

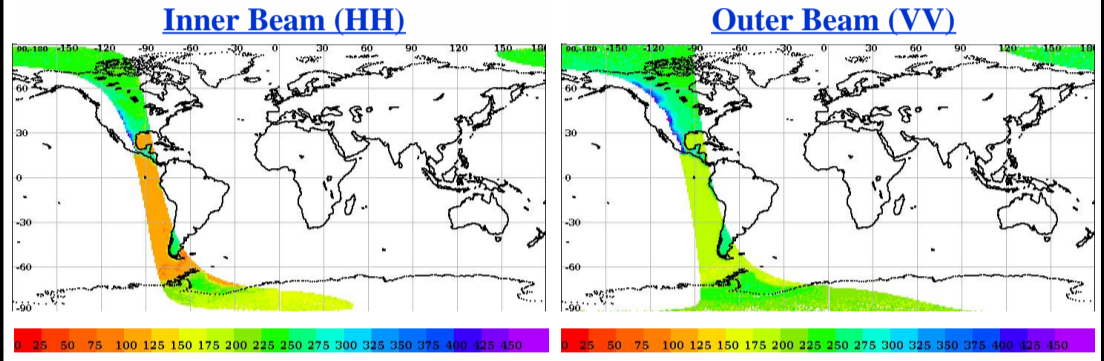
# SCATSAT-1 Scatterometer Level-1B Data Quality Evaluation Report

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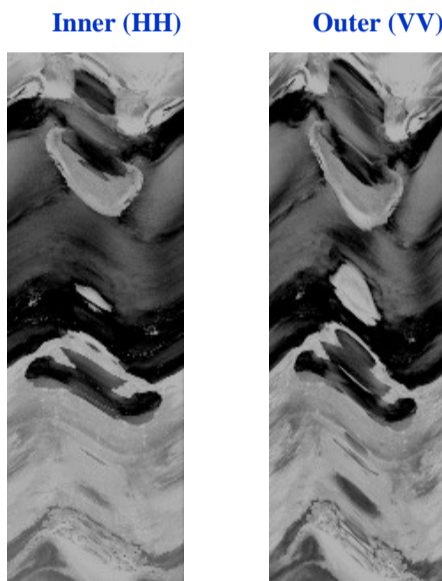
- Half-Orbit Coverage using BT & Sigma-0
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<b>Satellite Id</b>	ScatSat-1	<b>Start Orbit</b>	12888	<b>Total Scans</b>	987
<b>Sensor Name</b>	Scatterometer	<b>End Orbit</b>	12889	<b>No of Inner FootPrints</b>	281
<b>Processor Version</b>	v1.1.3	<b>Rev. Number</b>	12888_12889	<b>No Of Outer FootPrints</b>	282
<b>Half Orbit Direction</b>	SN	<b>Data Production Date</b>	04-03-2019	<b>No. Of Inner Slices</b>	9
<b>Equator Crossing Date</b>	04-03-2019	<b>Equator Crossing Time</b>	02:26:35.000	<b>No Of Outer Slices</b>	15

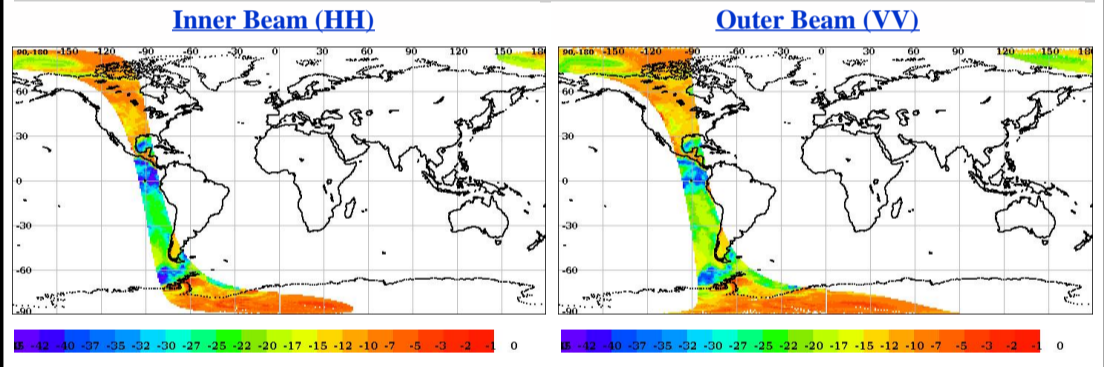
## Brightness Temperature(k) Footprint trace



## Image Snapshot for Inner & Outer Beam



## Sigma0(dB) Footprint trace



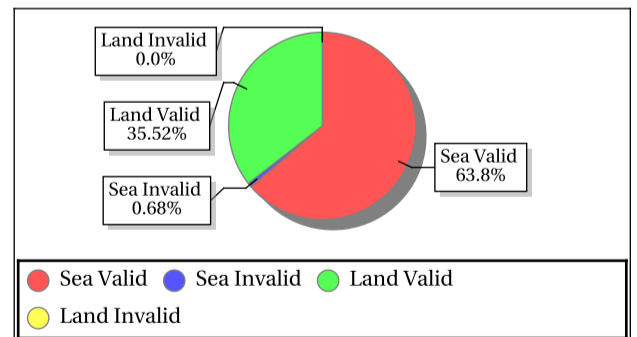
## Invalid and Poor Sigma-0 Quality Flag Statistics for Inner/Outer Slices\*

Sigma-0 Flags	Inner Beam	Outer Beam
Invalid Sigma0(%)	0.35	1.85
Data Not Available From Payload (%)	5.118289	0.968429
Slice not within sample array limits (%)	94.88	99.03
C(S+N) - C(N) < 0.1 (%)	0.00	0.00
Poor Sigma0(%)	22.71	13.66
Noise samples for blending Saturated	2.471988	2.57685
Count samp. for interpol. saturated (%)	0.00	0.00
Sigma0 < lower bound (-96dB) (%)	0.0	0.0
Sigma0 > upper bound (0 dB) (%)	0.00	0.00
SNR < -65 dB (%)	0.046738	0.084668

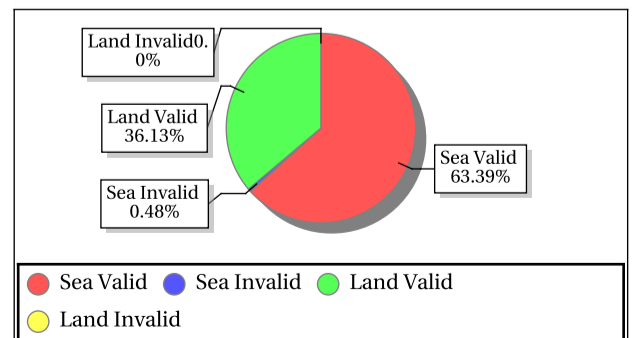
\*DP Format Document

## Sigma-0 Quality Flag Statistics for Inner/Outer Footprints

### Inner Beam (HH)



### Outer Beam (VV)



## Overall statistics for the Static Parameters (Footprint-wise)

Inner Beam (HH)																
	Sea Aft				Sea Fore				Land Aft				Land fore			
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)
<b>Kp</b>	0.12	282.44	0.55	6.650	0.12	299.98	0.48	5.652	0.12	0.13	0.12	0.000	0.12	0.15	0.12	0.000
<b>Kpa</b>	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000
<b>Kpb</b>	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000
<b>Kpc</b>	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
<b>SNR</b>	-34.64	27.83	4.36	2.113	-34.91	28.73	5.36	2.896	6.95	31.49	19.18	11.340	4.00	29.94	19.50	10.709

Outer Beam (VV)																
	Sea Aft				Sea Fore				Land Aft				Land fore			
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)
<b>Kp</b>	0.09	232.47	0.48	6.100	0.09	233.92	0.41	4.818	0.09	0.13	0.09	0.000	0.09	0.13	0.09	0.000
<b>Kpa</b>	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
<b>Kpb</b>	0.01	0.01	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
<b>Kpc</b>	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
<b>SNR</b>	-34.97	21.21	1.95	0.000	-34.99	21.59	3.09	0.000	1.62	22.74	13.35	0.026	1.93	22.95	13.32	0.030

Parameter Specifications					
Parameter	Kp	Kpa	Kpb	Kpc	SNR
Min	0.00	0.00	0.00	0.00	-65.00
Max	1.00	1.00	1.00	1.00	22.00

- Normal
- Deviations
- Alarming
- High Errors

## Overall statistics for static parameter (Footprint-wise)

	Inner Beam (HH)				Outer Beam (VV)				Parameter Specifications		
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Parameter	Min	Max
<b>Incidence Angle (deg)</b>	48.67	49.43	49.03	0.000	57.42	58.29	57.85	0.000	Inci.(Inner)	47.10	49.90
<b>Azimuth Diff. (deg)</b>	0.0000	88.14	1.27	2.502	0.0000	293.76	1.28	3.189	Inci.(Outer)	57.30	58.90
<b>Range(Km)</b>	1015.53	1084.54	1040.82	28.687	1190.07	1274.26	1219.89	44.594	Azimuth Diff.	0.60	2.00
<b>X Factor(dbm)</b>	-91.64	-89.69	-90.31	0.000	-94.93	-91.75	-92.15	0.000	Range(Inner)	1025.00	1095.70
<b>Across Distance (Km)</b>	15.39	15.93	15.64	0.000	20.30	42.80	20.91	9.000	Range(Outer)	1210.00	1280.00
<b>Along Distance (Km)</b>	18.61	11347.85	305.95	27.000	18.56	11879.23	456.07	39.000	X-Factor	-100.00	-80.00
									Ac.Distance(Inner)	15.00	20.00
									Ac.Distance(Outer)	15.00	22.00
									Al.Distance(Inner)	15.00	30.00
									Al.Distance(Outer)	10.00	30.00

