

SCATSAT-1 Scatterometer Level-1B Data Quality Evaluation Report

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Satellite Id	ScatSat-1	Start Orbit	13962	Total Scans	1016
Sensor Name	Scatterometer	End Orbit	13963	No of Inner FootPrints	281
Processor Version	v1.1.3	Rev. Number	13962_13963	No Of Outer FootPrints	282
Half Orbit Direction	NS	Data Production Date	17-05-2019	No. Of Inner Slices	9
Equator Crossing Date	17-05-2019	Equator Crossing Time	03:13:42.000	No Of Outer Slices	15

Brightness Temperature(k) Footprint trace

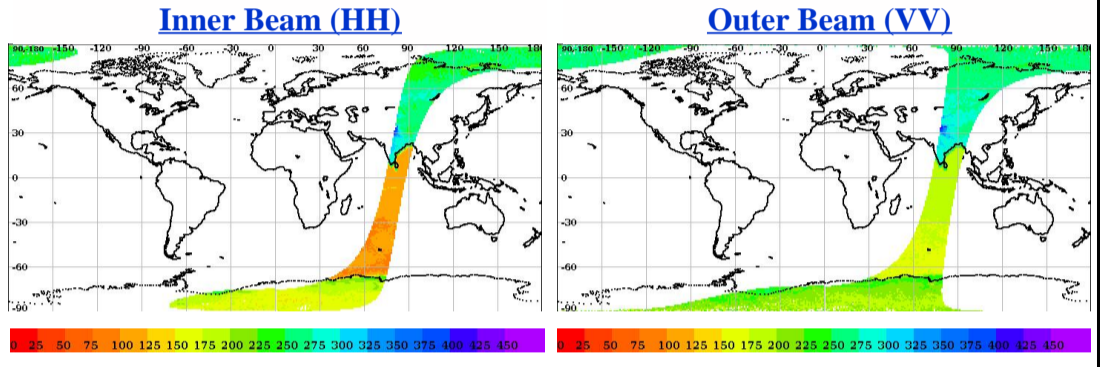
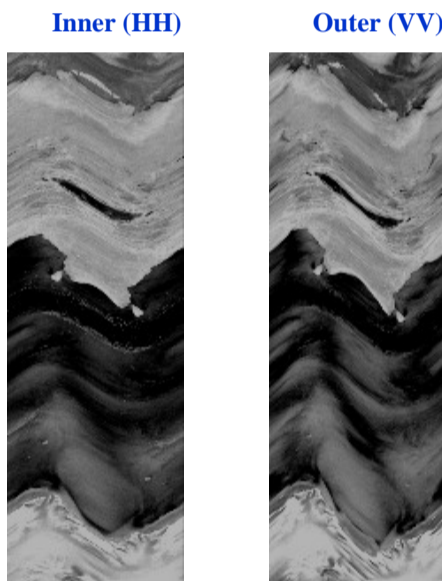
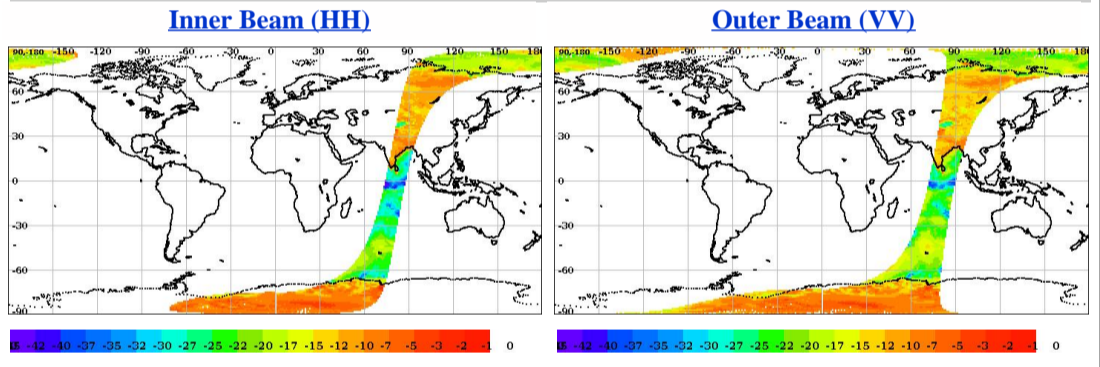


Image Snapshot for Inner & Outer Beam



Sigma0(dB) Footprint trace



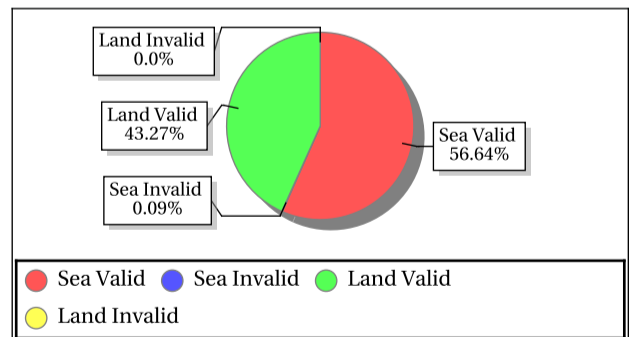
Invalid and Poor Sigma-0 Quality Flag Statistics for Inner/Outer Slices*

Sigma-0 Flags	Inner Beam	Outer Beam
Invalid Sigma0(%)	0.06	0.29
Data Not Available From Payload (%)	78.20774	15.29137
Slice not within sample array limits (%)	21.79	84.71
C(S+N) - C(N) < 0.1 (%)	0.00	0.00
Poor Sigma0(%)	22.25	13.37
Noise samples for blending Saturated	0.199045	0.323999
Count samp. for interpol. saturated (%)	0.00	0.00
Sigma0<lower bound (-96dB) (%)	0.0	0.0
Sigma0>upper bound (0 dB) (%)	0.00	0.00
SNR <-65 dB (%)	0.017491	0.047852

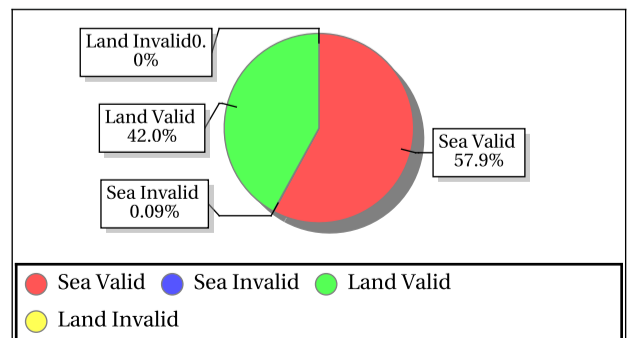
*DP Format Document

Sigma-0 Quality Flag Statistics for Inner/Outer Footprints

Inner Beam (HH)



Outer Beam (VV)



Overall statistics for the Static Parameters (Footprint-wise)

Inner Beam (HH)																
	Sea Aft				Sea Fore				Land Aft				Land fore			
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)
Kp	0.12	281.49	0.25	1.827	0.12	288.33	0.23	1.384	0.12	0.93	0.12	0.000	0.12	0.44	0.12	0.000
Kpa	0.01	0.02	0.01	0.000	0.01	0.02	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.02	0.01	0.000
Kpb	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000	0.02	0.02	0.02	0.000
Kpc	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
SNR	-34.63	24.83	5.74	0.008	-34.73	25.04	6.61	0.005	-9.36	29.80	18.97	12.071	-5.57	30.44	19.93	22.715

Outer Beam (VV)																
	Sea Aft				Sea Fore				Land Aft				Land fore			
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)
Kp	0.09	205.14	0.24	1.952	0.09	162.76	0.22	1.854	0.09	0.95	0.09	0.000	0.09	4.83	0.09	0.041
Kpa	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
Kpb	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
Kpc	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000	0.01	0.01	0.01	0.000
SNR	-34.42	16.90	3.82	0.000	-33.42	16.43	3.75	0.000	-10.77	22.83	13.01	0.030	-18.08	23.72	13.79	0.145

Parameter Specifications					
Parameter	Kp	Kpa	Kpb	Kpc	SNR
Min	0.00	0.00	0.00	0.00	-65.00
Max	1.00	1.00	1.00	1.00	22.00

- Normal
- Deviations
- Alarming
- High Errors

Overall statistics for static parameter (Footprint-wise)

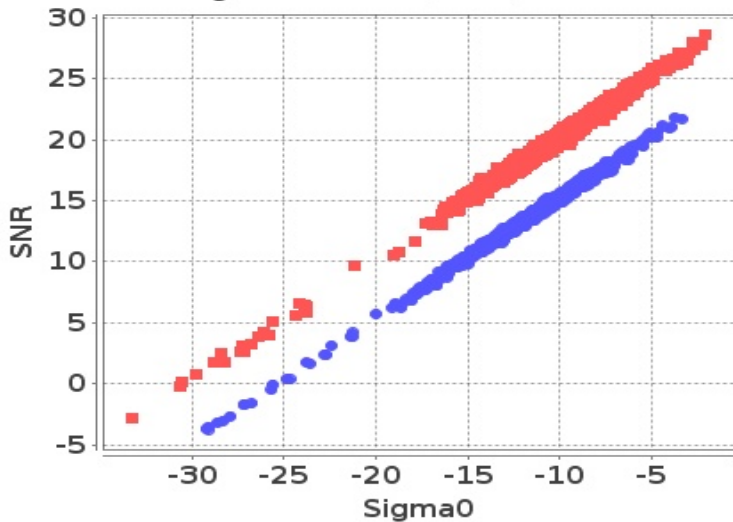
	Inner Beam (HH)				Outer Beam (VV)				Parameter Specifications		
	Min	Max	Mean	Bad Occ. (%)	Min	Max	Mean	Bad Occ. (%)	Parameter	Min	Max
Incidence Angle (deg)	48.62	49.32	48.96	0.000	57.35	58.20	57.81	0.000	Inci.(Inner)	47.10	49.90
Azimuth Diff. (deg)	0.0029	71.01	1.27	2.528	0.0000	296.88	1.27	3.647	Inci.(Outer)	57.30	58.90
Range(Km)	1016.39	1091.33	1042.85	26.138	1189.18	1282.53	1223.57	44.432	Azimuth Diff.	0.60	2.00
X Factor(dbm)	-91.39	-89.64	-90.34	0.000	-93.44	-91.71	-92.04	0.000	Range(Inner)	1025.00	1095.70
Across Distance (Km)	16.09	16.63	16.20	0.000	21.25	22.21	21.34	1.000	Range(Outer)	1210.00	1280.00
Along Distance (Km)	18.97	1398.76	22.47	2.000	18.67	1840.33	23.25	2.000	X-Factor	-100.00	-80.00
									Ac.Distance(Inner)	15.00	20.00
									Ac.Distance(Outer)	15.00	22.00
									Al.Distance(Inner)	15.00	30.00
									Al.Distance(Outer)	10.00	30.00
									 Normal	 Alarming	
									 Deviations	 High Errors	



