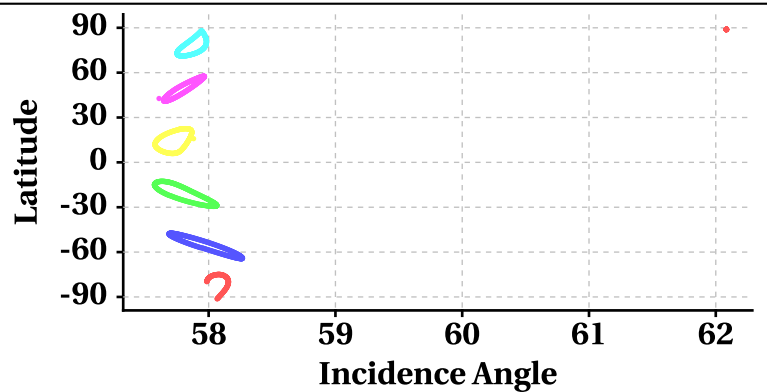
Latitude Vs Incidence Angle

Incidence Angle at Scan Interval of 200 [Inner Beam(HH)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

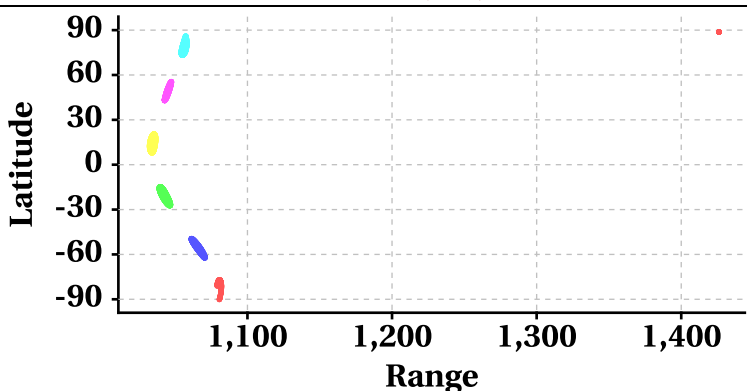
Incidence Angle at Scan Interval of 200 [Outer Beam (VV)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

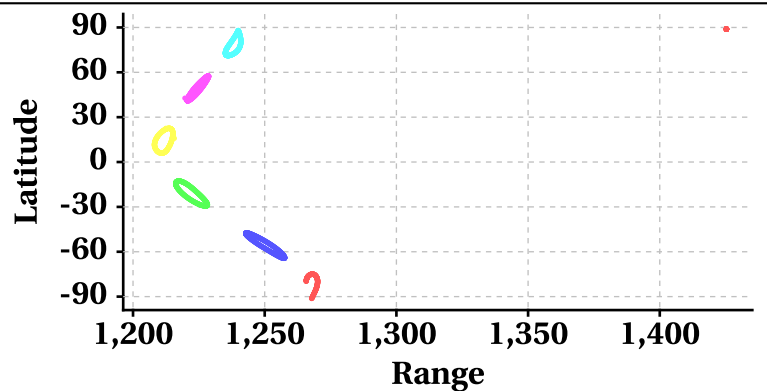
Latitude Vs Range

Range at Scan Interval of 200 [Inner Beam(HH)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

Range at Scan Interval of 200 [Outer Beam(VV)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000



Variation in Orbit and Attitude Parameters