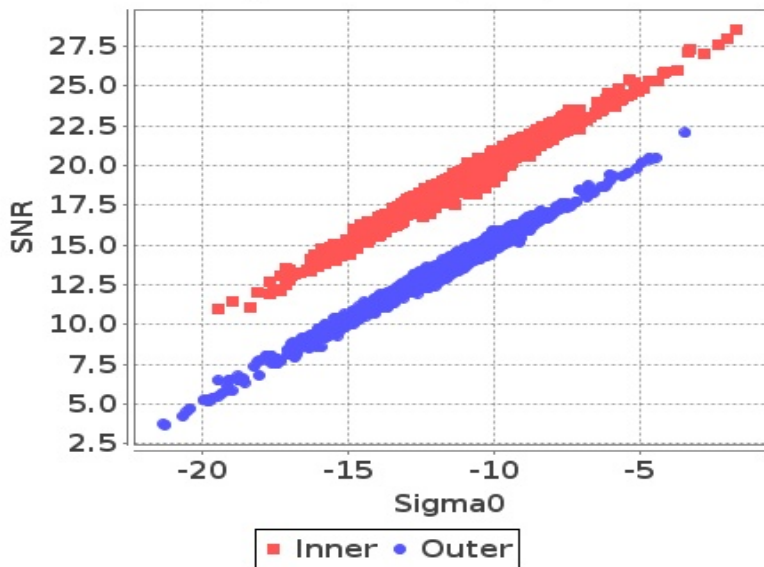
- Normal
- Deviations
- Alarming
- High Errors



## Sigma0 Behaviour (Sigma0 Vs SNR)

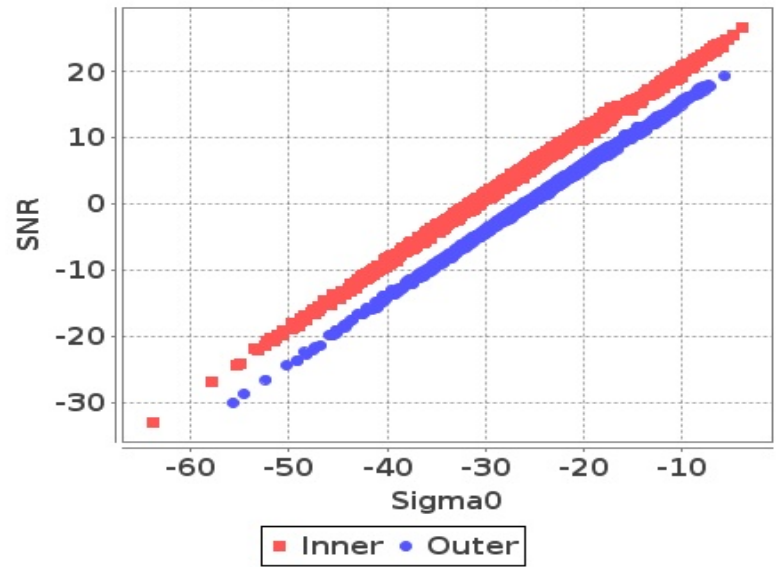
Footprint-Land

Sigma0 Vs SNR (Land)



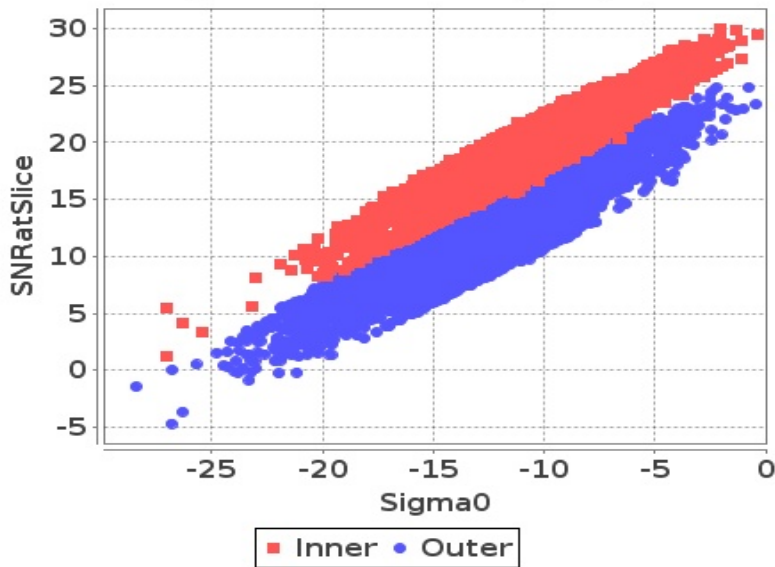
Footprint-Sea

Sigma0 Vs SNR (Sea)



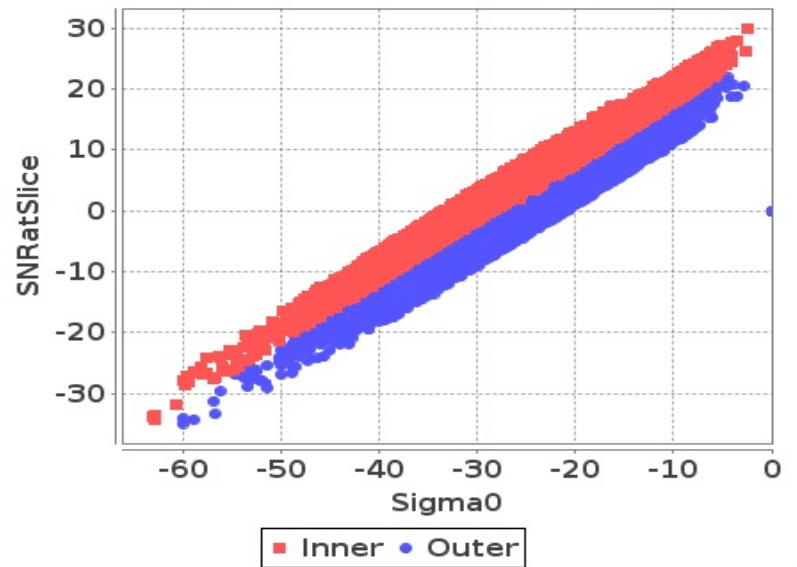
Slice-Land

Sigma0 Vs SNRatSlice (Land)



Slice-Sea

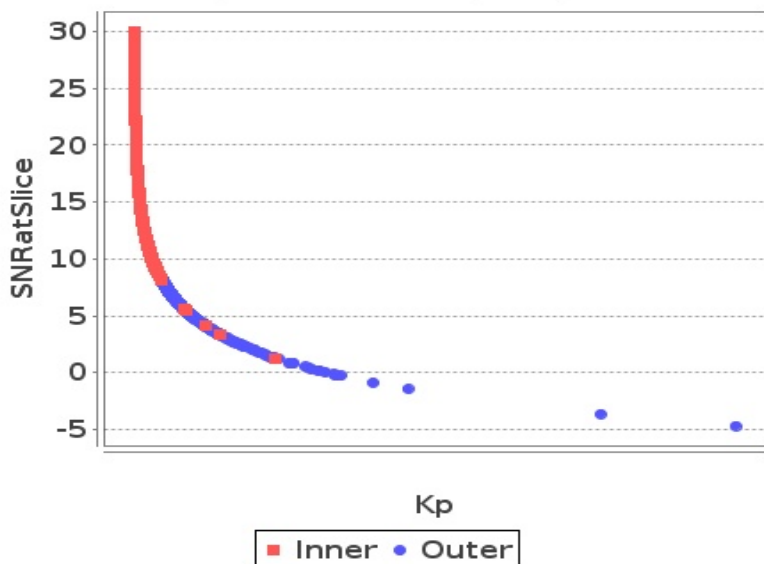
Sigma0 Vs SNRatSlice (Sea)



## Sigma0 Behaviour (Kp Vs SNR)

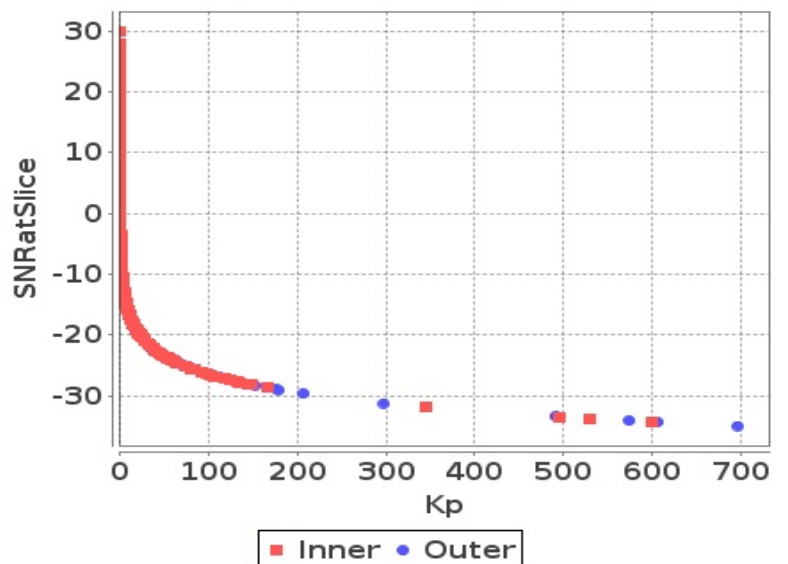
Slice

Kp Vs SNRatSlice (Land)



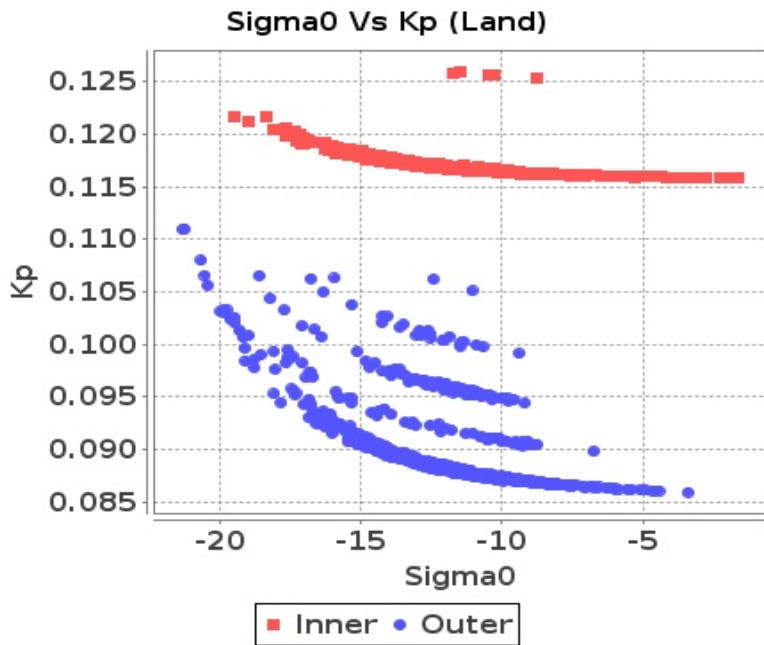
Slice

Kp Vs SNRatSlice (Sea)