Sigma0 Behaviour (Sigma0 Vs SNR)

Footprint-Land

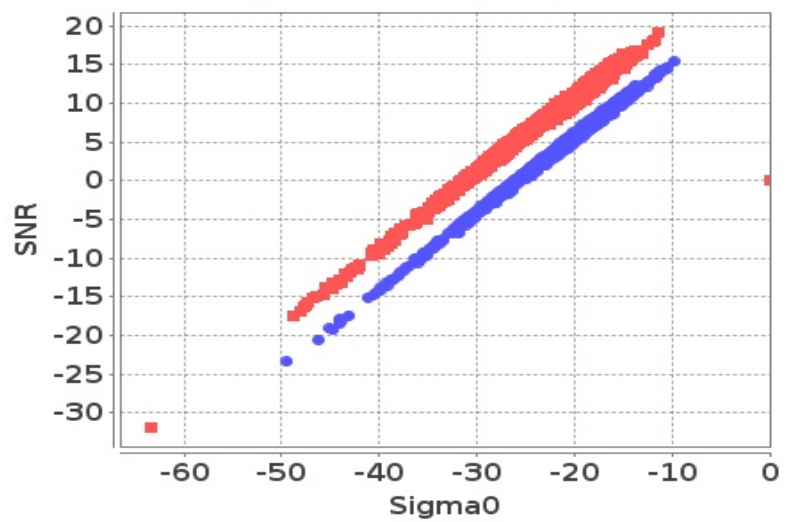
Sigma0 Vs SNR (Land)



■ Inner ● Outer

Footprint-Sea

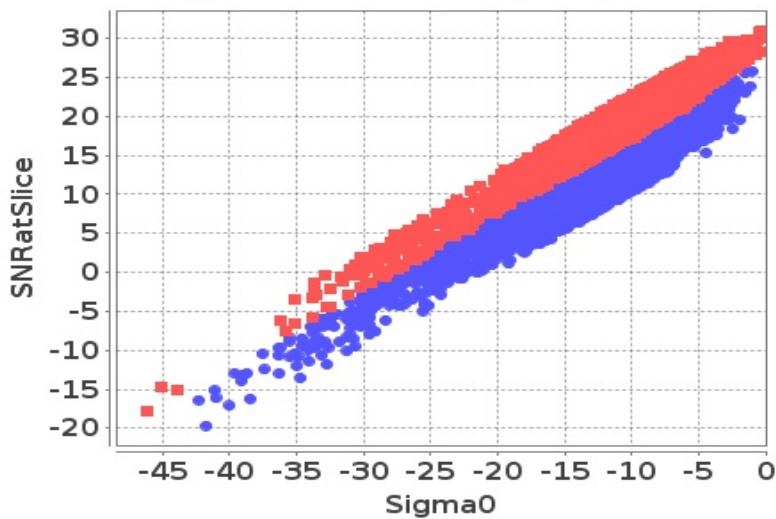
Sigma0 Vs SNR (Sea)



■ Inner ● Outer

Slice-Land

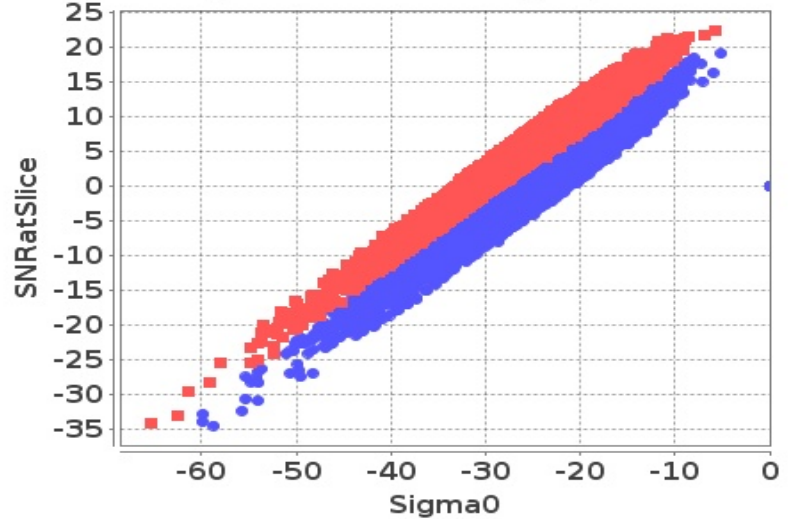
Sigma0 Vs SNRatSlice (Land)



■ Inner ● Outer

Slice-Sea

Sigma0 Vs SNRatSlice (Sea)

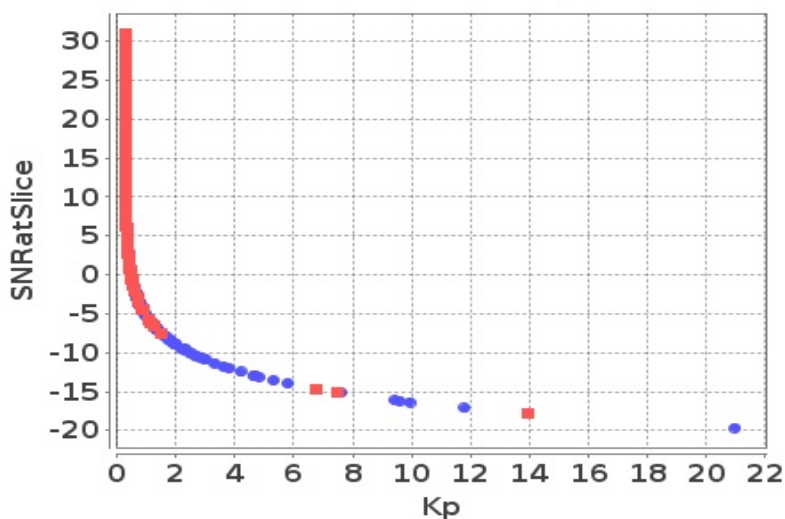


■ Inner ● Outer

Sigma0 Behaviour (Kp Vs SNR)

Slice

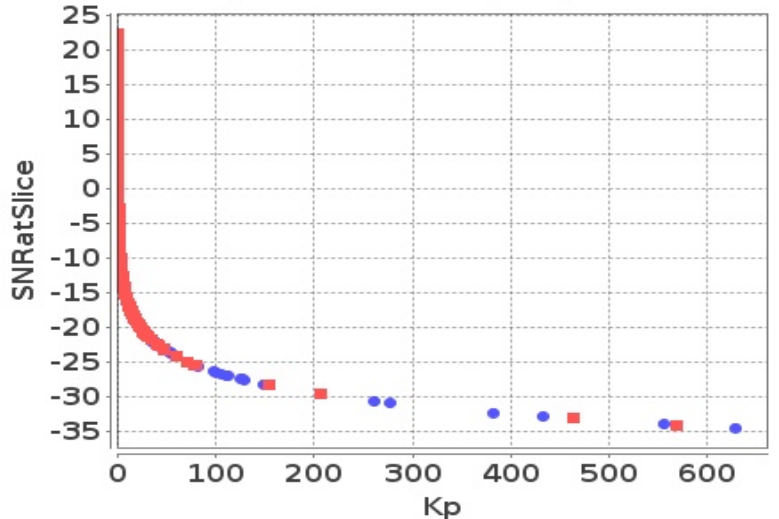
Kp Vs SNRatSlice (Land)



■ Inner ● Outer

Slice

Kp Vs SNRatSlice (Sea)



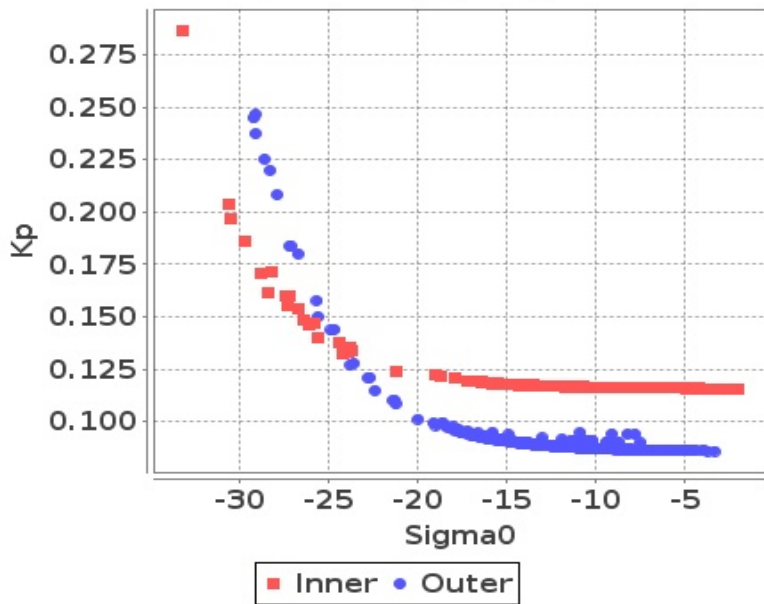
■ Inner ● Outer



Sigma0 Behaviour(Sigma0 Vs Kp)

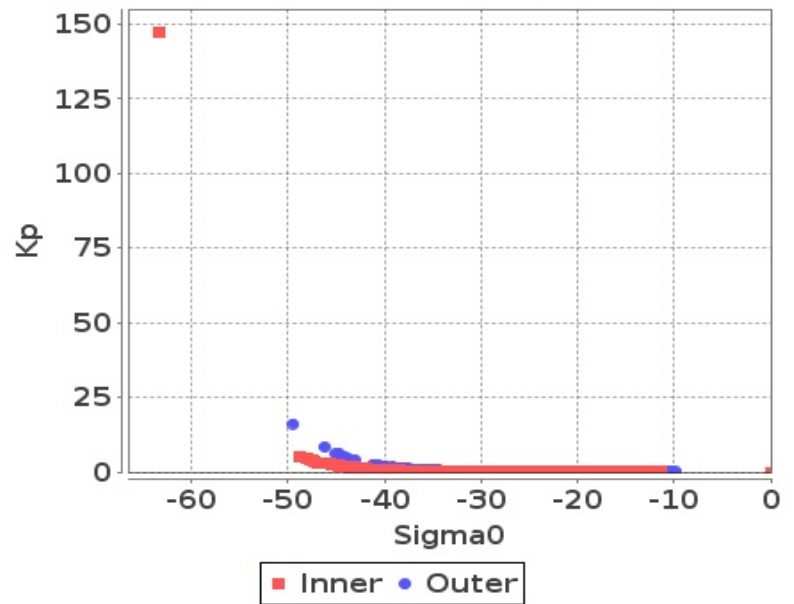
Footprint-Land

Sigma0 Vs Kp (Land)



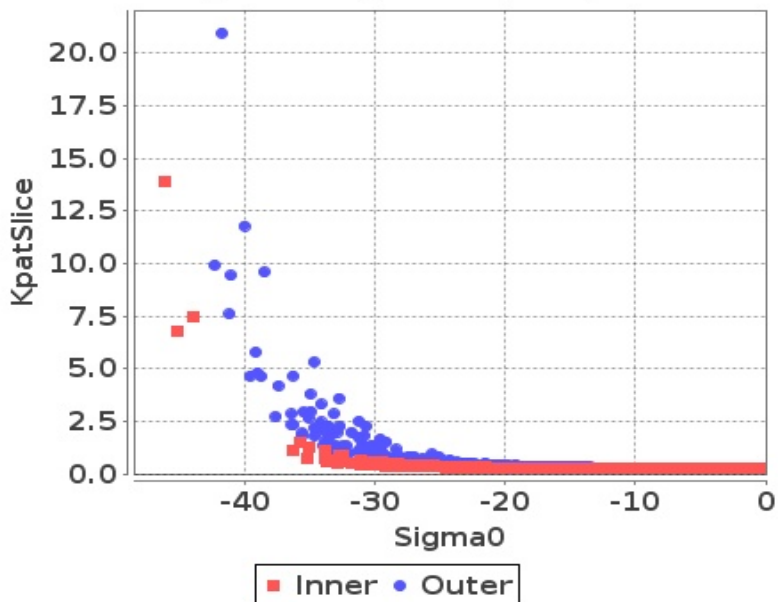
Footprint-Sea

Sigma0 Vs Kp (Sea)



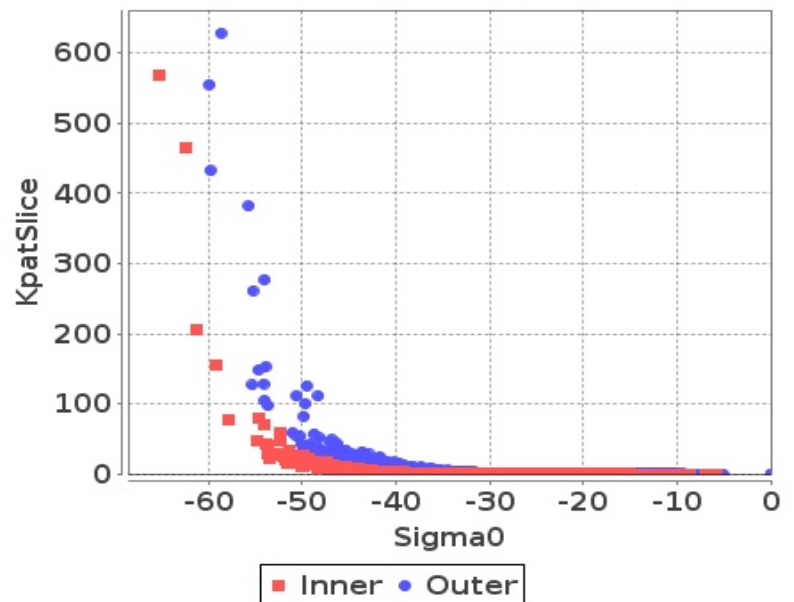
Slice-Land

Sigma0 Vs KpatSlice (Land)



Slice-Sea

Sigma0 Vs KpatSlice (Sea)

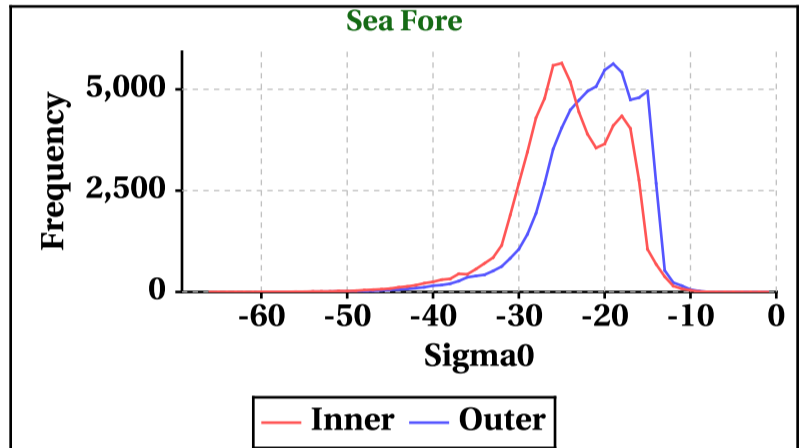
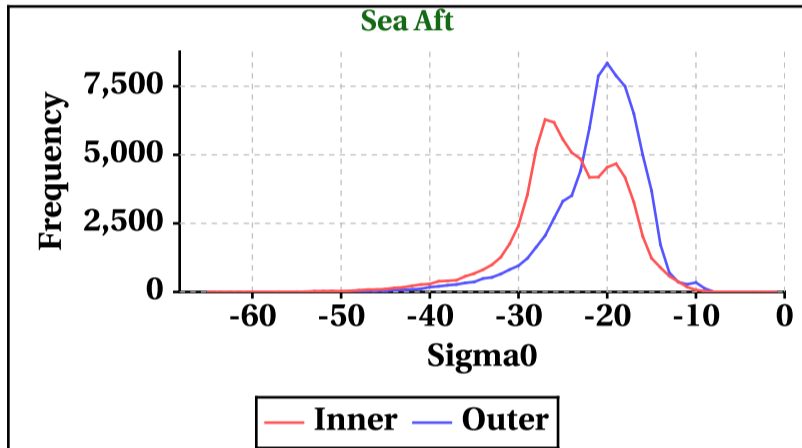
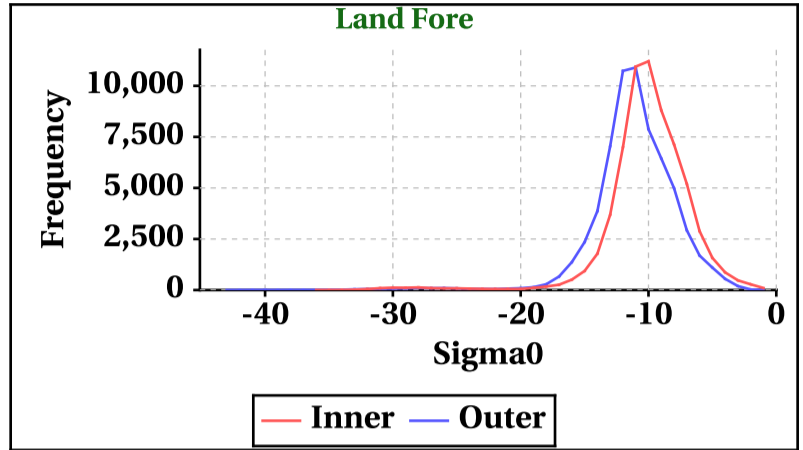
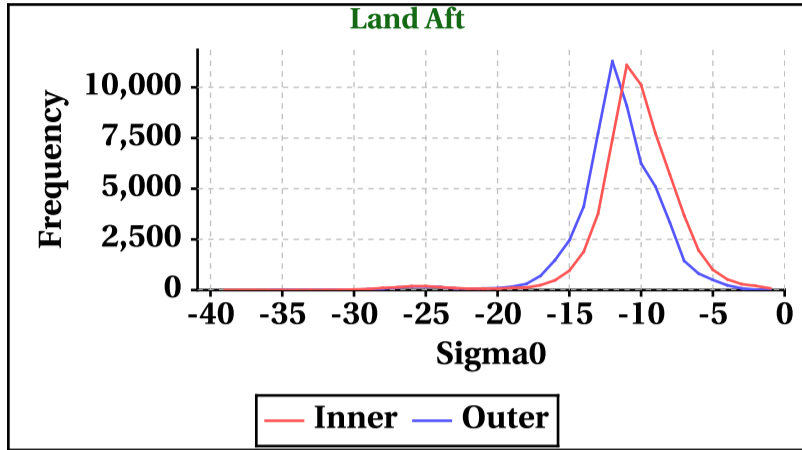


Dynamic Range (Data Histograms)

Sigma0(db)

Inner Beam (HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-39	-36	-65	-66
Max	0	0	0	0