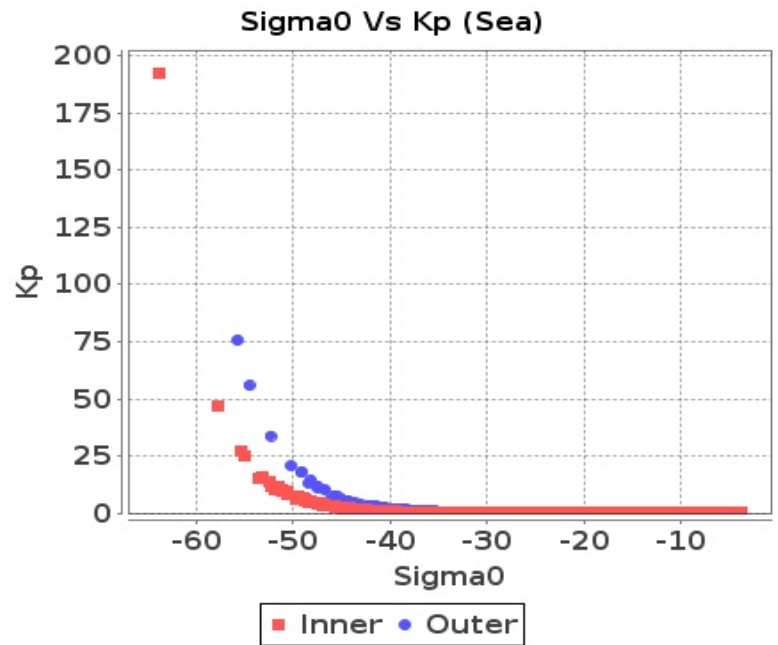


# Sigma0 Behaviour(Sigma0 Vs Kp)

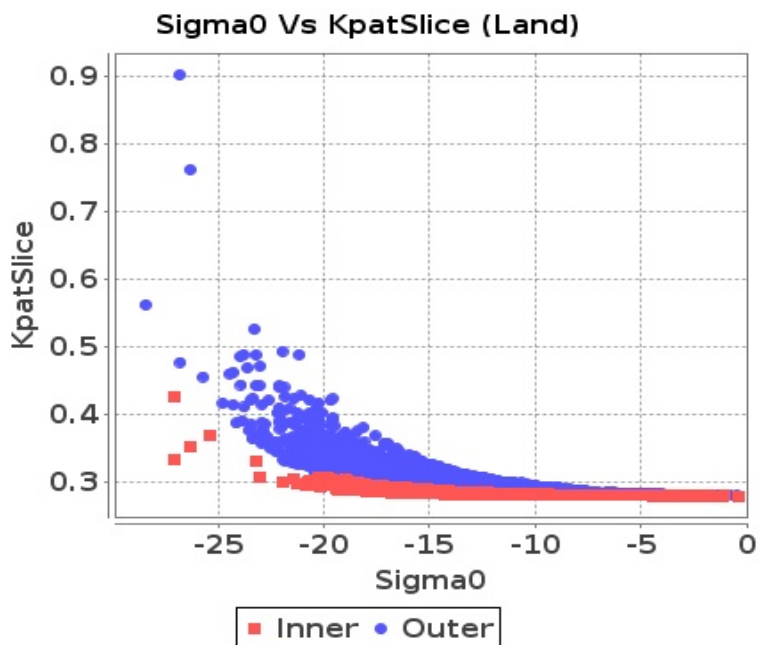
## Footprint-Land



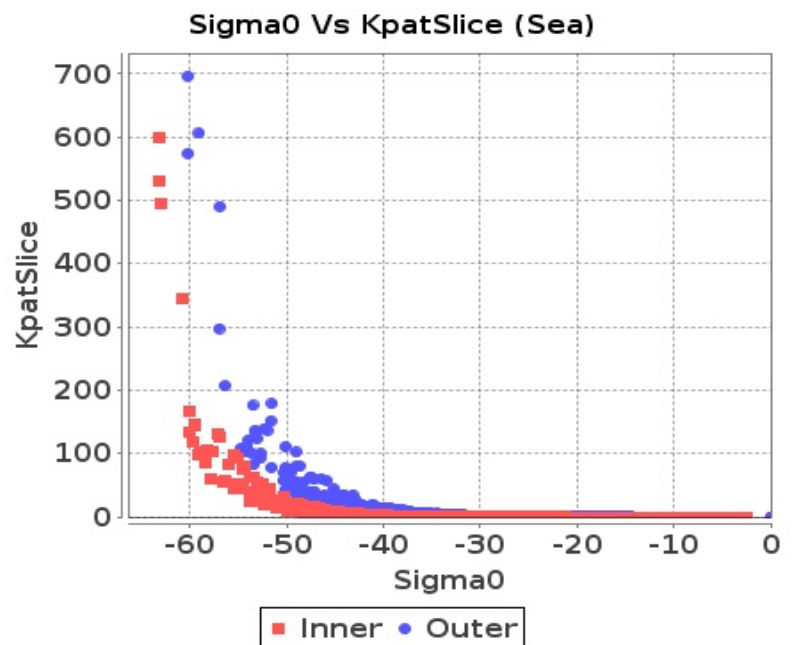
## Footprint-Sea



## Slice-Land



## Slice-Sea

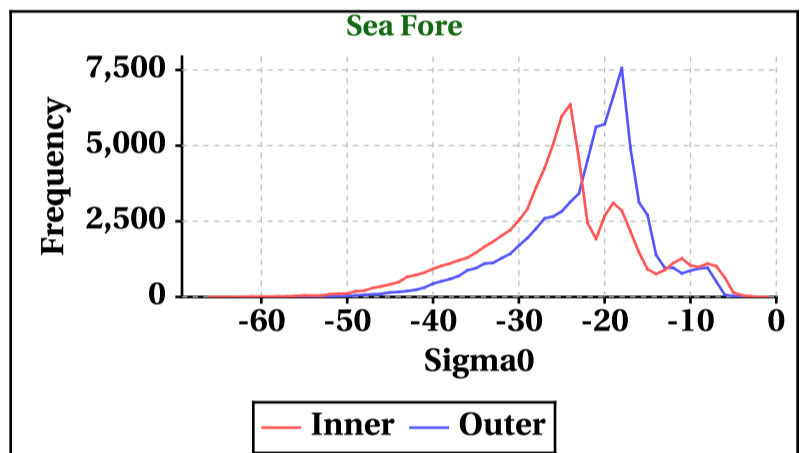
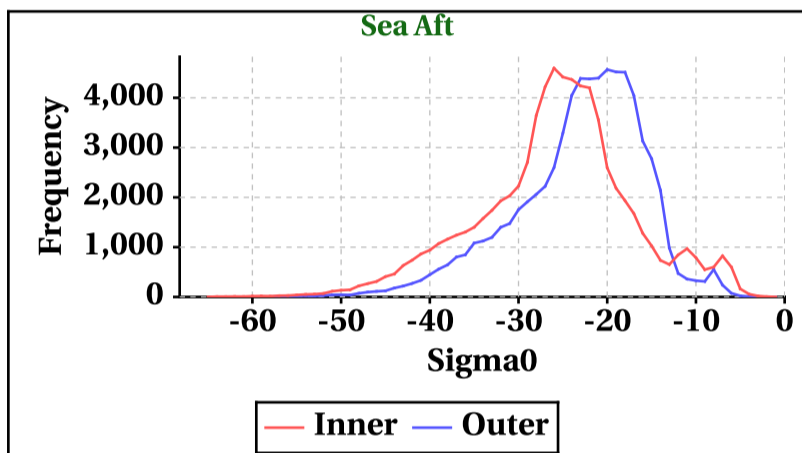
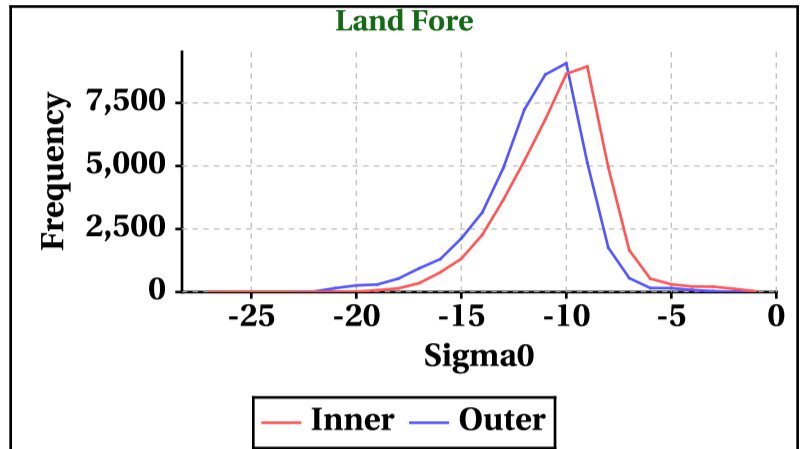
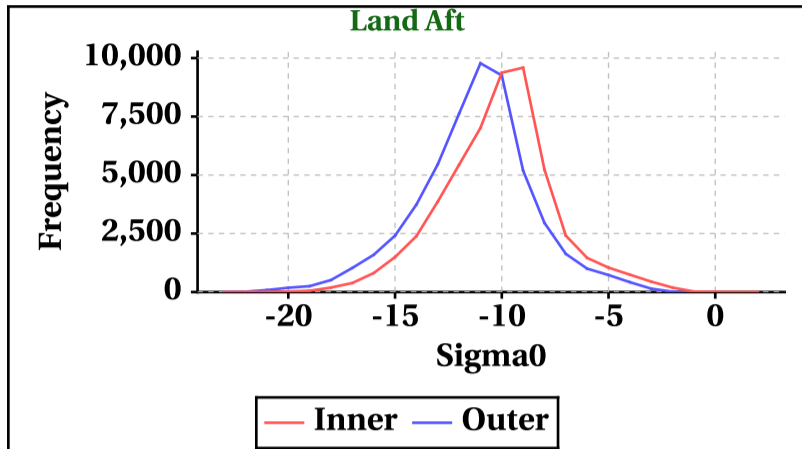


# Dynamic Range (Data Histograms)

## Sigma0(db)

Inner Beam (HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-23	-27	-65	-66
Max	2	0	0	0