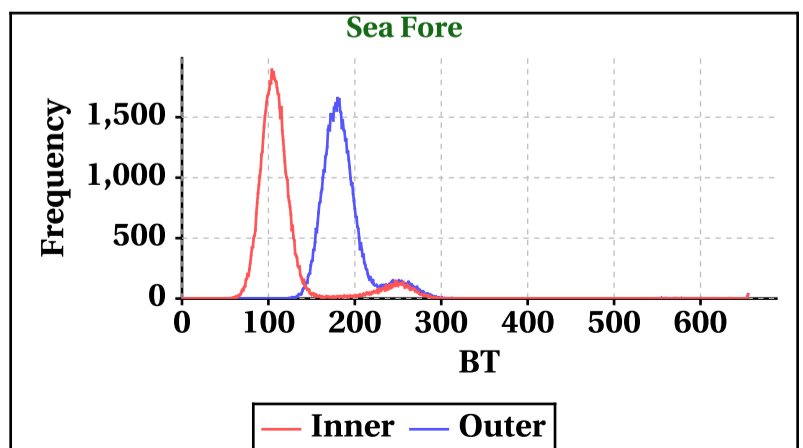
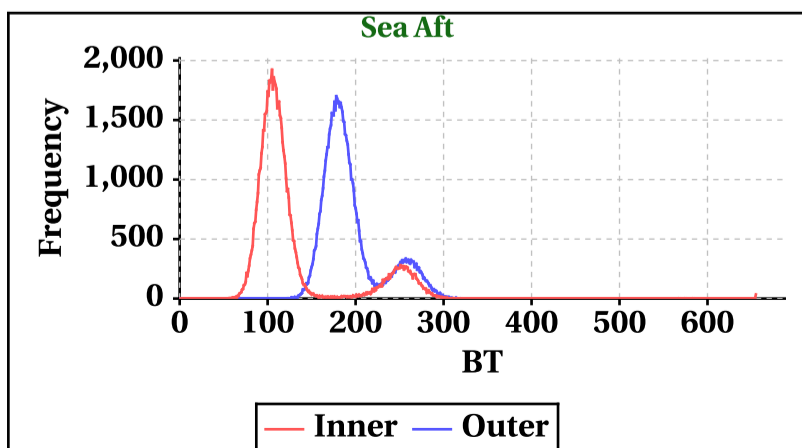
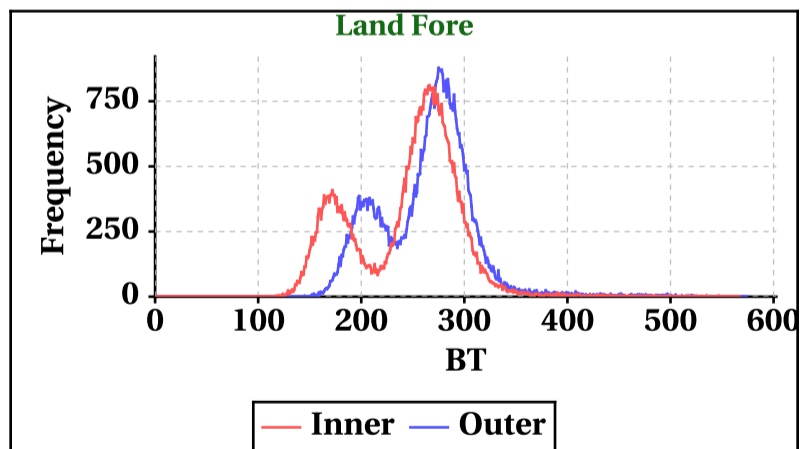
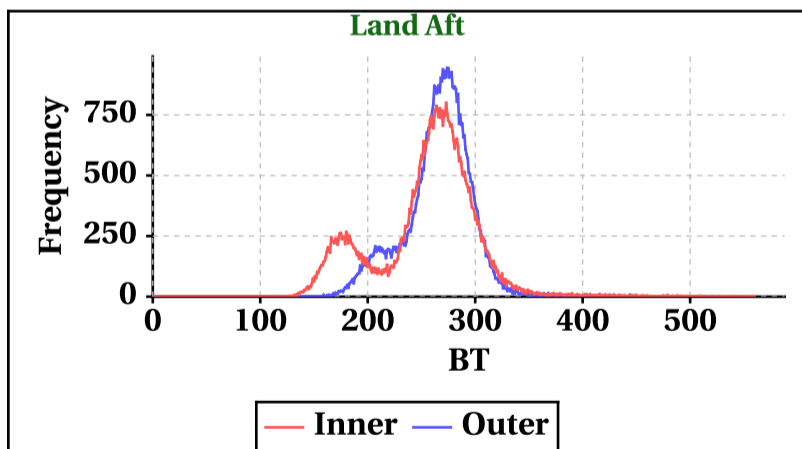
Outer Beam (VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-36	-43	-60	-59
Max	0	0	0	0



Brightness Temperature(K)

Inner Beam(HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	0	0
Max	560	567	655	655

Outer Beam(VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	0	0	0	0
Max	526	574	637	655

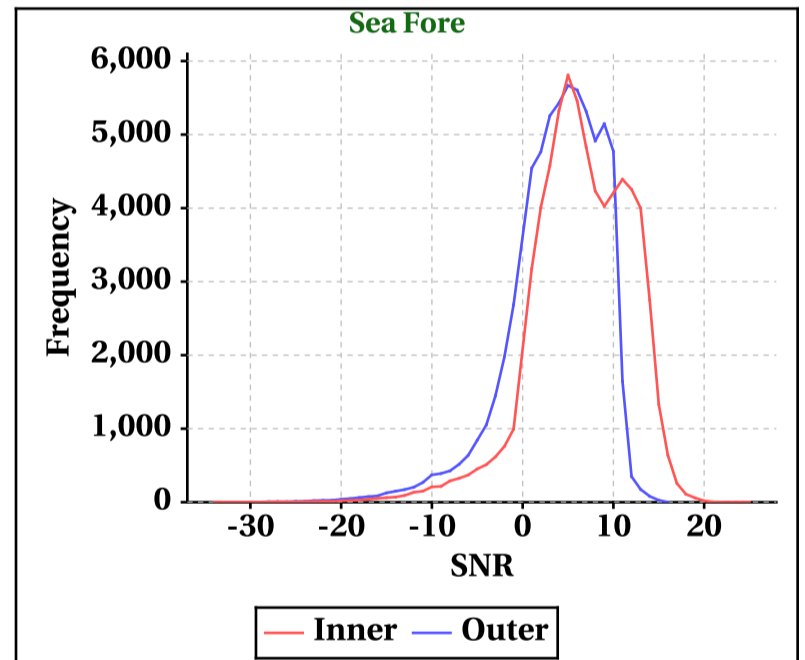
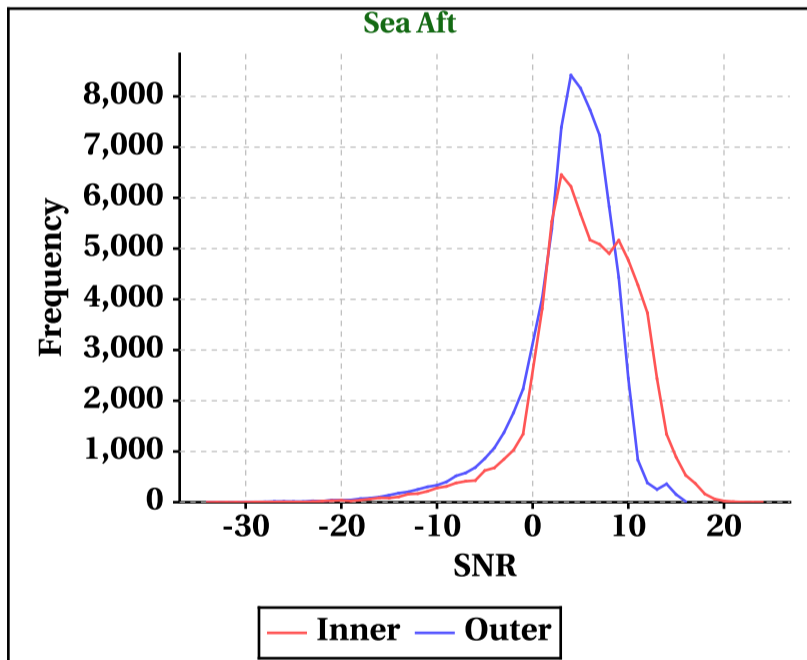
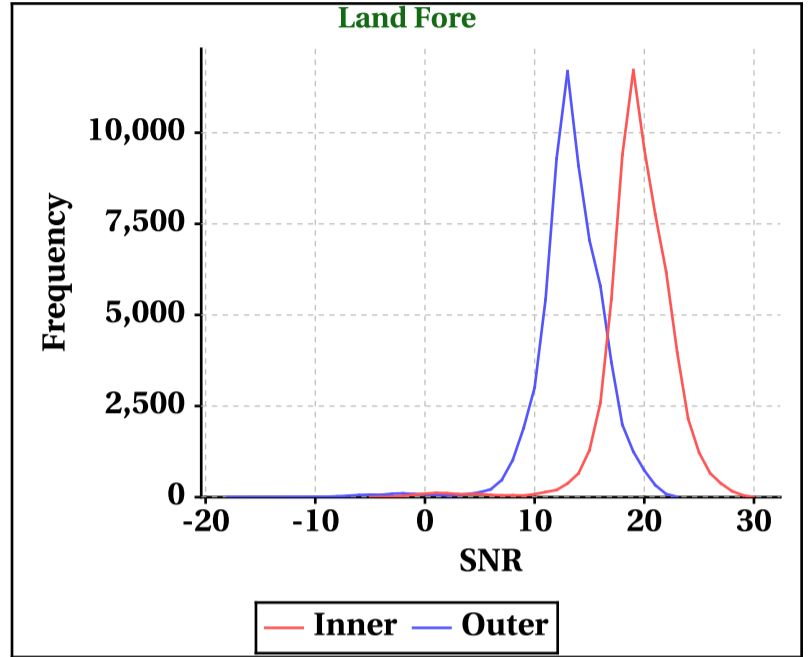
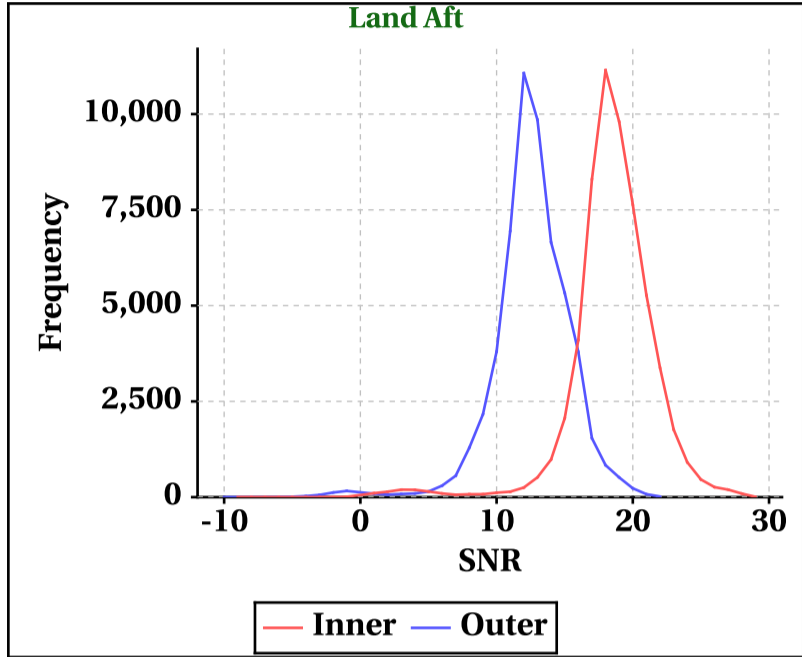


Dynamic Range (Data Histograms)

SNR(dBm)

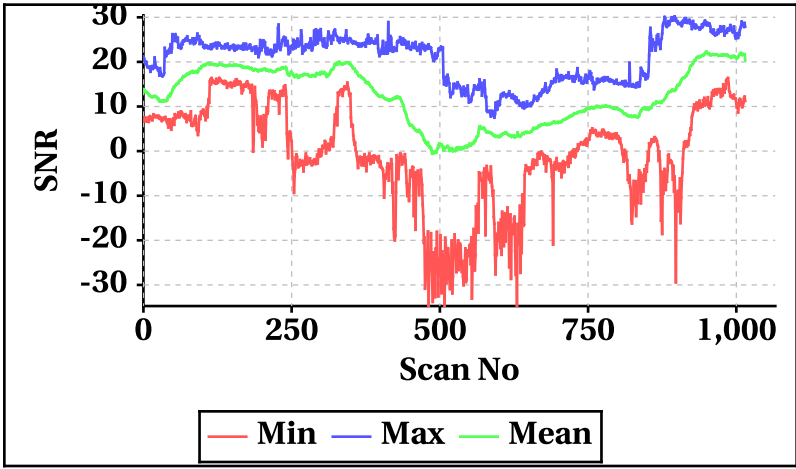
Inner Beam (HH)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-9	-5	-34	-34
Max	29	30	24	25

Outer Beam (VV)				
	Land Aft	Land Fore	Sea Aft	Sea Fore
Min	-10	-18	-34	-33
Max	22	23	16	16

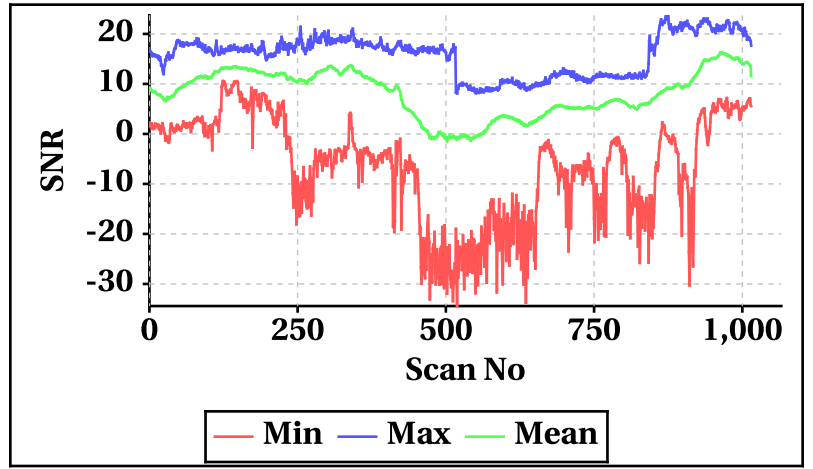


Orbit-wise behaviour of SNR

Inner Beam (HH)

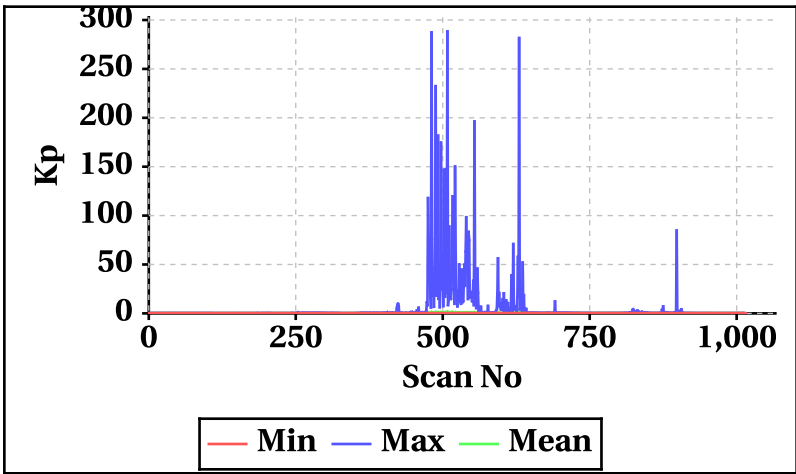


Outer Beam(VV)

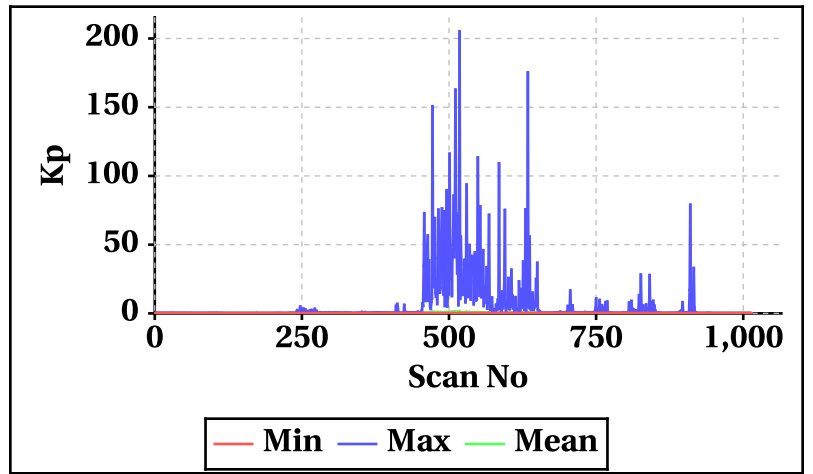


Orbit-wise behaviour of Kp,Kpa,Kpb,Kpc

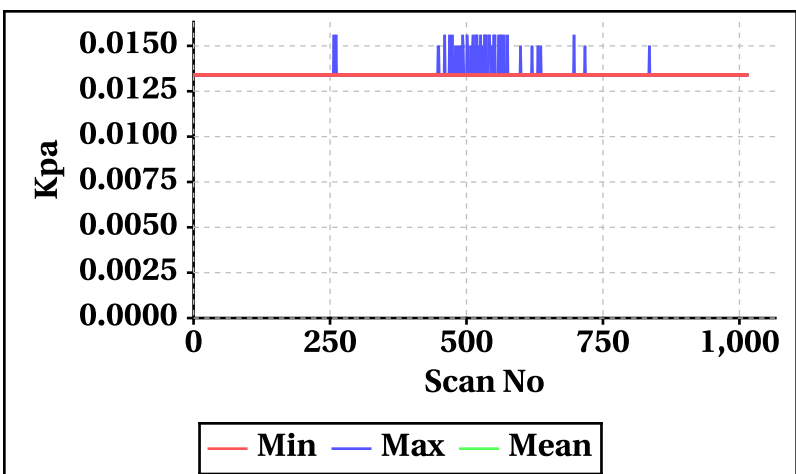
Inner Beam(HH)



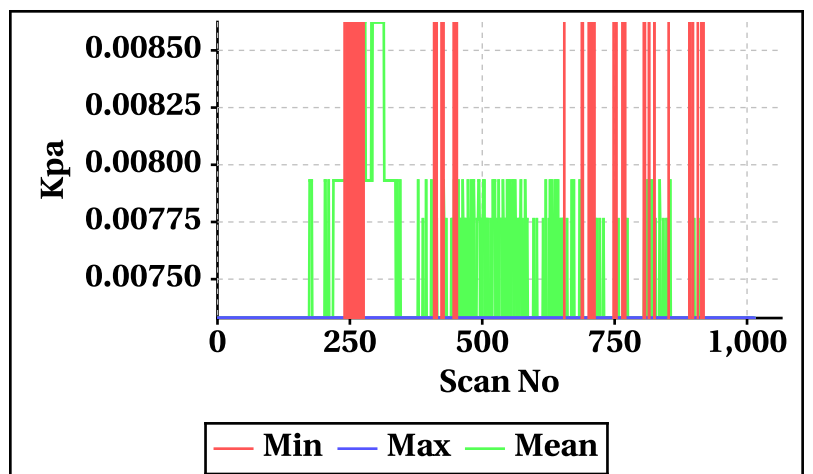
Outer Beam(VV)



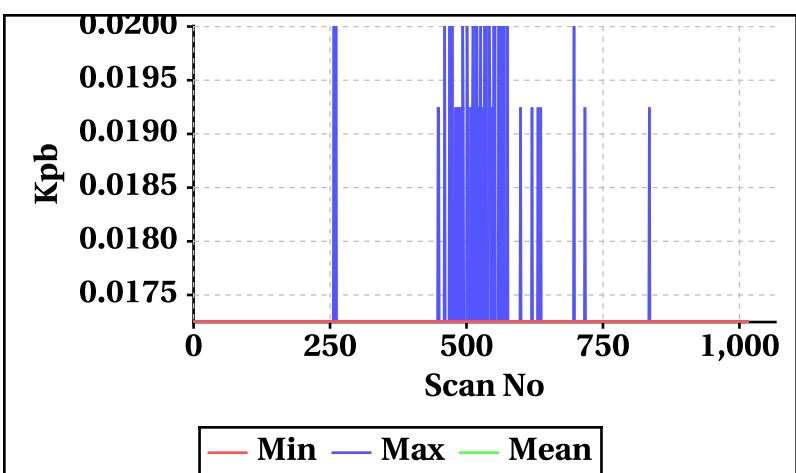
Inner Beam(HH)



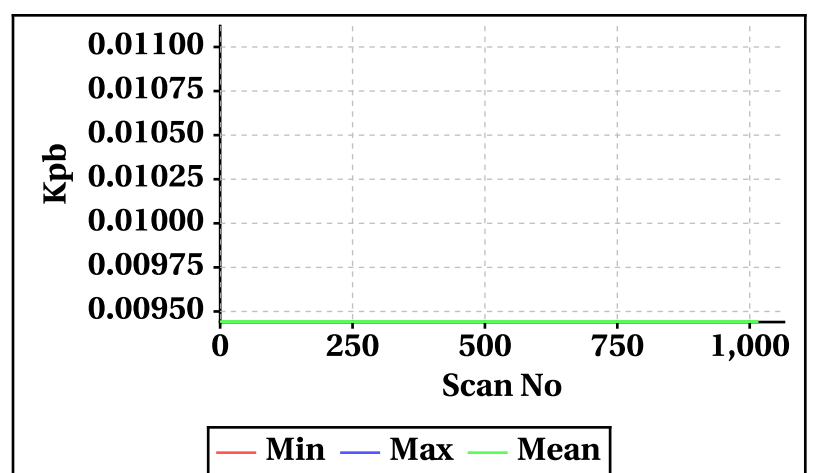
Outer Beam(VV)