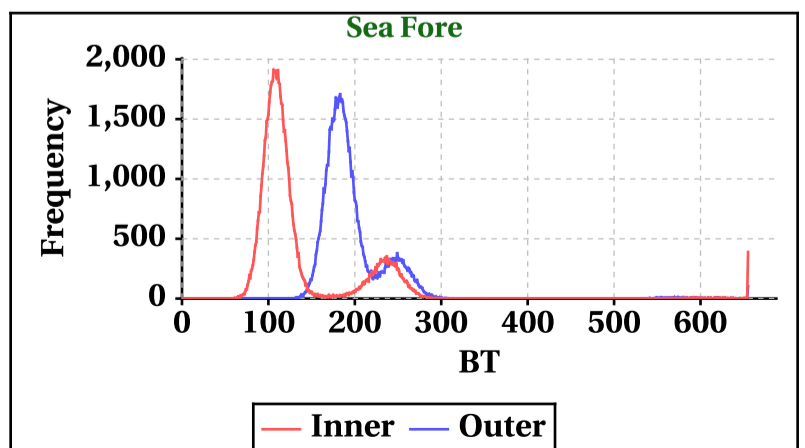
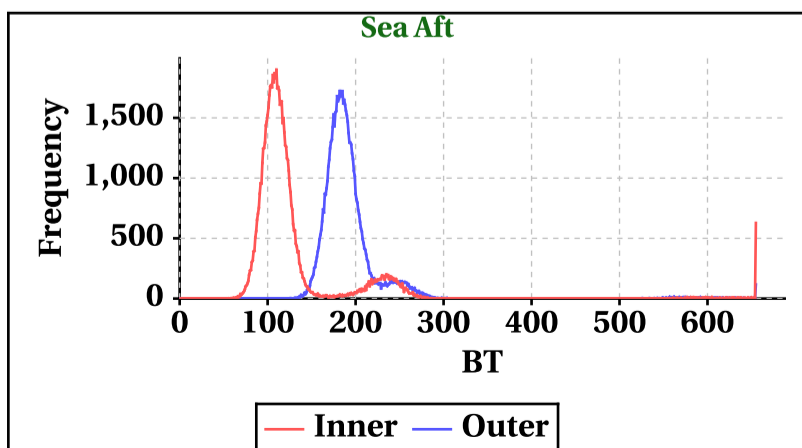
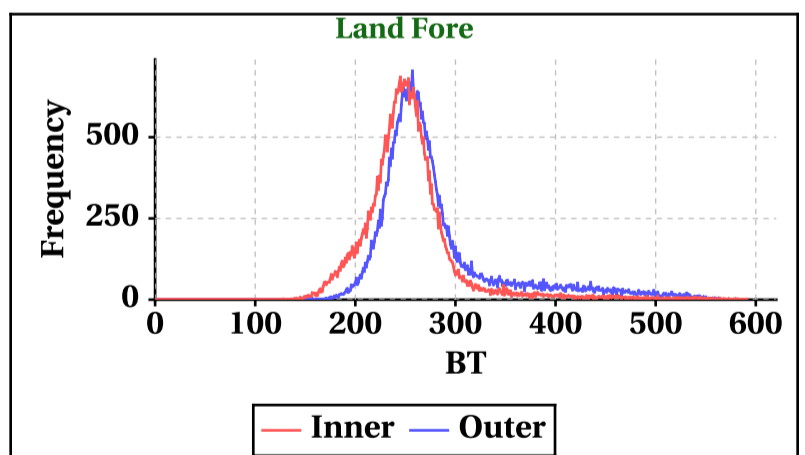
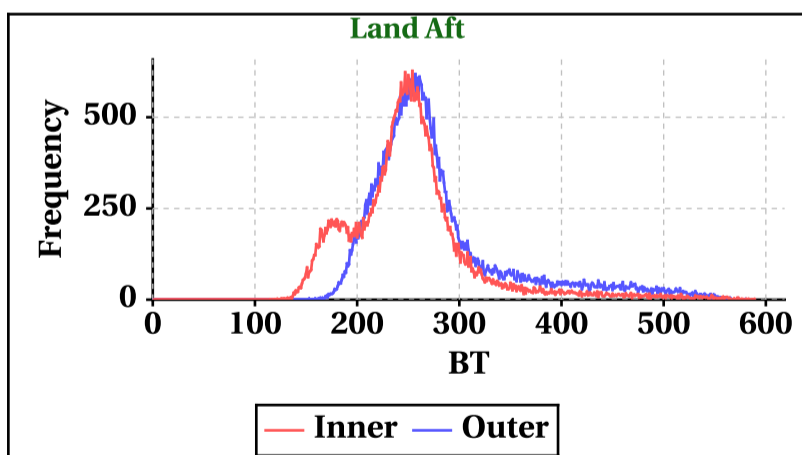
Outer Beam (VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-23	-23	-60	-60
Max	0	0	0	0



## Brightness Temperature(K)

Inner Beam(HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	0	0
Max	589	591	655	655

Outer Beam(VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	0	0
Max	580	570	655	655

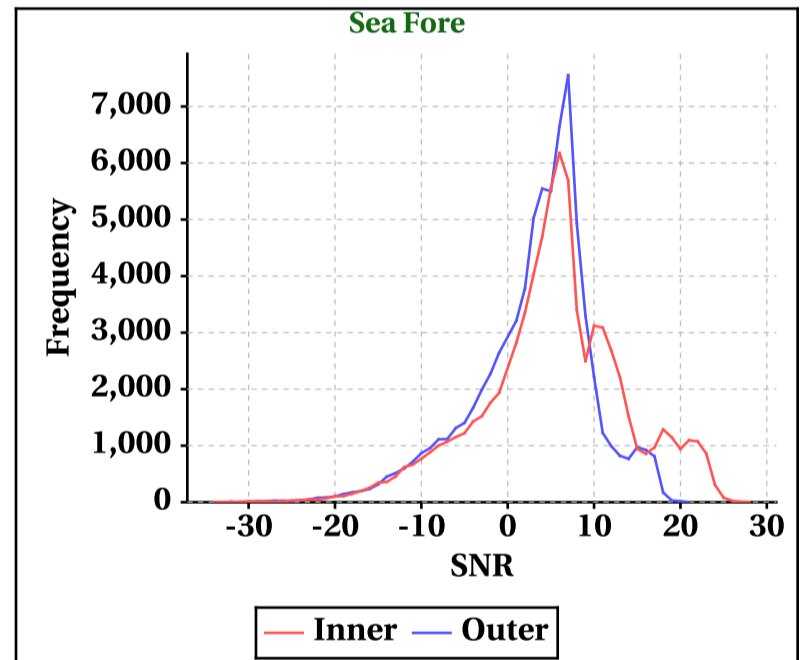
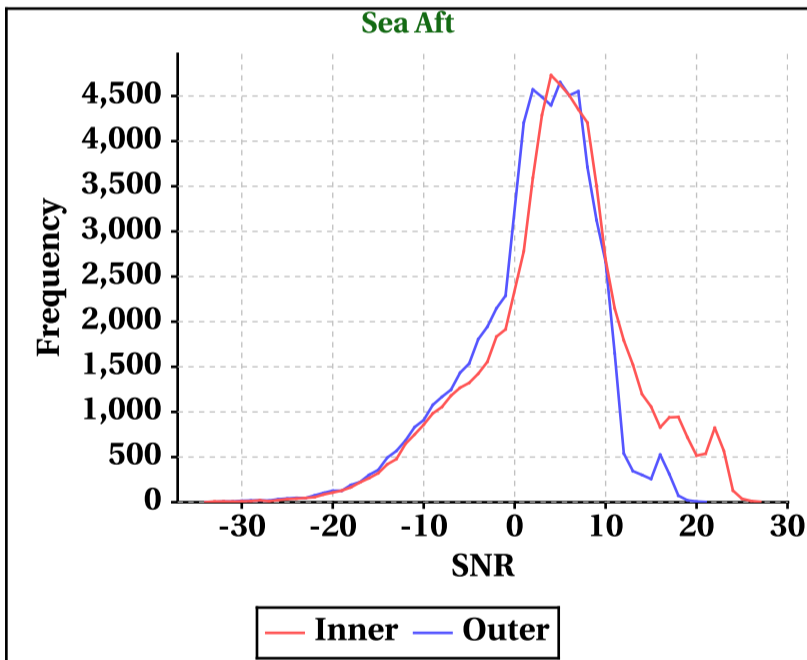
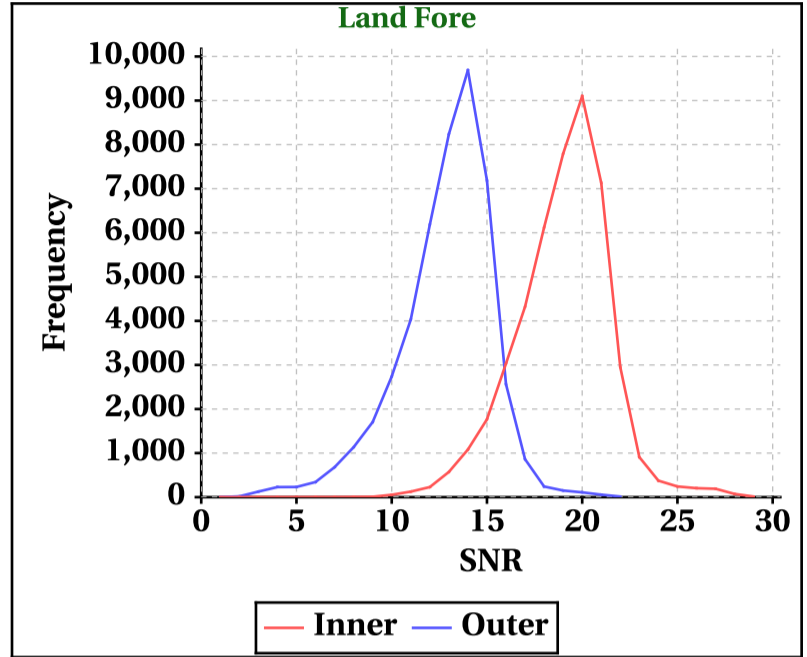
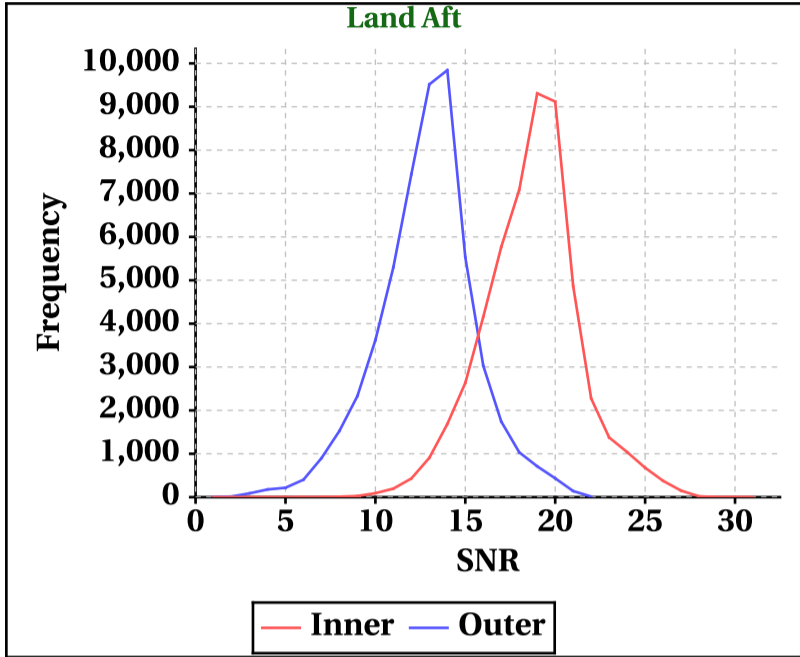