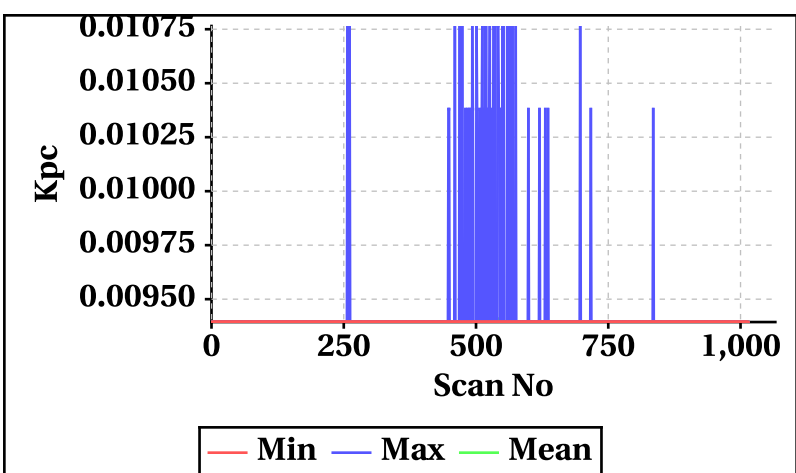
Inner Beam(HH)



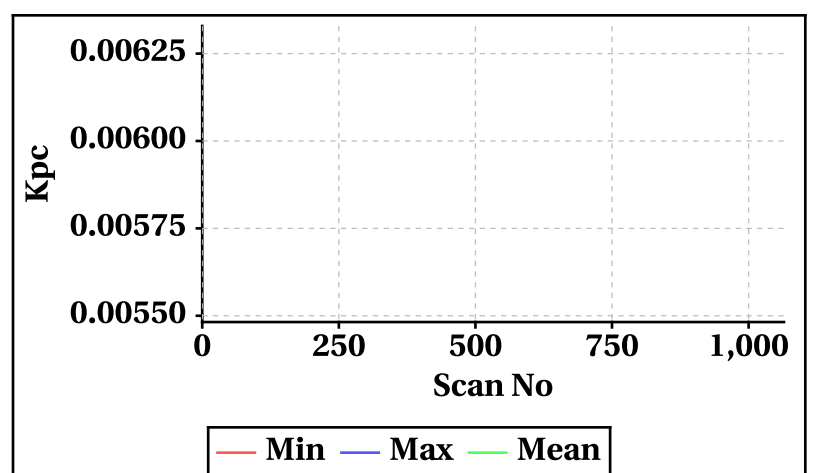
Outer Beam(VV)



Inner Beam(HH)

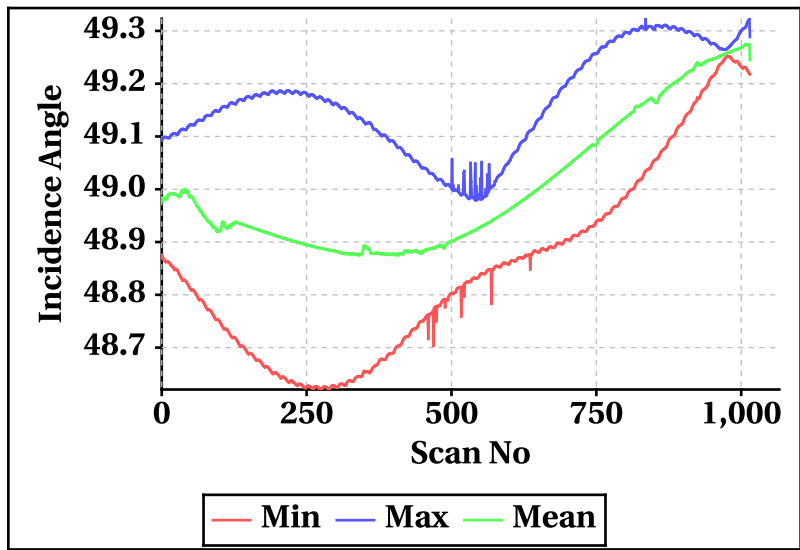


Outer Beam(VV)

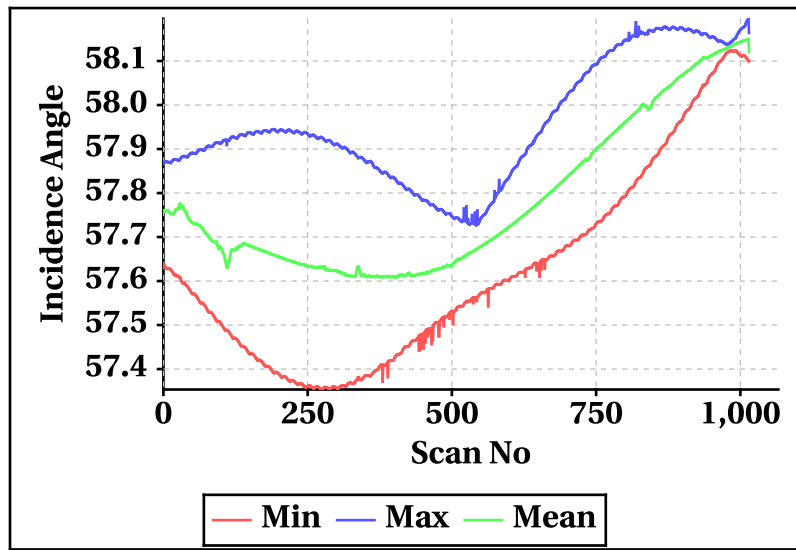


Orbit-wise behaviour of Incidence, Azimuth, Range, X-Factor

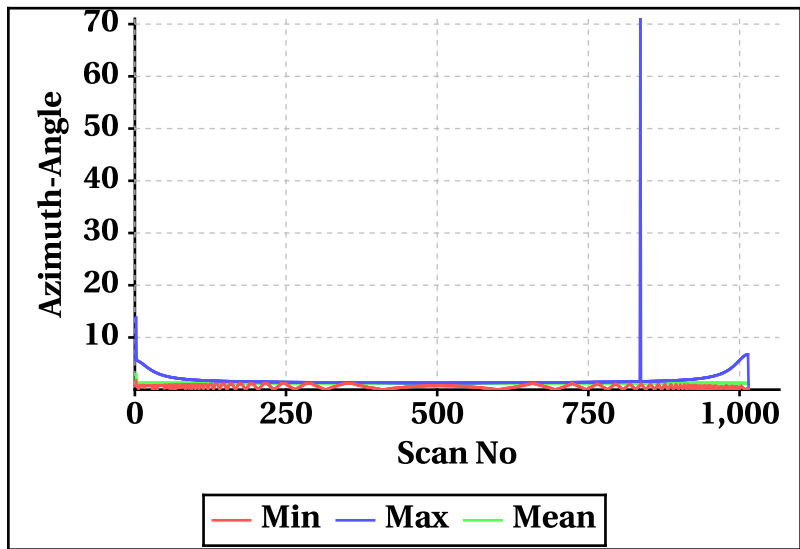
Inner Beam (HH)



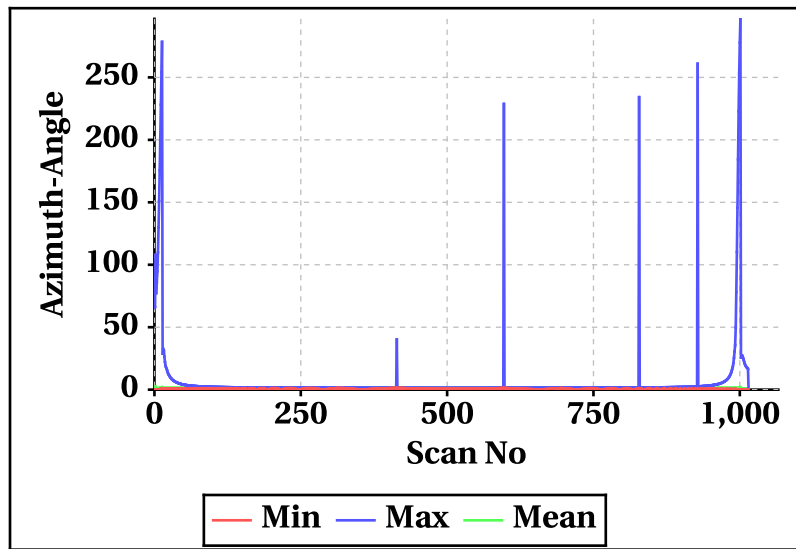
Outer Beam(VV)



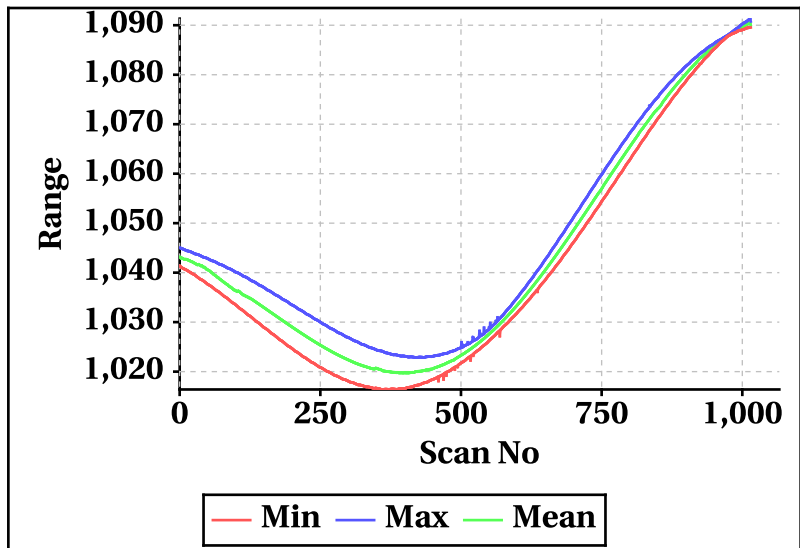
Inner Beam (HH)