# Dynamic Range (Data Histograms)

## SNR(dBm)

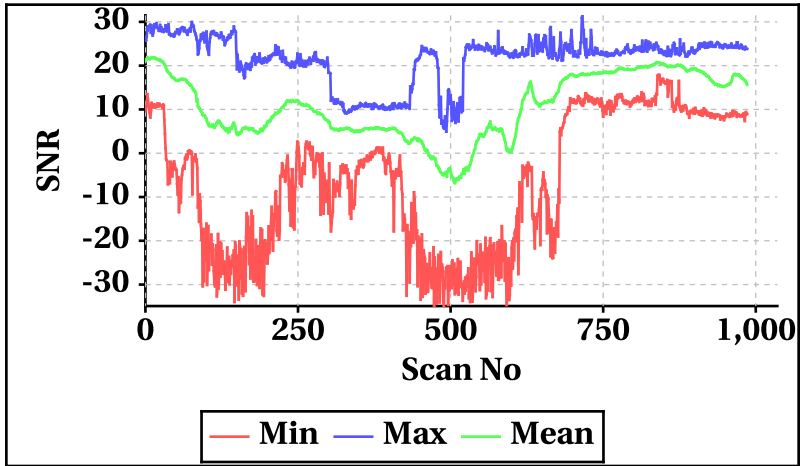
Inner Beam (HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	-34	-34
Max	31	29	27	28

Outer Beam (VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	-34	-34
Max	22	22	21	21

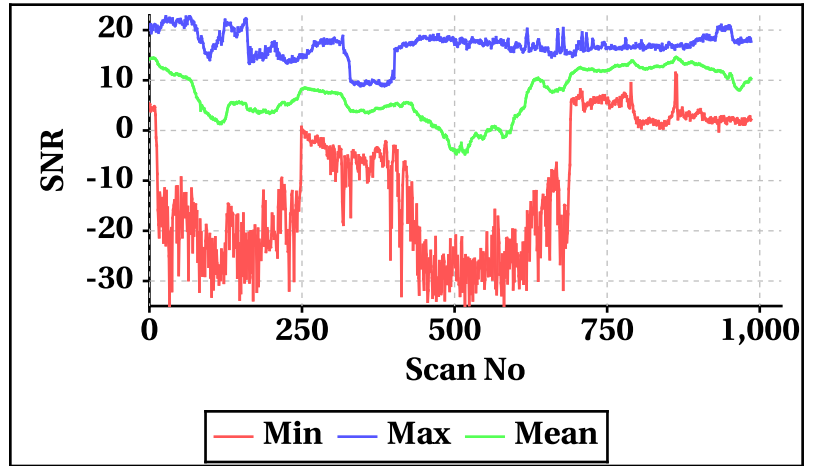


## Orbit-wise behaviour of SNR

Inner Beam (HH)

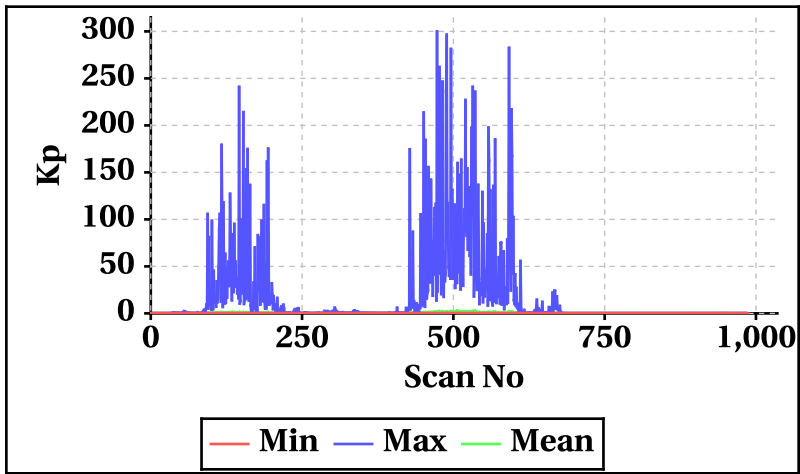


Outer Beam(VV)

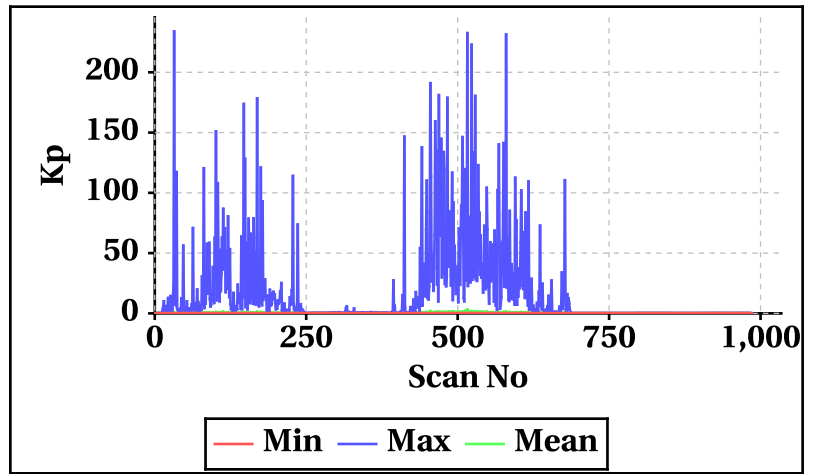


## Orbit-wise behaviour of Kp,Kpa,Kpb,Kpc

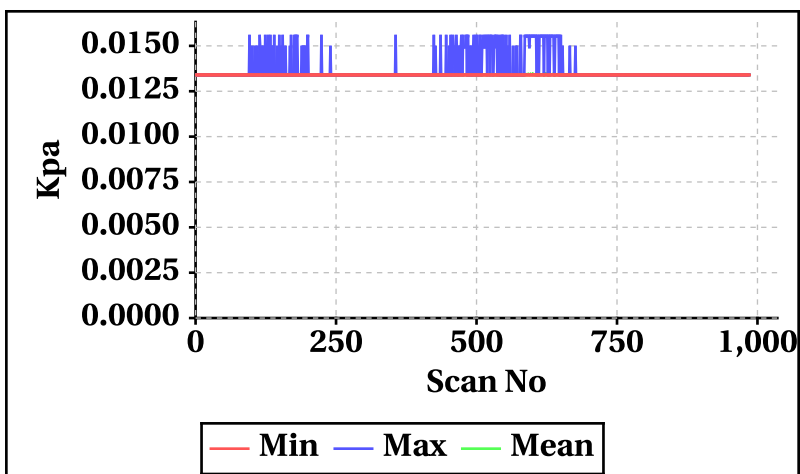
Inner Beam(HH)



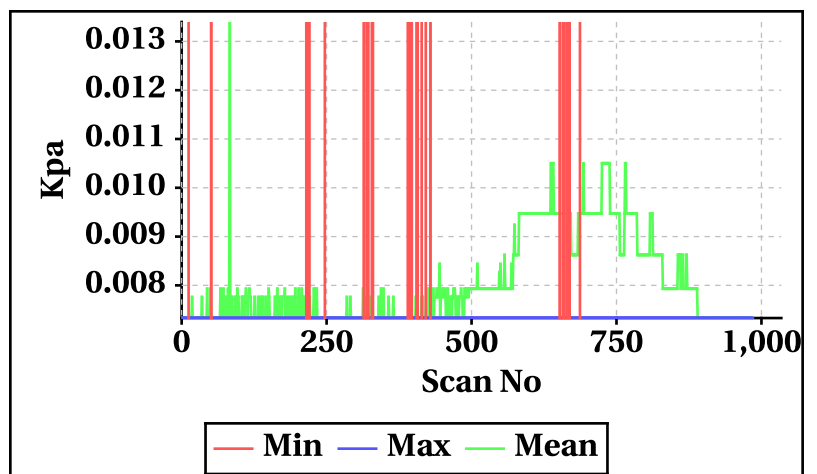
Outer Beam(VV)



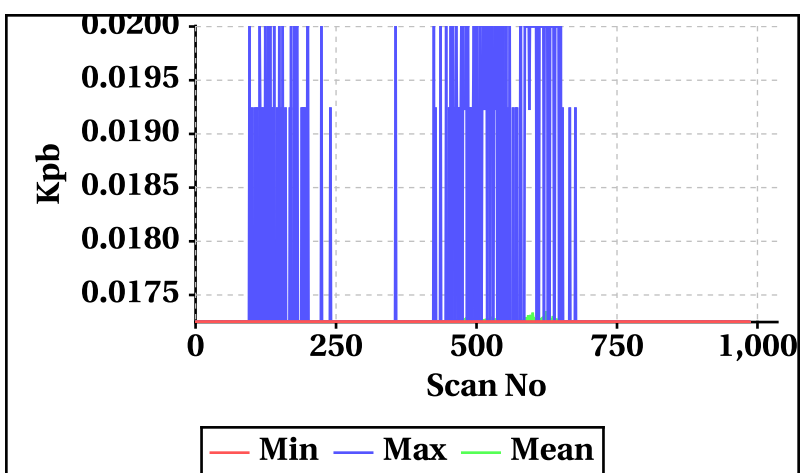
Inner Beam(HH)



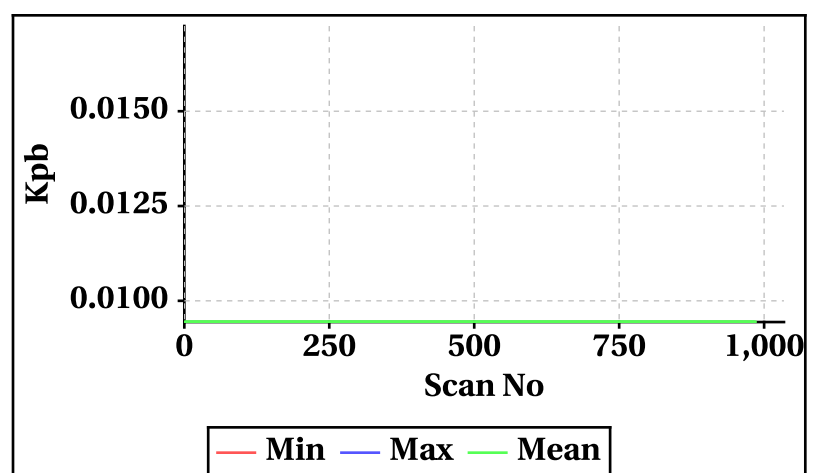
Outer Beam(VV)



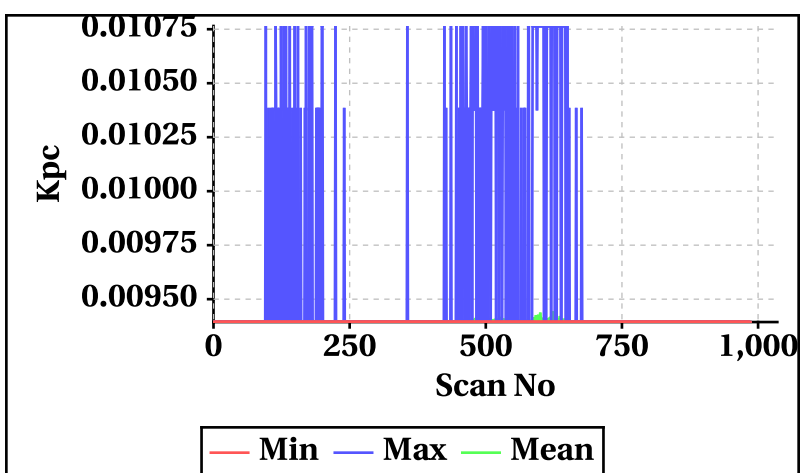
Inner Beam(HH)



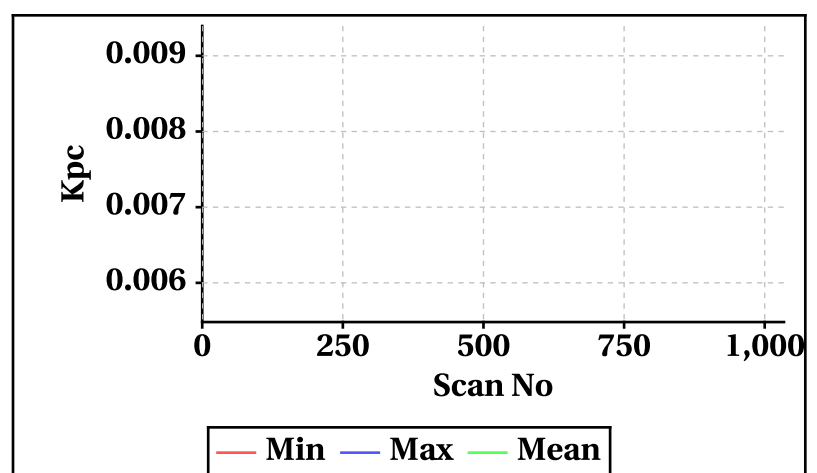
Outer Beam(VV)



Inner Beam(HH)

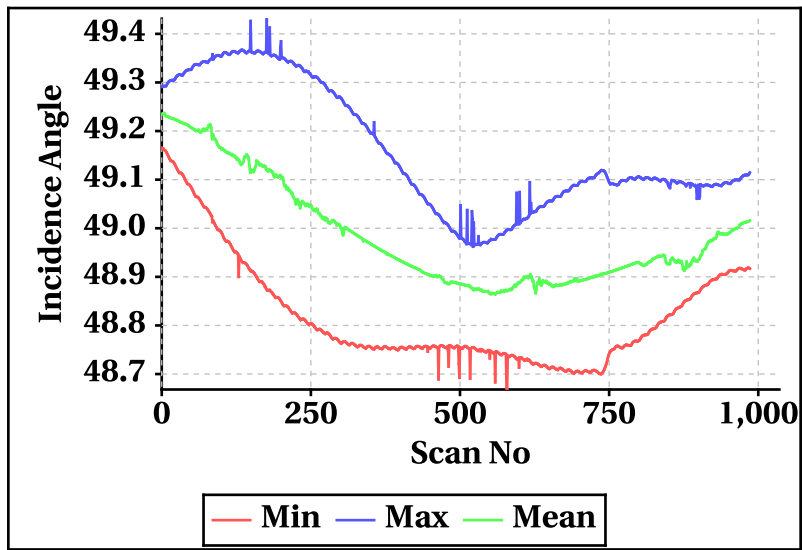


Outer Beam(VV)

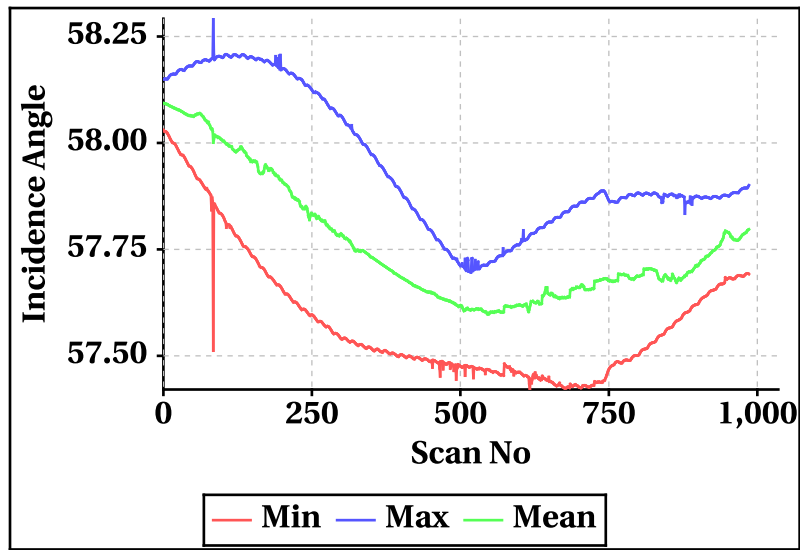


Orbit-wise behaviour of Incidence,Azimuth,Range,X-Factor

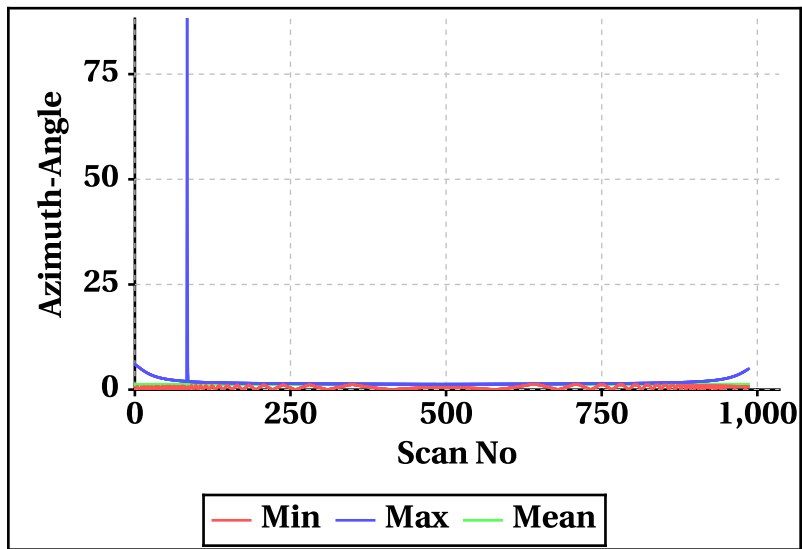
Inner Beam (HH)



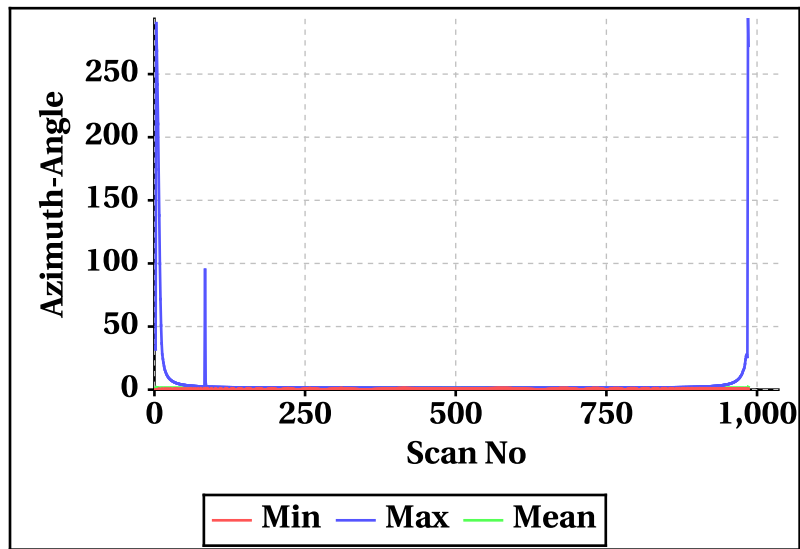
Outer Beam(VV)



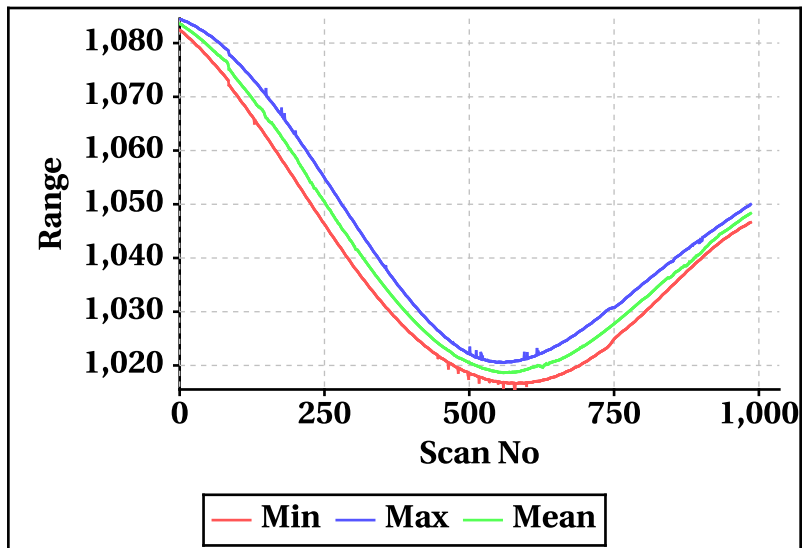
Inner Beam (HH)