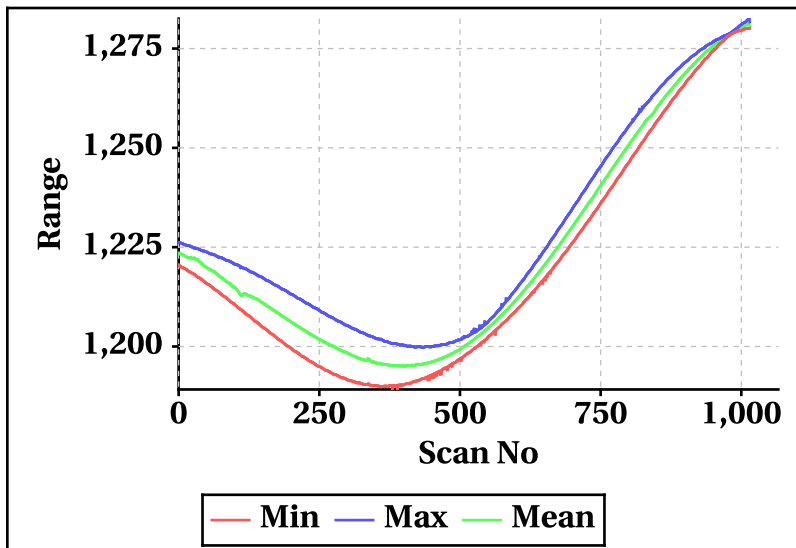
Outer Beam(VV)



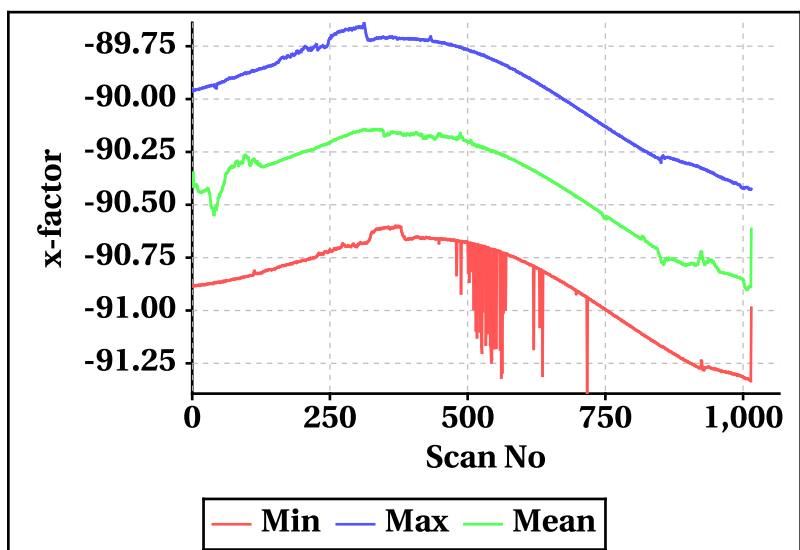
Inner Beam (HH)



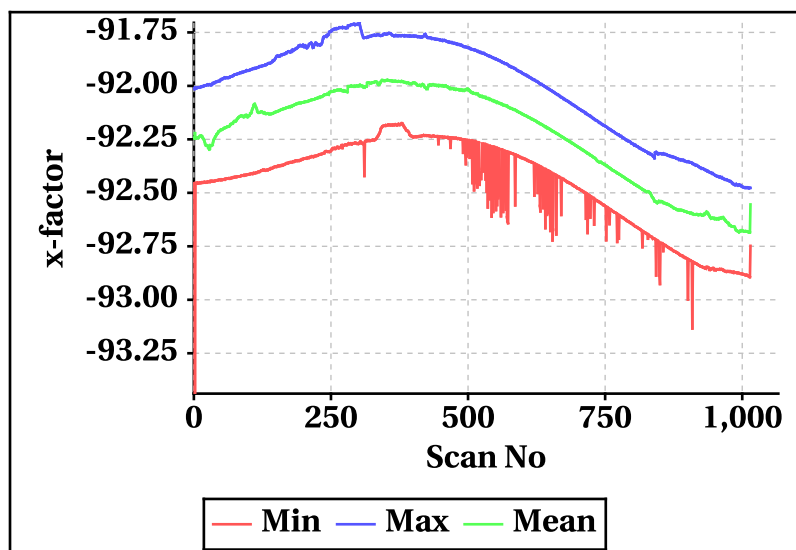
Outer Beam(VV)



Inner Beam (HH)



Outer Beam(VV)

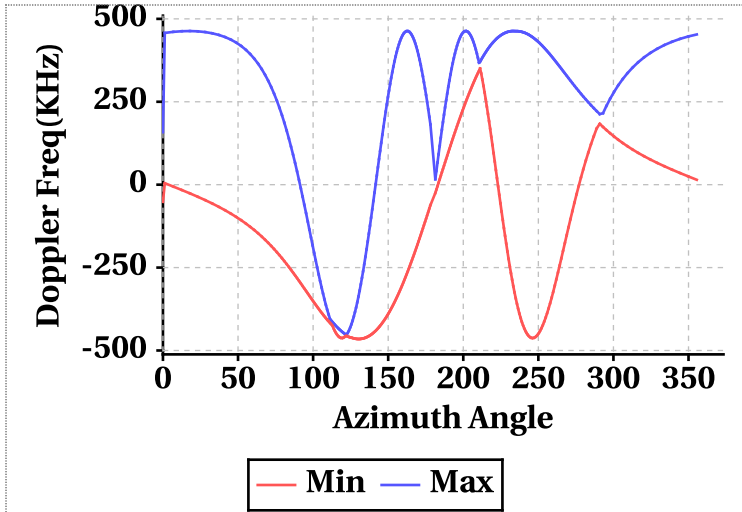


Doppler Frequency Variation

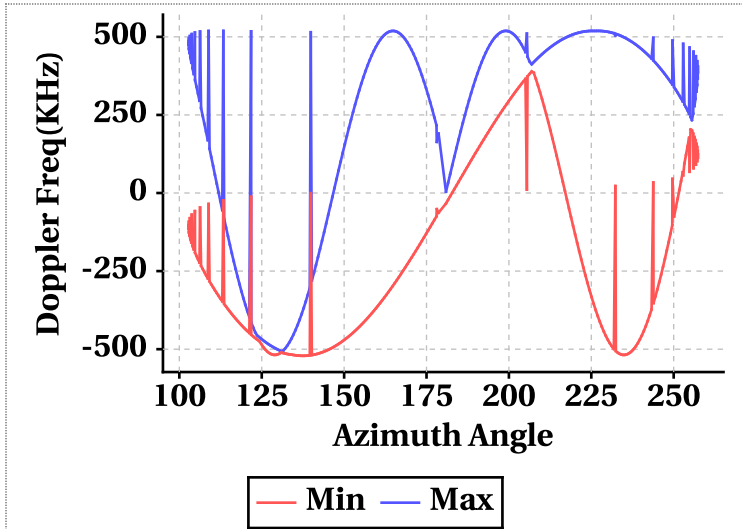
Doppler Frequency(KHz) variation statistics Over the half Orbit

	Inner Beam (HH)	Outer Beam (VV)
Min	-465.34	-521.20
Max	463.26	519.06

Footprint wise Doppler frequency variation Inner Beam (HH)



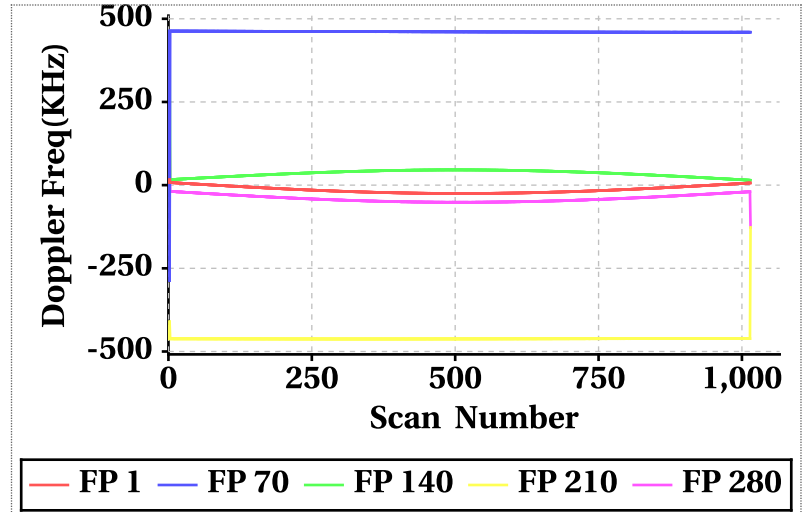
Footprint wise Doppler frequency variation Outer Beam (VV)



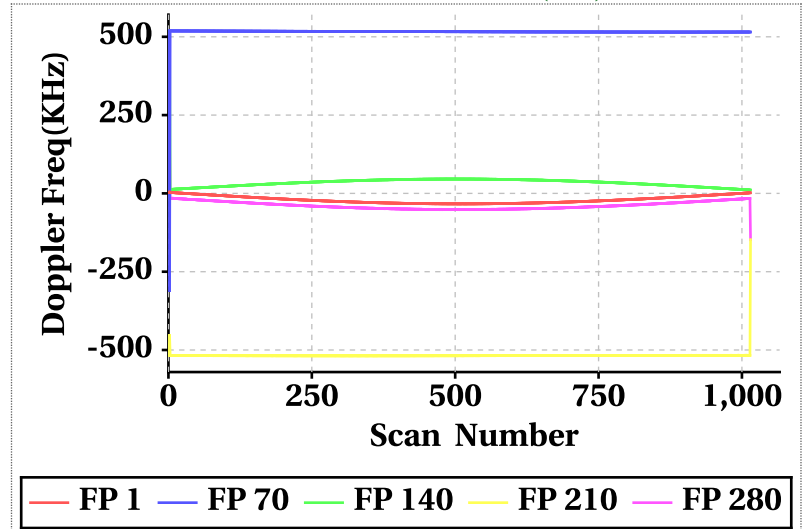
Doppler Frequency(KHz) variation

Doppler_FP	Inner Beam (HH)			Outer Beam (VV)		
	Min	Max	Mean	Min	Max	Mean
Doppler_1	-25.06	16.40	-13.24	-33.42	4.20	-20.27
Doppler_70	-286.90	463.12	460.19	-310.44	518.78	515.60
Doppler_140	14.70	452.96	35.18	10.88	510.34	33.81
Doppler_210	-462.40	-127.12	-461.51	-518.54	-147.84	-517.49
Doppler_280	-127.12	158.24	-39.60	-147.84	163.76	-38.32