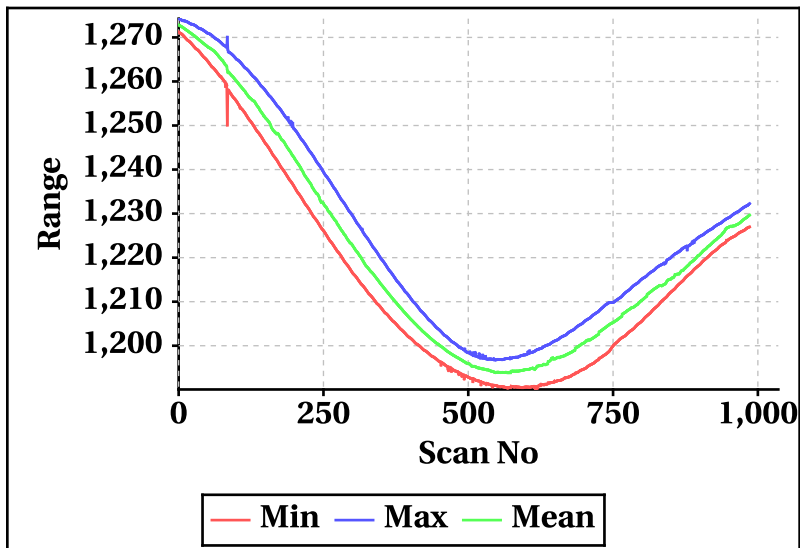
Outer Beam(VV)



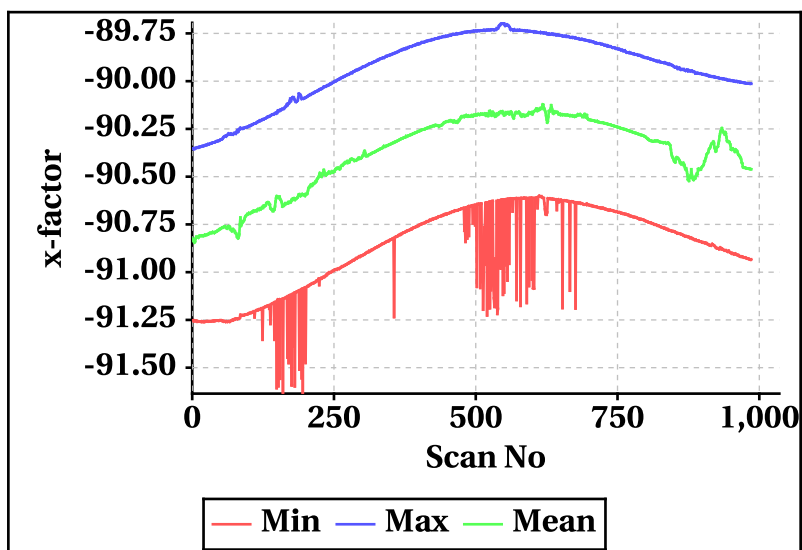
Inner Beam (HH)



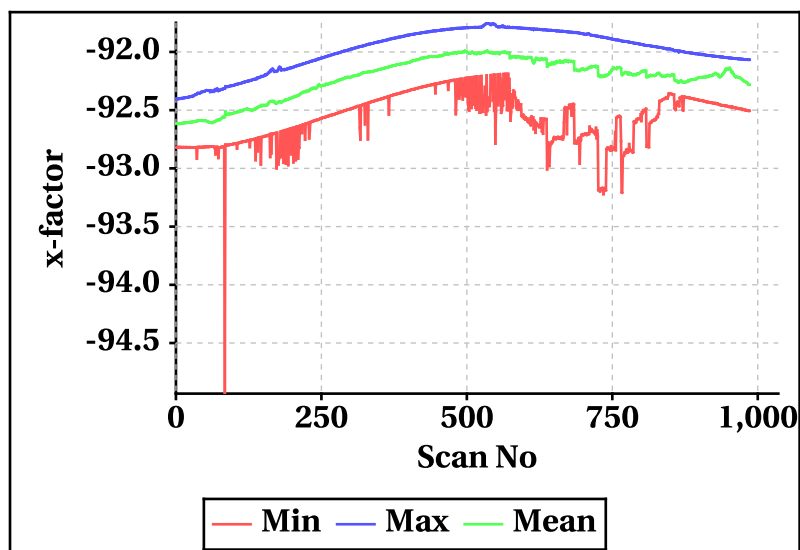
Outer Beam(VV)



Inner Beam (HH)



Outer Beam(VV)



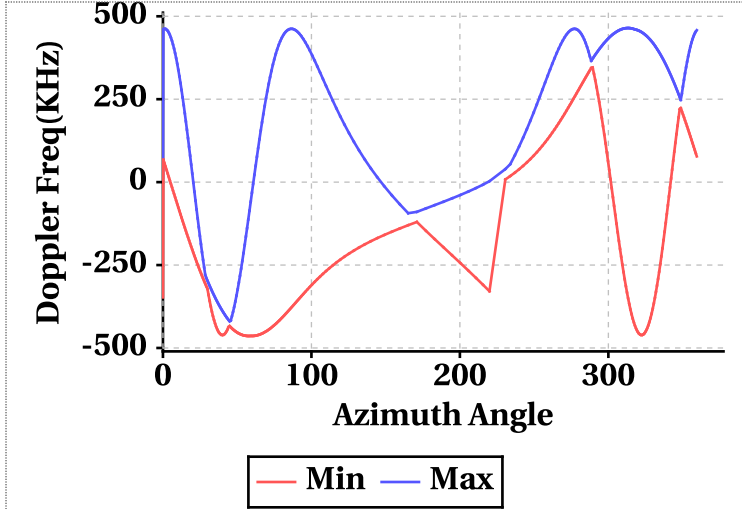


# Doppler Frequency Variation

Doppler Frequency(KHz) variation statistics Over the half Orbit

	Inner Beam (HH)	Outer Beam (VV)
Min	-463.84	-519.90
Max	464.50	520.46

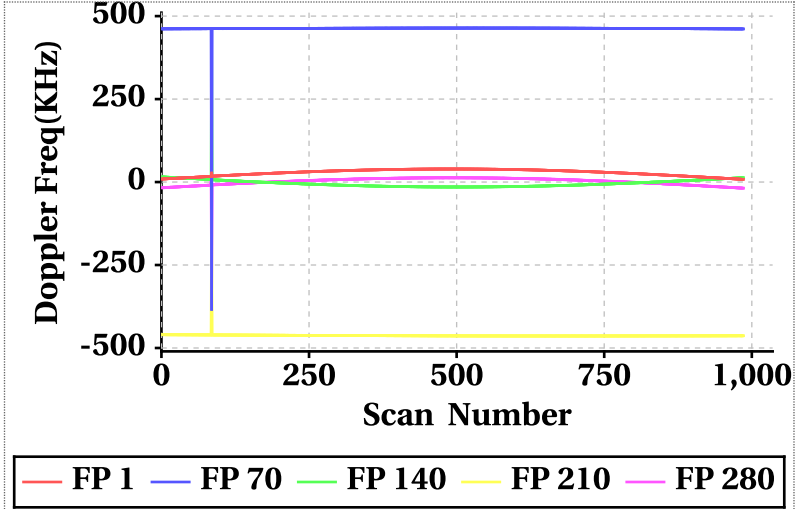
Footprint wise Doppler frequency variation Inner Beam (HH)



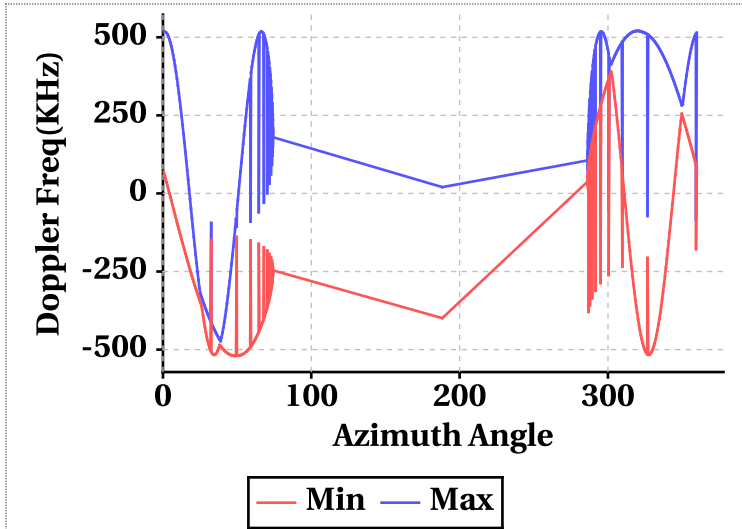
Doppler Frequency(KHz) variation

Doppler_FP	Inner Beam (HH)			Outer Beam (VV)		
	Min	Max	Mean	Min	Max	Mean
Doppler_1	8.08	39.32	28.23	3.66	38.32	25.94
Doppler_70	-383.48	463.98	462.17	-421.32	520.14	518.03
Doppler_140	-14.96	426.34	-3.91	-22.74	471.50	-10.30
Doppler_210	-463.82	-86.20	-462.39	-519.74	-81.66	-518.23
Doppler_280	-347.38	12.94	1.46	-399.34	20.28	7.44

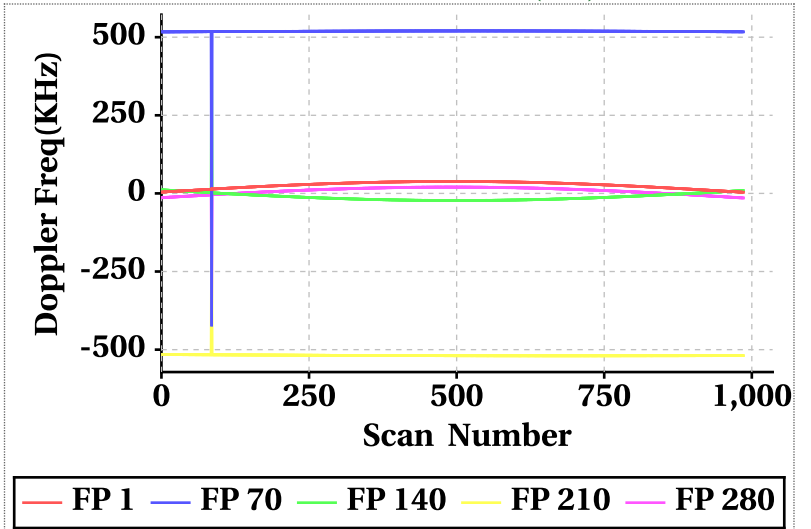
Doppler frequency variation at footprints: 1, 70, 140, 210 & 280 Inner Beam (HH)



Footprint wise Doppler frequency variation Outer Beam (VV)

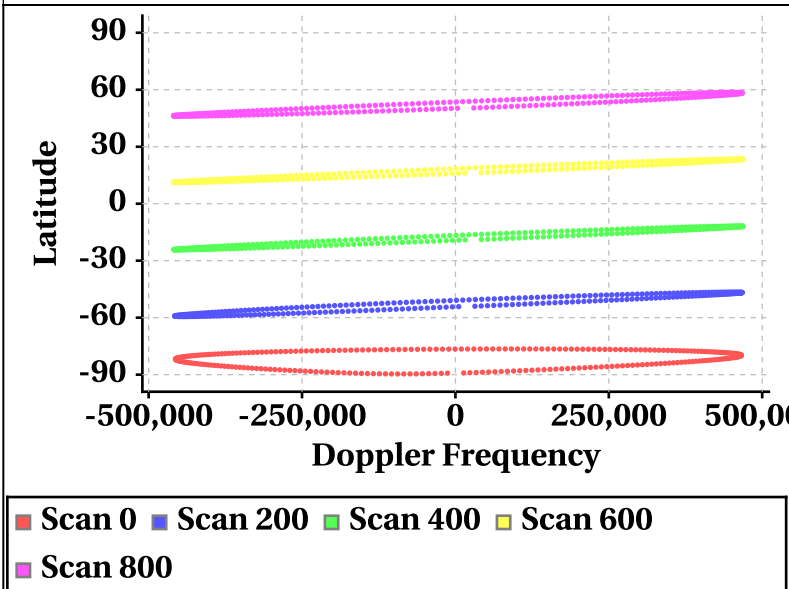


Doppler frequency variation at footprints: 1, 70, 140, 210 & 280 Outer Beam (VV)

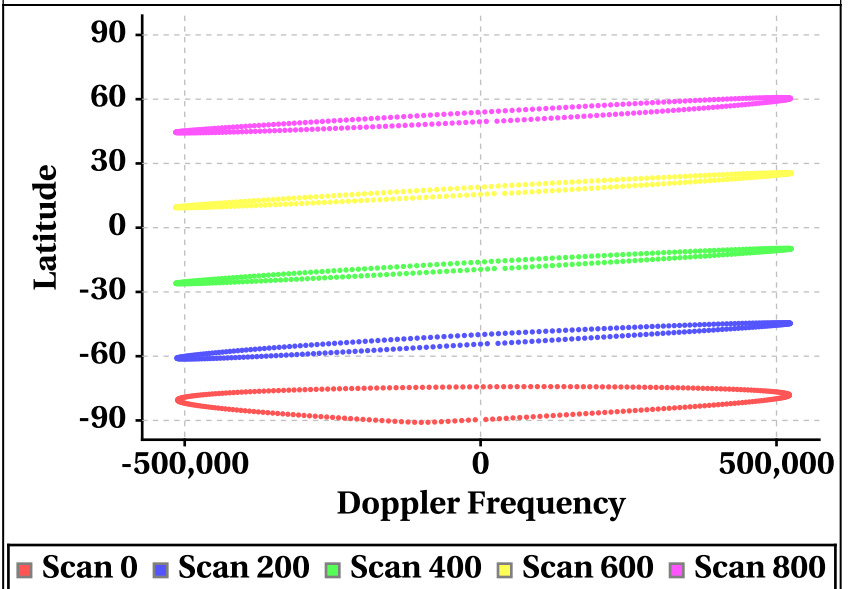


# Latitude Vs Doppler Frequency

Doppler Frequency at Scan Interval of 200 [Inner Beam(HH)]



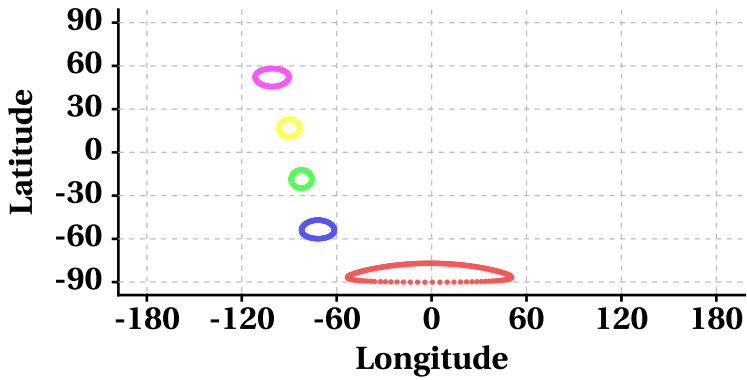
Doppler Frequency at Scan Interval of 200 [Outer Beam(VV)]



# Parameter as a function of Latitude

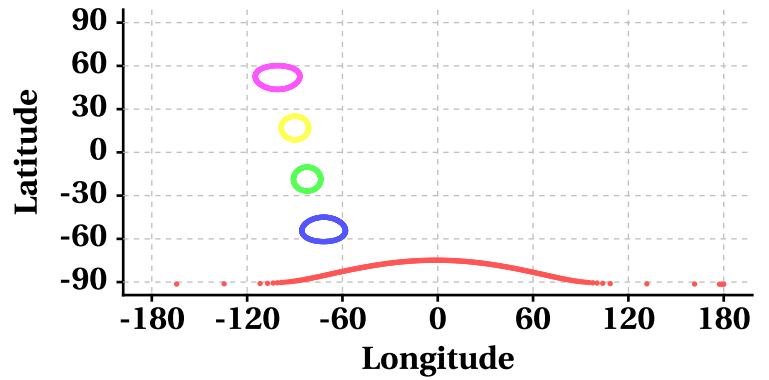
## Latitude Vs Longitude

Scan Trace [Inner Beam(HH)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800

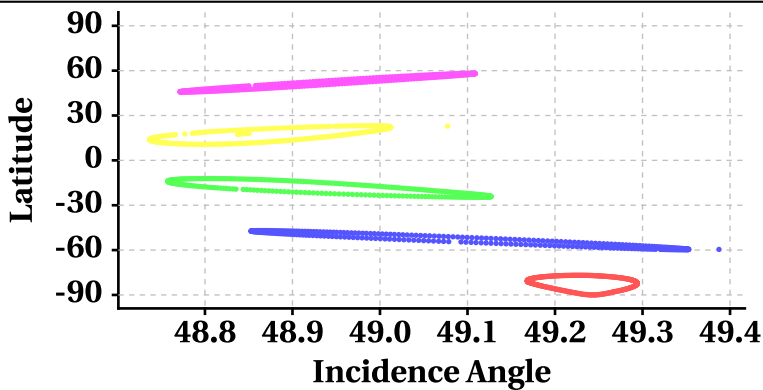
Scan Trace [Outer Beam (VV)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800

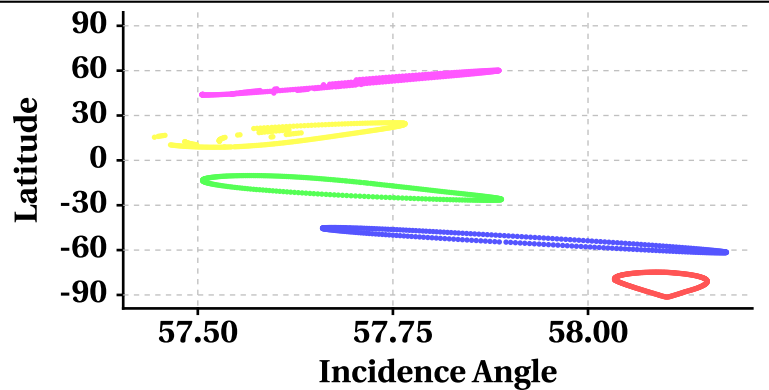
## Latitude Vs Incidence Angle

Incidence Angle at Scan Interval of 200 [Inner Beam(HH)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800

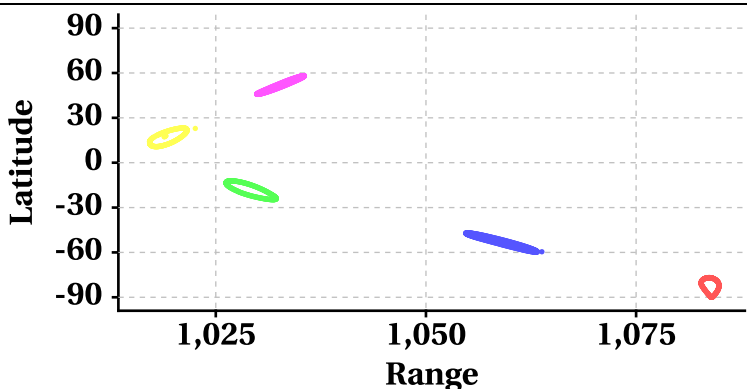
Incidence Angle at Scan Interval of 200 [Outer Beam (VV)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800

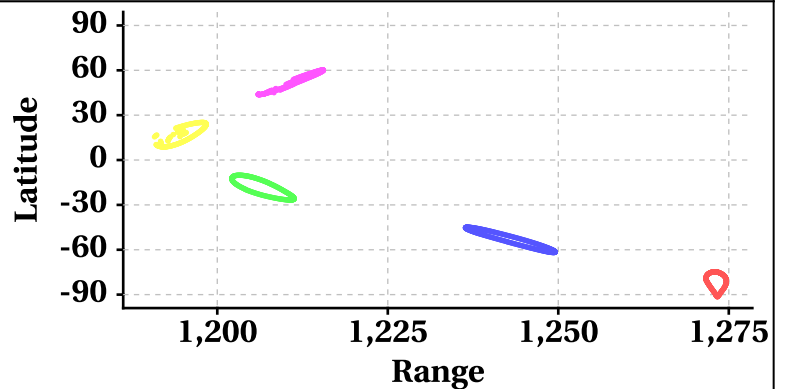
## Latitude Vs Range

Range at Scan Interval of 200 [Inner Beam(HH)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800

Range at Scan Interval of 200 [Outer Beam(VV)]



Scan 0 Scan 200 Scan 400 Scan 600  
Scan 800



# Variation in Orbit and Attitude Parameters