Doppler frequency variation at footprints: 1, 70, 140, 210 & 280 Inner Beam (HH)

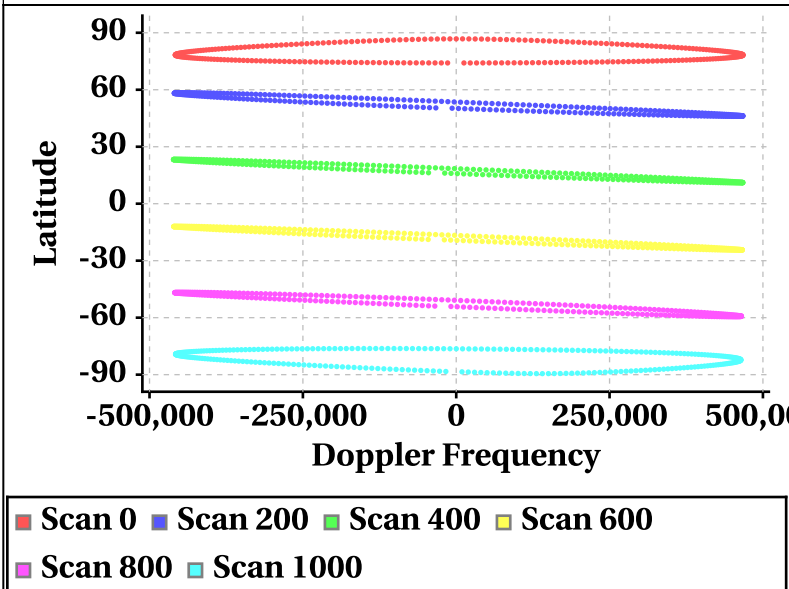


Doppler frequency variation at footprints: 1, 70, 140, 210 & 280 Outer Beam (VV)

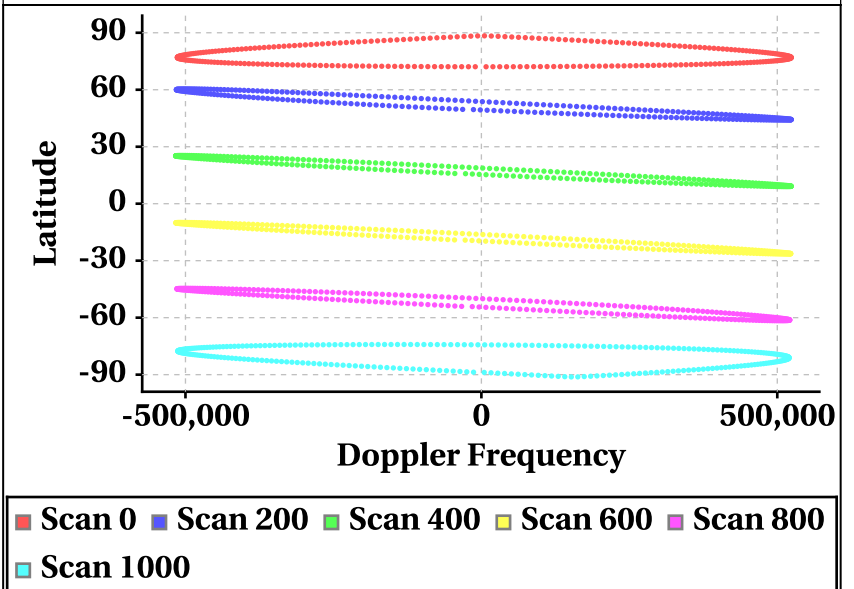


Latitude Vs Doppler Frequency

Doppler Frequency at Scan Interval of 200 [Inner Beam(HH)]



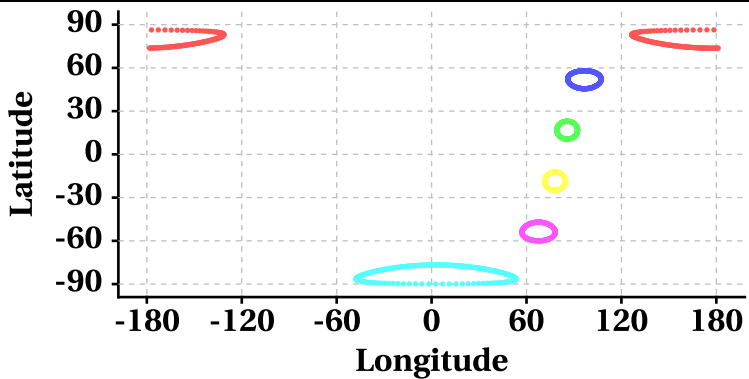
Doppler Frequency at Scan Interval of 200 [Outer Beam(VV)]



Parameter as a function of Latitude

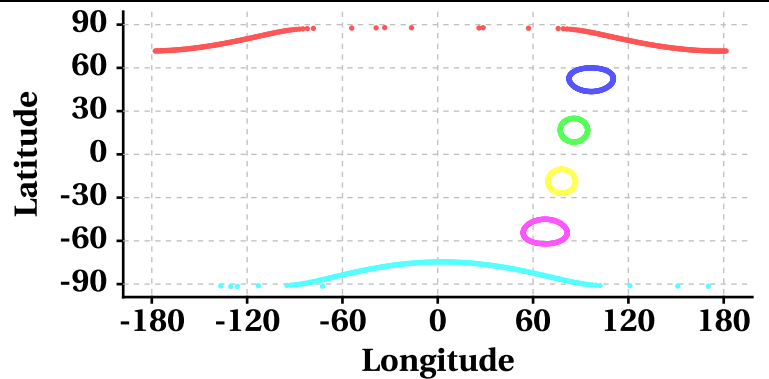
Latitude Vs Longitude

Scan Trace [Inner Beam(HH)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

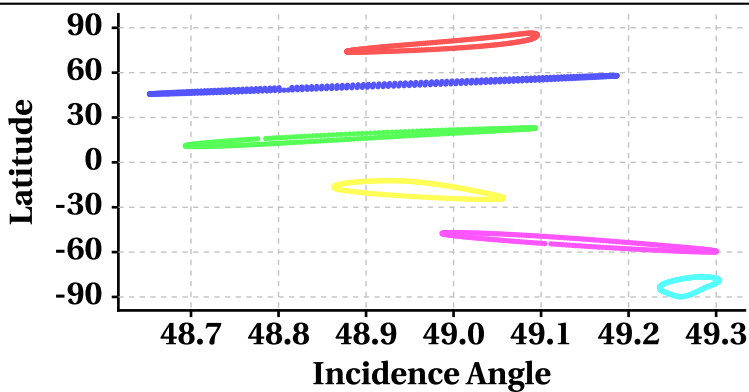
Scan Trace [Outer Beam (VV)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

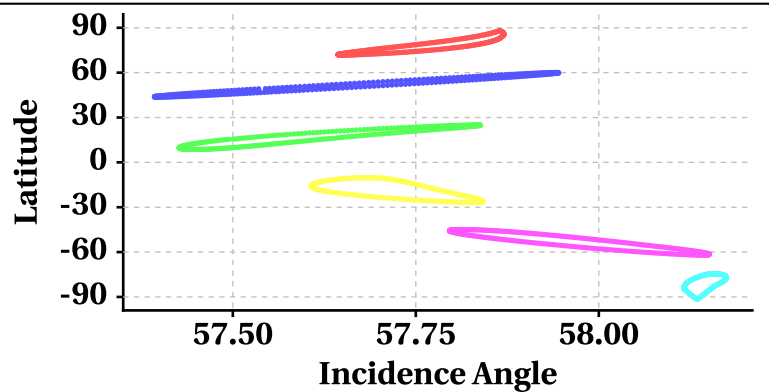
Latitude Vs Incidence Angle

Incidence Angle at Scan Interval of 200 [Inner Beam(HH)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

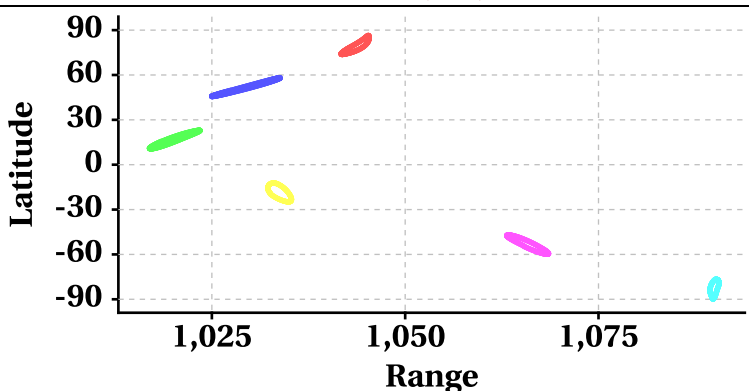
Incidence Angle at Scan Interval of 200 [Outer Beam (VV)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

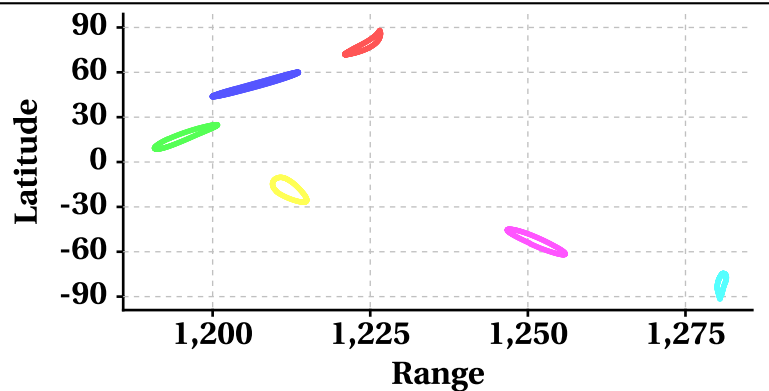
Latitude Vs Range

Range at Scan Interval of 200 [Inner Beam(HH)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000

Range at Scan Interval of 200 [Outer Beam(VV)]



■ Scan 0 ■ Scan 200 ■ Scan 400 ■ Scan 600
■ Scan 800 ■ Scan 1000



Variation in Orbit and Attitude Parameters

